



### **ON-BOARD DIAGNOSTICS**

# **V6 and V8 Engine Management**

## **Vehicle Coverage:**

X-Type 2.5L V6 and 3.0L V6 2001 model year onwards

X-Type 2.0L V6 2001 model year onwards

S-Type 3.0L V6, 4.2L V8 (normally aspirated and supercharged) from 2002 model year onwards

XK Range 4.2L V8 (normally aspirated and supercharged) from 2003 model year onwards

New XJ 4.2L V8 2003 model year onwards.

Includes Anti-lock Braking System (ABS) monitors from 2004 model year

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#### 2 OBDII Systems

California On-Board Diagnostics II (OBD) applies to all gasoline engine vehicles up to 14,000 lbs. Gross Vehicle Weight Rating (GVWR) starting in the 1996 model year and all diesel engine vehicles up to 14,000 lbs. GVWR starting in the 1997 model year.

"Green States" are states in the Northeast that chose to adopt California emission regulations, starting in the 1998 model year. At this time, Massachusetts, New York, Vermont and Maine are Green States. Green States receive California certified vehicles for passenger cars and light trucks up to 6,000 lbs. GVWR.

The National Low Emissions Vehicle program (NLEV) requires compliance with California OBDII, including 0.020" Evaporative Emissions (EVAP) system monitoring requirements. The NLEV program applies to passenger cars and light trucks up to 6,000 lbs. GVWR nationwide from 2001 model year through 2003 model year.

Federal OBD applies to all gasoline engine vehicles up to 8,500 lbs. GVWR starting in the 1996 model year and all diesel engine vehicles up to 8,500 lbs. GVWR starting in the 1997 model year.

OBDII system implementation and operation is described in the remainder of this document.

#### 2.1 Generic OBD-II Drive Cycle

For each monitoring strategy, the OBD-II drive cycle to be used is stated. The purpose of the drive cycle is to run the onboard diagnostics monitoring strategy under consideration. The number of drive cycles that must be completed in order to illuminate the MIL is given in the Monitoring Operation table for each monitoring strategy. The drive cycle should be performed after any Diagnostic Trouble Codes (DTCs) have been erased from the ECM's memory, or after the battery has been disconnected.

Unless stated otherwise, the following generic drive cycle will apply:

Drive cycle under review.

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#### 3 Engine Management System

The Engine Control Module (ECM) controls the engine management system. The system consists of an ECM and a number of sensing and actuating devices. The sensors supply the ECM with input signals, which relate to engine operating conditions and driver requirements. The ECM uses calibrated data-tables and maps to evaluate the sensor information. The ECM then uses the results to command an appropriate response from the actuating devices. The system provides the necessary engine control accuracy and adaptability to:

- Minimize exhaust emissions and fuel consumption.
- Provide optimum driver control under all conditions.
- Minimize evaporative fuel emissions.
- Provide system diagnostics when malfunctions occur.

In addition to these functions the ECM also interfaces with other vehicle systems through the Controller Area Network (CAN) communications network.

The 32-bit ECM is at the center of the system and provides the overall control. Its functions are listed below, each of which are dependent on the engine and vehicle state at any moment of time and driver requirements.

- Starting: Ensures that conditions are safe to crank the engine.
- Engine: Controls the rate of air and fuel flow into the cylinders; adjusts the intake manifold volume; controls the ignition and intake camshaft timing.
- Fuel supply: Controls the operation of the fuel pumps and the EVAP canister purge valve.
- Cooling: Controls the engine cooling fans.
- Battery: Optimizes the battery charging conditions.
- Air Conditioning (A/C) and screen heater: Controls the speed of the engine when these additional loads are added, also disables the A/C when it is beneficial to reduce the load on the engine.
- Speed control: Provides the option to maintain a fixed vehicle speed without driver intervention.
- Robustness: Maintains engine running condition under intermittent or permanent single point failures on any sensors or actuators fitted to the system, and records Diagnostic Trouble Codes (DTCs) of these failures for system diagnosis.
- Diagnosis: Notifies the driver when a system malfunction occurs and records data for system diagnosis.

#### 3.1.1 Fuel Injection

The ECM controls one injector per cylinder in sequential operation. The size of the injector used is so that stoichiometric control is possible at minimum load with allowance for EVAP canister purge valve correction, and at maximum load to provide sufficient fuel flow at all engine speeds. The timing of injector firing, relative to intake valve closing, during normal starting and running conditions is optimized to provide the best compromise between emissions and performance, time to first-ignition and smooth engine operation at start-up, for all engine conditions at all temperatures. The mass of fuel per-injection is derived from a calculation based on a ratiometric match to the metered airflow.

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The ECM is capable of adapting to fuel system tolerances and engine internal wear under all operating conditions. The ECM continually monitors the differential pressure between the fuel rail and plenum, and uses this value to calculate the injector pulse width with the required mass of fuel per-injection. The ECM also continually monitors the temperature of the fuel being injected into the engine and provides compensation for the changing flow characteristics of the fuel system at different temperatures. By monitoring the battery supply voltage the ECM can ensure that the fuel supply to the engine is unaffected by voltage fluctuation.

#### 3.1.2 Ignition

The system uses one ignition coil per-cylinder. A base ignition map is provided so that the engine can be optimized for emissions, fuel economy, performance and avoidance of cylinder knock throughout its speed and load range. Ignition timing during starting is used during engine cranking and under speed modes to provide the best compromise between emissions, time to first ignition and smooth engine operation at start up, at all temperatures. Provision is made to compensate for the effect of changing air intake temperature on the combustion detonation limit. The system contains the necessary hardware for the detection of combustion knock within the engine cylinders; the ECM uses this information to gradually adjust the ignition timing until the combustion knock is at a safe and inaudible level.

#### 3.1.3 Variable Valve Timing (Normally Aspirated Engines)

The ECM controls the fully variable phase change system, which acts on the intake camshafts. The target positions of both camshafts are optimized to provide the best compromise between performance, refinement, fuel economy and emissions. During transient operation, the rate of change of the Camshaft Position (CMP) is controlled to optimize drivability. Operation of the Variable Valve Timing (VVT) will be restricted if environmental conditions exist that could affect normal operation of the VVT, for example very low ambient temperatures. Provision is made to ensure that the intake camshafts are restrained in the retard position during engine start. The ECM will also detect a variable valve timing mechanical malfunction, and act to compensate for the malfunction.

### 3.1.4 Variable Air Intake System (V6 Engines)

The ECM controls two intake manifold tuning valves. Each valve is a two positional device; the switching point of the valve is dependant on engine speed and a definable change in engine performance. The valve switching points are optimized for maximum torque in the wide-open Throttle Position (TP).

#### 3.1.5 Exhaust Gas Recirculation (V8 Engines)

The ECM controls the flow of exhaust gases to reduce oxides of nitrogen in emissions by re-circulating metered amounts of exhaust gas into the intake of the engine. This lowers the combustion temperature, limiting the formation of nitrogen oxides. The Exhaust Gas Recirculation (EGR) flow is optimized for fuel economy, emissions and drivability for all engine-operating conditions.

#### 3.1.6 Electronic Throttle Control

The electronic throttle controls the airflow into the engine under closed loop feedback control of the ECM. The correct throttle disc position is calculated as a function of driver demand and of the engine's momentary operating mode. A fail safe system is incorporated that complies with legislative requirements, including mechanical limp-home operation.

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### 3.1.7 Idle Speed Control

Idle speed is dependent on Engine Coolant Temperature (ECT) and gear selection (neutral or drive). Idle speed is optimized for combustion stability, idle quality, Idle Speed Control (ISC) capability and fuel economy at all operating conditions. Compensations to the idle speed will be made for conditions, such as variable ambient air temperature, to increase idle speed to satisfy charging system requirements.

#### 3.1.8 Vehicle Speed Control

The engine management system incorporates a speed control system. This enables the driver to set a speed, and control and maintain the speed of the vehicle without having to operate the accelerator pedal. The speed control switches are momentary action switches, mounted on the steering wheel. The function of the switches is organized so that a function relating to a switch priority always overrides a function relating to a lower priority switch. The switch priority is:

- 1. Cancel
- 2. Set
- 3. Resume

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### 4 Sensors and Actuators

The following table defines the function of the engine mounted sensors and actuators:

Component	Function
Fuel injectors	Delivers fuel to the engine cylinder intake ports in sequential order. There are 12 fuel injection holes per cylinder, delivering fuel droplets as small as 60 microns in diameter. This size of fuel droplet reduces fuel wetting of the intake port and promotes excellent fuel air mixing. Reducing noxious emissions and improving fuel economy while the engine is warming up.
On-plug ignition coil	The ECM controls one coil per spark plug in sequential order. The ignition coil provides the energy to the spark plug to ignite the air fuel mixture in the engine cylinder. The ignition coil works on the principle of 'mutual induction'. By closing and then opening the ignition coil primary circuit, the primary current increases, and then suddenly decreases to induce the high voltage in the secondary circuit needed to fire the spark plug.
CMP sensor	Signals from the CMP sensors are used to synchronize the ECM to the engine cycle during engine starting. For example, whether the Crankshaft Position (CKP) sensor is indicating an induction or firing stroke. The position of both intake camshafts is monitored to allow the ECM to control the phase of the intake camshafts relative to the position of the crankshaft. On engines with VVT, the CMP sensor provides feedback control on the intake camshaft's position relative to the position of the crankshaft and exhaust camshafts.
Oil control solenoid - VVT (normally aspirated engines)	The oil control solenoid is a hydraulic actuator, which advances and retards the intake camshaft timing, thereby altering the camshaft-to-crankshaft phasing.
Manifold Absolute Pressure (MAP) sensor	The manifold absolute pressure sensor is used for EGR diagnostic testing only.
Knock sensor	The knock sensors produce a voltage signal with respect to the engine's combustion level. The knock sensor detects and reports combustion knock within the engine cylinders. The ECM uses this information to gradually adjust the ignition timing until the combustion knock is at a safe and inaudible level. The knock control system cannot advance the ignition past the mapped values; it retards the ignition timing to reduce combustion knock and then advances to its original value.
Fuel rail pressure sensor	Continuously monitors the fuel pressure between the fuel rail and plenum, this value is used by the ECM as one of its factors to calculate the injector pulse-width required to deliver the correct mass of fuel per injection. The ECM also uses this information to demand a specific fuel flow rate from the fuel pump via the fuel pump module.
Fuel rail temperature sensor	The fuel rail temperature sensor continuously monitors the temperature of fuel being injected into the engine; this value is used by the ECM to provide compensation for the changing flow characteristics of the fuel system with temperature. The ECM therefore ensures that engine performance is unaffected by temperature changes in the fuel supply.
Intake manifold tuning valves (V6 engines)	The intake manifold tuning valves are a two positional 'open or close' device used to create a variable air intake system. The intake manifold tuning valve positions are switched, via signals from the ECM, to optimize torque across the engine speed and load range. The intake manifold tuning valves work in conjunction with the operation of the throttle body sensors.

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Component	Function
Throttle body assembly	The throttle body controls the airflow into the engine by use of the throttle motor and Throttle Position (TP) sensor.
	Throttle-disc position is operated by the throttle motor using signals received from the Accelerator Pedal Position (APP)
	sensor, via the ECM. The ECM, via the TP sensor, monitors throttle disc angle. The ECM on application of external loads,
	for example the A/C compressor, makes compensation to the throttle disc angle.
Mass Airflow (MAF) sensor with	The MAF sensor informs the ECM of the rate of airflow entering the engine by producing a voltage, which increases as the
integrated Intake Air Temperature	rate of airflow increases. The MAF sensor also takes into account the density of air entering the engine so it is possible to
(IAT) sensor	maintain the required air fuel ratio, and compensate for variations in atmospheric pressure and temperatures. The integral
	IAT sensor measures the temperature of the air entering the intake system. The ECM uses this information to compensate
	for higher than normal IAT upon combustion detonation.
CKP sensor	The CKP sensor is an inductive pulse generator, which scans protrusions on a pulse ring, to inform the ECM of the
	crankshaft's position and engine speed.
Engine Coolant Temperature	The thermistor type sensor provides an input signal to the ECM, which is proportional to the temperature of the engine
sensor	coolant being circulated around the coolant system.
Engine Oil Temperature (EOT)	The thermistor type sensor provides an input signal to the ECM, which is proportional to the temperature of the oil being
sensor	circulated around the engine oil passageways.
Heated Oxygen Sensor (HO2S) 1	The HO2S 1 is a linear characteristic type sensor, fitted forward of the exhaust system's catalytic converter. The sensor is
	used by the ECM as a primary sensor to measure oxygen content within the exhaust system. The sensor is used in
	conjunction with the ECM to provide closed loop fuelling control.
HO2S 2	The HO2S 2 is a non-linear characteristic type sensor fitted to the exhaust system's catalytic converter, and is used by the
	ECM as a secondary sensor to measure oxygen content within the exhaust system. Used in conjunction with the ECM and
	the HO2S 1, the HO2S 2 aids closed loop fuelling control. It is also used to monitor catalyst efficiency.
EGR valve	A defined portion of the engine's exhaust emissions is extracted and returned to the intake mixture via a solenoid valve, as
	controlled by the ECM.
Air intake control flap solenoid	The ECM directly controls the solenoid, to open and close the air intake control flap in the air cleaner assembly. The
(S/C engine)	control flap is opened at high engine speed and loads to satisfy engine air charge requirements.
Engine oil pressure switch	This switch is connected to the Instrument Pack (IPK) and is used for a low oil pressure warning. It is not used by the
	engine management system.

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## 5 Mode \$06 Data

SAE J1979 Mode \$06 Data							
Test ID	Comp ID	Description	Units				
\$02	\$00	Catalyst system efficiency below threshold 1 - bank (delay time)	msec				
\$04	\$04 \$00 Catalyst system efficiency below threshold 2 - bank (delay time)						
Conversion for TIE	Conversion for TID \$02 and \$04: Multiply by 4 to get result in milliseconds.						
\$06	\$00	EVAP system leak detected (20 thou)	kPa				
\$07	\$00	EVAP system leak detected (gross leak)	kPa				
\$08	\$00	EVAP system leak detected (40 thou)	kPa				
		by 6.25/1024, then subtract 4.125 to get result in kPa.					
		1024 to get result in kPa.					
\$09	\$00	EGR system flow malfunction (GA changing rate low)	g/sec				
\$0A	\$00	EGR system flow malfunction (GA changing rate high)	g/sec				
		by 400/65536, then subtract 200 to get result in g/sec. Result can be positive or negative.					
\$0B	\$00	EVAP system flow check	None				
	\$0C \$00 EVAP system flow check None						
	Conversion for TID \$0B and \$0C: Multiply by 0.5/65536.						
\$0D	\$00	EVAP system flow check	None				
\$0E	\$00	EVAP system flow check	None				
Conversion for TIE	\$0D and \$0E: Multiply						
\$0F	\$00	EVAP system flow check	rpm				
\$10	\$00	EVAP system flow check	rpm				
\$11	\$00	EVAP system flow check	rpm				
		ultiply by 100/256 to get result in RPM.					
\$12	\$00	EVAP system flow check	g/sec				
		24 to get result in g/sec.					
\$13	\$00	Catalyst system efficiency below threshold 1 - bank (high airflow)	None				
\$14	\$00	Catalyst system efficiency below threshold 2 - bank (high airflow)	None				
	) \$13 and \$14: Multiply						
\$1A	\$00	Upstream HO2S 11 lean to rich response time counter	msec				
\$1B	\$00	Upstream HO2S 21 lean to rich response time counter	msec				
Conversion for TIE	) \$1A and \$1B: Multiply	y by 64 to get result in msec.					

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SAE J1979 Mode \$06 Data – Continued								
\$1C	\$1C \$00 Upstream HO2S 11 minimum sensor current for test cycle mA							
\$1D	\$00	Upstream HO2S 21 minimum sensor current for test cycle	mA					
\$1E \$00 Upstream HO2S 11 maximum sensor current for test cycle mA								
\$1F	\$00	Upstream HO2S 21 maximum sensor current for test cycle	mA					
Conversion for TIE	) \$1C, \$1D, \$1E and \$1	F: Multiply by 1/256, then subtract 128 to get result in mA. Result can be positive or negative.						
\$21	\$00	EGR system flow malfunction (MAP changing rate low)	kPa					
\$22	\$00	EGR system flow malfunction (MAP changing rate high)	kPa					
Conversion for TIE	\$21 and \$22: Multiply	by 500/65536, then subtract 133.35 to get result in kPa. Result can be positive or negative.	Conversion for TID \$21 and \$22: Multiply by 500/65536, then subtract 133.35 to get result in kPa. Result can be positive or negative.					

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#### 6 On Board Monitoring

The vehicle drive train is continually monitored throughout its life to maintain its proper function and ensure that emission levels do not exceed accepted limits.

#### 6.1 Catalyst Efficiency Monitor

Catalytic converters oxidize unburned Hydrocarbons (HC) and Carbon Monoxide (CO) by combining them with oxygen to produce water vapor, and reduce nitrogen oxides to nitrogen and oxygen. When the engine air fuel ratio is lean, the oxygen content of the catalytic converter reaches its maximum value. When the air fuel ratio is rich, the oxygen content is depleted. If the air fuel ratio remains rich for an extended period, the converter may fail to convert the harmful gases.

The Catalyst monitor operates once per trip, and is not a continuous monitor.

The monitor waits until all entry conditions are met, including the modeled catalyst temperature reaching its threshold. Once all entry conditions are met, the monitor starts to run. The fuelling is cycled rich and lean (called dither) by approximately 3% to get a reaction at the downstream Oxygen Sensor (O2S). At the start of the monitor, delay counters operate so that the fuelling is stable when the diagnosis takes place. If the entry conditions then drop out, the monitor result and execution timer are held at the values that they were when the entry conditions dropped out. The next time entry conditions are met the monitor carries on from where it stopped previously. This will happen for a maximum of four attempts, after this, the monitor will reset and the diagnosis restarts.

The monitor runs for a calibratable period of time, after which the monitor results are made. The monitor results are decided by accumulating the locus of the downstream O2S signal versus the accumulation of the upstream O2S. The more active the downstream sensor, the less oxygen storage capacity the catalyst has, so the higher the locus value.

With a 100,000-mile catalyst, the downstream O2S is not so active, so lower locus values are obtained.

A judgment is made when the monitor has finished. The judgment made can either be "normal" or "fail". The normal judgment is made if the accumulated count is lower than a calibratable threshold at the judgment point. The failure judgment is made if the accumulated count equals or exceeds the calibratable threshold at the judgment point. If a failure judgment is made, then the relevant DTCs are stored within the engine management system.

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# **6.1.1 Monitoring Structure**

	Catalyst Monitoring Operation – Up to 2004 Model Year										
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL			
Catalyst efficiency Bank A Catalyst efficiency Bank B	P0420	Ratio of locus of upstream/ downstream HO2S during mixture dither.	Accumulative locus of downstream sensor	> 17	Engine speed Closed lop fuelling Engine Coolant Temperature Intake Air Temperature Mass Airflow Atmospheric pressure Airflow change Engine speed change Throttle angle change Idle Sub feedback compensation Air fuel ratio compensation Linear air fuel ratio compensation Fuel level Disable:	1300 to 3000 RPM Active 75 to 120 °C -20 to 110 °C 14 to 65 g/s > 70.0 kPa < 30 g/s/s < 360 RPM/s < 10 deg/s Inactive 0.9 to 1.1 0.75 to 1.25 0.5 to 1.5 > 11% P0101, P0102, P0103, P0 P0108, P0111, P0112, P0					
						P0118, P0121, P0122, P0 P0222, P0223, P0301, P0302, P0303, P0 P0307, P0308, P0443, P0 P0603, P1224, P1229, P1 P1316, P1367, P1368, P1609, P1611, P1 P1642, P1215, P1216, P1 P1338, P3029	123, P0128 1304, P0308 1444, P0448 251, P1313 631, P1633	5, P0128, 5, P0306, 5, P0460, 3, P1314, 3, P1637,			
					Bank A	P0031, P0032, P0037, P0 P0140, P0171, P0172, P0 P0207, P0351, P0353, P0	201, P0203	3, P0205,			
					Bank B	P0051, P0052, P0057, P0 P0160, P0174, P0175, P0 P0208, P0352, P0354, P0	202, P020 <sup>2</sup>	4, P0206,			

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Catalyst Monitoring Operation – From 2004 Model Year										
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL		
Catalyst efficiency Bank A  Catalyst efficiency Bank B	P0420	Ratio of locus of upstream/ downstream HO2S during mixture dither.	Accumulative locus of downstream sensor	>= 16 (XK8) >= 17 (XJ) >= 18 (V6 S-Type)	Intake Air Temperature  Mass Airflow  Atmospheric pressure  Airflow change  Engine speed change Throttle angle change Idle Sub feedback control Short term fuel trim Total fuel trim Fuel level  Disable:	1300 to 2900 (X-Type) 1300 to 3000 (V8) 1300 to 3250 (V6 S-Type) Active 75 to 119 °C -20 to 101 °C -8.13 to 110 °C (X-Type) 10 to 65 g/s 10 to 40 g/s (X-Type) >= 70.0 kPa >= 75.5 kPa (X-Type) <= 30 g/s/0.512s <=20 g/s/0.512s (X-Type) <= 360 RPM/0.512s <= 10 deg/1.024s Inactive 0.9 to 1.1 0.75 to 1.25 0.5 to 1.5 >= 11%  C1137, C1145, C1155, C1 P0101, P0102, P0103, P0 P0108, P0111, P0112, P0 P0117, P0118, P0121, P0 P0117, P0118, P0121, P0 P0195, P0128, P0181, P0 P0191, P0192, P0193, P0 P0441, P0443, P0444, P0 P0603, P1104, P1224, P1 P1234, P1236, P1251, P1 P1316, P1338, P1339, P1 P1609, P1611, P1631, P1 P1642	165, C1175 106, P0107, 113, P0116, 122, P0123, 182, P0223, 445, P0460, 229, P1233, 313, P1314, 367, P1368,	Cycles		

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		Cataly	st Monitoring O	peration – Fr	om 2004 Model Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL
					Bank A Bank B	P0031, P0032, P0037, P0 P0137, P0138, P0140, P0 P0201, P0203, P0205, P0 P0353, P0355, P0357 P0051, P0052, P0057, P0	171, P0172, 207, P0351,	Cycles
					Disable Additions:	P0157, P0158, P0160, P0 P0202, P0204, P0206, P0 P0354, P0356, P0358 P0069, P0607, P0627, P0	174, P0175, 208, P0352,	Cycles
						P2118, P2119, P2135, P2 P2632, P2633, P2634, P2		Cycles

		Cataly	yst Monitoring Op	eration –	2008 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Catalyst Monitoring Catalyst efficiency bank A Catalyst efficiency bank B	P0420 P0430	U/s HO2S signal locus compared to d/s HO2S signal locus during A/F dither.	Locus ratio	>= 13	Engine Speed Engine Coolant Temperature Intake Air Temperature Mass Airflow RPM change TP change MAF change Atmospheric pressure Sub F/B trim Total A/F trim (long + short term) short term A/F trim CL A/F control & sub F/B control Idle Fuel level	1300 < N < 3000 rpm >= 78 degC -8 < T < 110 degC 10 < MAF < 45 g/s <= 360 /512ms <= 15.0deg/1024ms <= 30 g/s/512ms >= 75.5 kPa 0.9 < F < 1.1 0.5 < F < 1.5  0.75 < trim < 1.25  Active Inactive >= 11 %	20 s	2 Drive Cycles

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		Cataly	st Monitoring O	peration – 2	2008 Model Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
					Fault Codes that disable P0430	P0300 P0301 P0303 P0309 P0306 P1313 P1314 P131 P0137 P0140 P0172 P017 P0069 P0118 P0117 P011 P0353 P0355 P1367 P136 P0205 P0031 P0032 P044 P0112 P0113 P0111 P062 P0629 P0102 P0103 P110 P0038 P0037 P1637 P164 P1609 P0128 P0193 P019 C0037 C003A P0501 P217 P0123 P0222 P0223 P213 P0607 P1633 P0305 P P1313 P1314 P1316 P0153 P P0175 P0174 P2229 P2228 P P0116 P0125 P0354 P P0202 P0204 P0206 P0051 P0443 P0112 P0113 P0111 P0629 P0102 P0103 P1104 P P0443 P0112 P0113 P0111 P0629 P0102 P0103 P1104 P P0443 P0112 P0113 P0111 P0629 P0102 P0103 P1104 P P0443 P0112 P0113 P0111 P0629 P0102 P0103 P1104 P P0113 P0119 P0113 P0119 P0113 P0119 P0113 P0119 P0119 P0113 P0119 P0119 P0113 P0119 P0119 P0119 P0113 P0112 P0123 P P1251 P1631 P0607 P1633	6 P0133 P01 1 P2229 P22 6 P0125 P03 8 P0201 P02 4 P0445 P04 7 P2635 P06 4 P0101 P00 2 P0603 P04 2 P0191 P01 9 P2118 P0 5 P1251 P16 0302 P0304 P 0158 P0157 P 0052 P0444 P 0627 P2635 P 0101 P0060 P 0460 P1609 P	228 351 203 443 528 054 460 181 122 531 20306 20160 20117 21368 20445 20628 20058 20128 20501

## **6.1.2 Drive Cycle Information**

Drive cycle under review.

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#### 6.2 Misfire Monitor

A misfire is caused by a failure of combustion. When this occurs, unburned HC and excess oxygen are exhausted from the cylinder. Consequently, the catalytic converter may suffer damage through overheating as it tries to convert the excessive HC. Secondly, the O2S will report a lean condition to the ECM, which in turn will increase the injector pulse width and add more raw fuel to the exhaust stream.

The misfire detection monitor is continuous and is designed to detect levels of misfire that can cause thermal damage to the catalyst and/or result in excessive tailpipe emissions. Determination of a misfire is made by analysis of changes in crankshaft speed, a misfire causing a drop in acceleration after an anticipated firing event. This data is analyzed in four ways to ensure all possible combinations of misfire can be detected.

The results of the misfire judgment process on each firing event are used to determine whether two failure levels have been met, 'catalyst damage' misfire and 'excess emissions' misfire. Each fault judgment process has its own failure threshold and calculation period.

#### Monitor DTCs

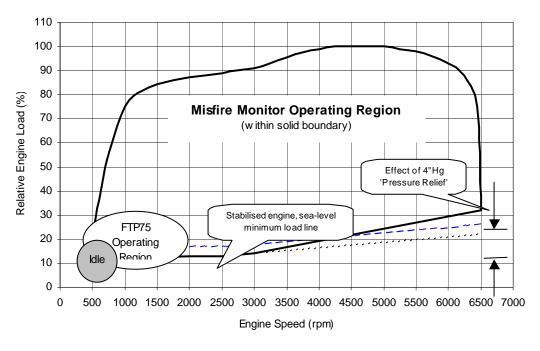
P0300 P0301 P0302	Random/multiple cylinder misfire Cylinder 1 (1 Bank A) misfire Cylinder 2 (1 Bank B) misfire
P0303	Cylinder 3 (2 Bank A) misfire
P0304	Cylinder 4 (2 Bank B) misfire
P0305	Cylinder 5 (3 Bank A) misfire
P0306	Cylinder 6 (3 Bank B) misfire
P0307	Cylinder 7 (4 Bank A) misfire (V8 engines only)
P0308	Cylinder 8 (4 Bank B) misfire (V8 engines only)
P1313	Catalyst damage misfire, Bank A
P1314	Catalyst damage misfire, Bank B
P1316	Excess emissions misfire

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#### **Monitoring Strategy**

The misfire monitor operates continuously within the boundaries of the regulated monitor operation window, as shown below:



Region of misfire monitor operation

After engine start, the monitor will enable as soon as the engine speed rises above the minimum operation speed (150 RPM below fully warm stabilized idle speed). Two revolutions of crank angle data, i.e. One sample of data from each cylinder firing, are 'buffered' before any decisions can be made by the monitor. Before engine speed has reached the top of the start flare the monitor will be ready to make misfire judgments, which are then made on every cylinder firing, irrespective of whether the monitor is enabled or not.

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# **6.2.1 Monitoring Structure**

		М	isfire Monitor Op	eration – Up	to 2004 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Random misfire  Misfire cylinder 1  Misfire cylinder 2	P0300 P0301	Crank speed fluctuation	Catalyst damage Excessive emissions		Steady state Engine speed (RPM) 4.2L N/A Auto 4.2L S/C Auto 3.0L Manual	450 - 6500 450 - 6200 580 - 7000	200 or 1000 revolutions	1+2 Drive Cycles 1+2 Drive Cycles
Misfire cylinder 3	P0302 P0303				3.0L Auto Engine Coolant Temperature Intake Air Temperature	530 - 7000 -8 to 120°C -8 to 100°C		1+2 Drive Cycles 1+2 Drive
					Atmospheric pressure	> 68 kPa		Cycles
Misfire cylinder 4	P0304				Fuel level Load	> 11% > Value in map		1+2 Drive Cycles
Misfire cylinder 5 Misfire cylinder 6	P0305 P0306					MIS2		1+2 Drive Cycles 1+2 Drive
Misfire cylinder 7 (V8)	P0307							Cycles 1+2 Drive Cycles
Misfire cylinder 8 (V8)	P0308							1+2 Drive Cycles
Misfire catalyst damage 1	P1313		Catalyst damage %	See table MIS1				No
Misfire catalyst damage 2	P1314		Catalyst damage %					No
Misfire excess emissions	P1316		Emissions failure Normally aspirated Supercharged					No
				Disable:	P0101-P0103, P1104, P0111- P011 P0336, P0460, P0603, P0121- P01 P0160, P0171, P0172, P0174, P01 P0831, P0832, P1234, P1236, P13 P1251, P1516, P1609, P1611, P16 C1137, C1165, C1175	23, P0137, P0138 75, P0181- P0183 38, P0222, P0223	, P0140, P0157, , P1233, P1339, , P1224, P1229,	P0158, P0106, P1230,

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			Misfire Monitor O	peration –	From 2004 Model Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL
Random misfire Misfire cylinder 1 Misfire cylinder 2 Misfire cylinder 3 Misfire cylinder 4 Misfire cylinder 5 Misfire cylinder 5 Misfire cylinder 6 Misfire cylinder 7 (V8) Misfire cylinder 8 (V8)	P0300 P0301 P0302 P0303 P0304 P0305 P0306 P0307 P0308	Crank speed fluctuation	Catalyst damage Excessive emissions		Steady state Engine speed (RPM) 4.2L NA Auto (XK8) 4.2L S/C Auto (XK8) 4.2L NA Auto (XJ) 4.2L S/C Auto (XK8) 3.0L Engine Coolant Temperature Intake Air Temperature Atmospheric pressure  Fuel level Load	450 to 6500 450 to 6200 450 to 6600 450 to 6400 530 - 7000 -8 to 119°C -40 to 119°C > 68 kPa > 75.5 kPa (X-Type) > 11% > Value in map	200 or 1000 revolutions	1+2 Drive Cycles
Misfire catalyst damage 1	P1313		Catalyst damage %	See table MIS1			200 revolutions	No
Misfire catalyst damage 2	P1314		Catalyst damage %					No
Misfire excess emissions	P1316		Emissions failure 4.2L normally aspirated 4.2L supercharged 3.0L S-Type X-Type manual X-Type automatic Disable:		5, C1155, C1165, C1175, P010			
		X-Type 2005 model year	Disable additional:	P0174, P0179 P0831, P0833 P1609, P161	3, P0125, P0128, P0137, P0138, 5, P0181-P0183, P0191-P0193, 2. P1104, P1224, P1229, P1233 1, P1631, P1633, P1637, P1642 7, P0627-P0629, P0851, P2118,	P0222, P0223, P033, P1234, P1236, P125	5, P0336, P0 51, P1338, P	460, P0603, 1339, P1516,

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			Misfire Monitor Oper	ation – 20	08 Model Year		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required
System  Misfire Monitoring  Random Misfire  Misfire cylinder 1  Misfire cylinder 2  Misfire cylinder 3  Misfire cylinder 4  Misfire cylinder 5  Misfire cylinder 6	P0300 P0301 P0302 P0303 P0304 P0305 P0306	Description  Crank speed fluctuation	Criteria  Misfire at catalyst damage level (200 rev block) or Misfire at excess emissions level (1000 rev block)	See table MIS1	Engine speed Engine Coolant Temperature Intake Air Temperature Atmospheric pressure Fuel level Engine load Fuel cut off Fuel cut off Ignition Retard Rough road Engine speed delta Engine load delta	Conditions  530 < N < 7000 rpm -8 < T < 119 degC -40 < T < 119 degC > 76 kPa >= 11 % Positive  Not active for at least 0.26 s Not detected for at least 0.5 s < 5078 rpm/s < 0.20 g/rev/64 ms for at	Depends on engine speed, misfire pattern and time after engine start
Misfire during first 1000 revs Catalyst damaging misfire Bank 1 Bank 2	P1316 P1313 P1314		Misfire during the first 1000 engine revolutions after start  Misfire at catalyst damage or excessive emissions level		Throttle angle delta  Fault Codes that disable Misfire Detection	P0138 P0137 P0140 P0158 P0 P0172 P0171 P0175 P0174 P0 P2229 P2228 P0069 P0118 P0 P0125 P0112 P0113 P0111 P0 P0628 P0629 P0102 P0103 P1 P0851 P1637 P1642 P0603 P0 P0128 P0193 P0192 P0191 P0 C003A P0501 P2119 P2118 P0 P0222 P0223 P2135 P1251 P1 P1633	335 P0336 117 P0116 627 P2635 104 P0101 460 P1609 181 C0037 1122 P0123

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#### 6.2.1 Misfire Detection

For the purposes of misfire detection, "steady - state" is defined as:

- At least 1 second since fuel cut-off was last invoked.
- At least 1 second since gear change was last made.
- At least 0.5 seconds since rough road detected (1second for 3.0L).
- At least 1 second since acceleration ignition retard was last invoked.
- At least 1 second since >15% shunt control ignition retard was last invoked (3.0L only).
- At least 1 second since fuel cut-off ignition retard was last invoked.
- At least 1 second since ISC feedback status (off to on only) changed.
- At least 1 second since A/C status (on or off) changed.
- At least 1 second since electrical load status (on or off) changed.
- At least 1 second since traction control ignition retard was last invoked.
- Rate of change of engine speed less than 250 RPM/0.064s.
- Rate of change of engine load has been less than 0.1g/revolution for at least 20 firing cycles.
- Rate of change of throttle angle is less than 1.5 degrees/0.008s.

							MIS1	– 2.5L							
Engine		Engine speed (RPM)													
load (g/s)	700	730	1000	1500	2000	2500	3000	3500	4000	4500	5000	5500	6000	6500	7000
0.30	148	148	138	116	100	100	100	90	82	74	42	32	32	20	18
0.60	124	124	108	108	90	82	70	64	58	50	42	32	32	20	18
0.80	106	106	106	100	82	74	60	56	50	42	36	30	24	20	18
1.00	100	100	100	82	74	66	50	50	42	32	30	28	32	20	20
1.20	88	88	88	74	62	44	42	40	32	32	28	28	32	30	30
1.40	88	88	88	74	62	60	56	56	48	36	36	32	32	36	36
1.60	88	88	88	74	62	60	56	56	48	36	36	32	32	36	36
2.00	88	88	88	74	62	60	56	56	48	36	36	32	32	36	36

Note: The figures in the map denote the number of misfires in 200 engine revolutions corresponding to catalyst damage misfire failure.

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	MIS1 – 3.0L (S-Type)														
Engine		Engine speed (RPM)													
load (g/s)	680	680         730         1000         1500         2000         2500         3000         3500         4000         4500         5000         5500         6000         6500         7000													
0.25	150	150													
0.3	138	138	138         125         120         119         110         100         93         93         74         70         66         66         62         58												
0.4	126	126													
0.6	121	121	118	118	102	93	80	69	67	56	55	46	46	43	42
0.9	117	117	111	100	84	72	60	53	52	48	39	31	31	27	26
1.2	93	93	93	76	67	58	56	50	51	38	32	23	23	23	23
1.3	84	84	84	77	64	61	50	41	44	27	27	26	26	25	25
1.6	100	100	100	77	73	68	50	46	57	50	41	36	38	39	38

Note: The figures in the map denote the number of misfires in 200 engine revolutions corresponding to catalyst damage misfire failure.

						MI	S1 - 3.0	L (X-Typ	oe)						
Engine		Engine speed (RPM)													
load (g/s)	700   730   1000   1500   2000   2500   3000   3500   4000   4500   5000   5500   6000   6500   7000												7000		
0.30	148	148	134	116	106	90	70	68	64	56	40	20	26	26	24
0.60	126	126	120	106	90	76	64	58	50	38	32	20	20	20	24
0.80	100	100	100	90	76	64	56	50	40	26	20	18	18	18	24
1.00	84	84	84	80	62	56	42	38	40	26	20	14	14	18	20
1.20	68	68	68	64	50	46	40	34	26	26	30	26	26	26	26
1.40	78	78	78	64	56	46	26	20	26	30	30	30	28	26	34
1.60	78	78	78	64	56	46	50	50	34	30	34	32	34	32	34
2.00	78	78	78	64	56	46	50	50	34	30	34	32	34	32	34

Note: The figures in the map denote the number of misfires in 200 engine revolutions corresponding to catalyst damage misfire failure.

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		MIS1 – 4.2L Normally Aspirated												
Engine		Engine speed (RPM)												
load (g/s)	600	650	1000	1500	2000	2500	3000	3500	4000	4500	5000	5500	6000	6500
0.3	187	187	179	167	140	122	118	104	94	89	74	60	51	62
0.4	183	183	175	163	137	119	114	100	94	86	70	56	47	58
0.6	173	173	165	153	134	109	109	109	92	83	68	53	44	56
8.0	164	164	156	146	133	120	106	94	83	66	53	41	30	40
1.2	151	151	143	114	96	75	75	63	50	33	20	20	20	20
1.6	122	122	114	94	75	58	50	29	26	20	20	20	20	20
2.2	120	120	112	92	74	58	45	33	26	27	26	31	31	34
2.8	120	120	112	92	74	60	48	36	31	30	26	31	31	34

Note: The figures in the map denote the number of misfires in 200 engine revolutions corresponding to catalyst damage misfire failure.

						MIS1 - 4	.2L Supe	rcharge	d					
Engine							Engine s	peed (RPM	)					
load (g/s)	600	650	1000	1500	2000	2500	3000	3500	4000	4500	5000	5500	6000	6200
0.4	186	186	180	164	150	134	117	101	89	77	64	68	72	74
0.6	186	186	178	160	150	130	110	97	85	73	60	64	68	70
1	183	183	175	159	142	125	108	93	77	63	49	51	52	53
1.6	158	158	150	134	117	104	90	72	54	50	46	52	57	60
2.2	125	125	117	109	100	93	85	66	47	49	52	58	64	68
2.8	122	122	114	88	62	52	42	50	57	56	56	68	80	84
3.4	116	116	108	84	60	55	50	54	58	57	57	69	74	77
3.8	116	116	108	84	60	55	50	53	61	65	70	71	73	77

Note: The figures in the map denote the number of misfires in 200 engine revolutions corresponding to catalyst damage misfire failure.

	MIS2 – 2.5L Automatic											
EOT (°C)	Engine speed (RPM) 700 730 1000 1500 2000 2500 3000 7000											
-10	0.64	0.64	0.64	0.43	0.43	0.43	0.43	0.72				
20	0.39	0.39	0.39	0.33	0.33	0.33	0.34	0.63				
50	0.27	0.27	0.27	0.25	0.26	0.26	0.27	0.56				
80	0.22	0.22	0.22	0.20	0.22	0.22	0.23	0.52				

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	MIS2 – 2.5L Automatic (2005 Model Year X-Type)											
EOT (°C)	Engine speed (RPM)											
	500	650	1000	1150	1380	1800	2300	2550	2760	3000	7000	
-8	0.45	0.45	0.45	0.45	0.45	0.46	0.47	0.47	0.47	0.47	0.72	
15	0.32	0.32	0.32	0.32	0.33	0.37	0.38	0.38	0.38	0.38	0.63	
45	0.26	0.26	0.26	0.26	0.28	0.32	0.32	0.32	0.32	0.32	0.57	
80	0.21	0.21	0.23	0.24	0.25	0.26	0.27	0.28	0.28	0.28	0.53	

	MIS2 – 2.5L Manual											
EOT (°C)	Engine speed (RPM)											
	700	700 730 1000 1500 2000 2500 3000 7000										
-10	0.47	0.47	0.47	0.33	0.33	0.34	0.35	0.64				
20	0.32	0.32	0.32	0.26	0.26	0.27	0.28	0.57				
50	0.23	0.23	0.23	0.21	0.22	0.23	0.24	0.53				
80	0.19	0.19	0.19	0.18	0.19	0.20	0.20	0.49				

	MIS2 – 2.5L Manual (2005 Model Year X-Type)												
EOT (°C)	Engine speed (RPM)												
	500	500 650 785 960 1165 1410 1725 2180 2700 3000 7000											
-8	0.50	0.50	0.50	0.43	0.37	0.33	0.33	0.33	0.37	0.37	0.66		
15	0.36	0.36	0.36	0.31	0.27	0.25	0.27	0.28	0.30	0.30	0.59		
45	0.26	0.26	0.26	0.24	0.21	0.22	0.24	0.25	0.25	0.26	0.55		
80	0.20	0.20	0.20	0.20	0.18	0.18	0.20	0.20	0.20	0.21	0.50		

	MIS2 – 3.0L S-Type Automatic											
EOT (°C)	Engine speed (RPM) 680 730 1000 1500 2000 2500 3000 7000											
-8.1	0.599	0.599	0.599	0.523	0.504	0.504	0.504	0.832				
20	0.404	0.404	0.404	0.409	0.399	0.4	0.38	0.709				
50	0.34	0.33	0.32	0.32	0.32	0.32	0.35	0.678				
80	0.295	0.29	0.27	0.27	0.255	0.26	0.26	0.589				

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	MIS2 – 3.0L S-Type Manual												
EOT (°C)	Engine speed (RPM)												
	680	680         730         1000         1500         2000         2500         3000         7000											
-8.1	0.399	0.399	0.399	0.399	0.409	0.432	0.432	0.841					
20	0.32	0.32	0.33	0.335	0.335	0.34	0.361	0.77					
50	0.3	0.3	0.314	0.29	0.29	0.3	0.3	0.709					
80	0.275	0.275	0.27	0.25	0.245	0.25	0.25	0.659					

	MIS2 – 3.0L X-Type Automatic											
EOT (°C)	Engine speed (RPM)											
	700 730 1000 1500 2000 2500 3000 7000											
-10	0.55	0.55	0.55	0.44	0.44	0.44	0.44	0.79				
20	0.41	0.41	0.41	0.35	0.36	0.36	0.36	0.71				
50	0.32	0.32	0.32	0.28	0.29	0.29	0.30	0.65				
80	0.24	0.24	0.24	0.22	0.22	0.23	0.24	0.59				

	MIS2 – 3.0L X-Type Manual											
EOT (°C)	Engine speed (RPM) 700 730 1000 1500 2000 2500 3000 7000											
-10	0.54	0.54	0.54	0.37	0.37	0.38	0.38	0.72				
20	0.36	0.36	0.36	0.30	0.30	0.30	0.30	0.64				
50	0.25	0.25	0.25	0.24	0.24	0.25	0.25	0.59				
80	0.23	0.23	0.23	0.20	0.20	0.20	0.21	0.55				

	MIS2 – 4.2L Normally Aspirated												
EOT (°C)	Engine speed (RPM)												
	600	600 650 1000 1500 2000 2500 3000 6500											
-8	0.45	0.45	0.45	0.45	0.46	0.46	0.46	0.88					
20	0.38	0.38	0.38	0.39	0.4	0.4	0.42	0.83					
50	0.31	0.31	0.31	0.32	0.33	0.33	0.34	0.75					
80	0.24	0.24	0.24	0.25	0.26	0.25	0.26	0.67					

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	MIS2 – 4.2L Supercharged											
EOT (°C)	Engine speed (RPM)											
	600	600 650 1000 1500 2000 2500 3000 6500										
-8	0.6	0.6	0.6	0.6	0.62	0.64	0.66	1.21				
20	0.5	0.5	0.5	0.51	0.51	0.52	0.54	1.09				
50	0.37	0.37	0.37	0.38	0.4	0.41	0.44	0.99				
80	0.28	0.28	0.28	0.28	0.29	0.31	0.35	0.9				

# **6.2.2 Drive Cycle Information**

Drive cycle under review.

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### 6.3 Heated Oxygen Sensor Monitor

An O2S comprises of a gas-tight zirconium dioxide ceramic tube covered with thin layer of platinum. One end of the tube is open to atmosphere; the other end is sealed and protrudes into the exhaust. When the tube is filled with oxygen rich atmospheric air, and the outer walls are exposed to the oxygen depleted exhaust gases, a chemical reaction takes place and produces a voltage. The voltage output reflects the differences in oxygen concentrations on either side of the ceramic sensor element. As the oxygen content decreases, the voltage increases. As the oxygen content increases, the voltage decreases.

The oxygen content of the exhaust gas stream is directly related to the air fuel mixture supplied to the engine. The voltage output by the O2S is typically 800 to 1000mV for rich mixtures, and around 100mV for lean mixtures.

The ceramic material in the sensor becomes sensitive to the presence of oxygen in the exhaust gas stream at around 315°C. An internal heater is used to bring the sensor quickly up to the operating temperature.

The engine management system runs two tests on the upstream and downstream HO2S, one on the sensor operation and one on the sensor's internal heater.

Note: Only the rear oxygen sensors are used for fuel control.

#### 6.3.1 Downstream Oxygen Sensors High/Low Input Monitor

The downstream O2S are checked for their maximum and minimum output values. The monitor increments an execution timer if the monitor entry conditions are satisfied. A low voltage failure is judged if the output of the sensor does not exceed a calibrated value prior to the monitor execution timer exceeding its calibrated failure threshold. A high voltage failure is judged if the sensor output remains above a calibrated value after the monitor execution timer has exceeded its calibrated failure threshold or after a defined period of over run fuel cut off has been conducted. Additionally, a high voltage failure is invoked if the sensor voltage exceeds battery short threshold for the required time.

Note: Unless specifically included in the tables below, Intake Air Temperature, Engine Coolant Temperature, vehicle speed and time after start up are not critical to enable these monitors.

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# **6.3.2 Monitoring Structure**

	Heated Oxygen Sensor Monitor Operation – Up to 2004 Model Year												
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL					
System	Codes	Description	Criteria	value	Parameter	Conditions	Required						
Downstream HO2S Bank A high voltage	P0138	Sensor voltage stuck high	Sensor voltage	0.9 volts During fuel cut off, duration > 3.8s 2 volts anytime	Air fuel rate feedback compensation: Closed loop compensation: Closed loop compensation Average: Engine Coolant Temperature: Intake Air Temperature: Time after start up	0.75 – 1.25 0.5 – 1.5 0.85 – 1.15 70 – 110 °C -8 – 100 °C 2 seconds	60s	2 Drive Cycles					
Downstream HO2S Bank B high voltage	P0158				Disable:	See HO2S downstream no activity check.		2 Drive Cycles					

	Heated Oxygen Sensor Monitor Operation – From 2004 Model Year (XK8, S-Type and New XJ)												
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL					
HO2S Bank A high voltage	P0138 P0158	Sensor voltage stuck high		>= 0.95 volts or >=2 volts anytime		>= 5s (S-Type) >= 3.5s (XJ)	3.8s (XK8) 5s (S-Type) 3.5s (XJ) Immediate 0.5s (XJ)	2 Drive Cycles 2 Drive Cycles					
g renage					Disable:	See HO2S downstr	eam no activit	y check.					

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Heated Oxygen Sensor Monitor Operation – From 2004 Model Year (X -Type)										
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL		
Downstream HO2S Bank A low input	P0137	Sensor voltage stuck low	Sensor voltage	< 0.30 volts	Heater control HO2S heater power Engine speed Mass Airflow	Active >=180 Watt sec >= 1500 RPM >= 15 g/s	151s	2 Drive Cycles		
Downstream HO2S Bank B low input	P0157				Atmospheric pressure Target Lambda Engine Coolant Temperature Intake Air Temperature	>= 74.5 kPa 0.75 to 1 70 to 119 °C -10 to 119°C		2 Drive Cycles		
Downstream HO2S Bank A high input	P0138	Sensor voltage stuck high	Sensor voltage or	> 0.80 volts	Time after start Closed loop fuelling Over run fuel cut off time	>= 30s Active >= 30s (high I/P)	151s	2 Drive Cycles		
	P0158		Sensor voltage	> 1.24 volts	Anytime		0.5s	2 Drive Cycles		
					Disable:	See HO2S downstream no activity check.				

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		Heated Ox	kygen Sensor Monit	tor Operat	ion – 2008 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Downstream HO2S Bank A low input Downstream HO2S Bank B low input	P0137	Sensor voltage stuck low	Maximum sensor voltage	< 0.04 V	Target lambda Closed Loop Fuelling Battery voltage Accumulated Mass Air Flow (This accumulates if: Atmospheric pressure Engine Coolant Temperature Intake Air Temperature Afterstart counter  Accumulated Heater Duty (This accumulates if: MAF accumulation conditions	0.75 <= Lambda <= 1.25	5 s	2 Drive Cycles
					Heater control Accumulated HO2S heater energy Engine Speed Target lambda	>= 180 Watt Seconds >= 500 rpm		
Downstream HO2S Bank A high input Downstream HO2S Bank B high input	P0138	Sensor voltage stuck high	Minimum sensor voltage	> 0.15 V	Closed Loop Fuelling Accumulated Mass Air Flow Accumulated Heater Duty An over run fuel cut off has occurred, duration	Active >= 185  >= 1400 >= 3.0 sec (U/s HO2S signal must be >= 0.75 during the fuel cut)		2 Drive Cycles
		<u>or</u>	sensor voltage	> 1.24 V			0.512 s	2 Drive Cycles
					Fault Codes that disable Bank A Bank B	See P0140 Monitor See P0160 Monitor		

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## 6.3.3 Downstream Oxygen Sensors Heater Circuit High

Heater resistance checks are performed when the heater is commanded on. If resistance values are outside of the limits when the heater is enabled, then a failure judgment is made.

## 6.3.4 Monitoring Structure

Heated Oxygen Sensor Monitor Operation										
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System Heater control circuit Bank A high input		Description Heater resistance check when on	Criteria Outside limits	value	Parameter	Conditions	Required 0.432s 0.4s (2004 model year) 0.43s (2008	2 Drive Cycles		
Heater control circuit Bank B downstream high input	P0058	Heater resistance when on	Outside limits		Disable:	P1609, P0603	model year) 0.432s 0.4s (2004 model year) 0.43s (2008 model year)	2 Drive Cycles		

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#### 6.3.5 Downstream Oxygen Sensors Heater Circuit Low

Heater resistance checks are performed when the heater is commanded off. If resistance values are outside of the limits, then a failure is flagged.

#### 6.3.6 Monitoring Structure

	Heated Oxygen Sensor Monitor Operation												
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL					
System	Codes	Description	Criteria	value	Parameter	Conditions	Required						
circuit Bank A low input	P0057	Heater resistance check when off  Heater resistance check when off	Outside limits Outside limits				0.432s 0.4s (2004 model year) 0.43s (2008 model year) 0.432s 0.4s (2004 model year)	2 Drive Cycles 2 Drive Cycles					
					Disable:		0.43s (2008 model year)						

# 6.3.7 Downstream Oxygen Sensors No Activity Detected

The monitor is single shot monitor (runs once per trip), which is designed to operate only when the sensor has been lit off (up to operating temperature). The monitor can be sub divided into two sections:

#### Stuck low

(Output voltage less than calibrated threshold (0.4 volts).

The monitor initially examines the fuelling control to ensure the system is stable, that linear airflow rate closed loop control, and sub feedback execution has been invoked. Once these conditions are satisfied and a calibrated load/airflow has been achieved, a lean stuck timer is incremented. The monitor then checks the output voltage from the sensor and sets a normal end judgment if a calibrated change in sensor output voltage is observed. If the change in sensor voltage is not detected and the lean stuck timer exceeds the failure threshold, and the associated failure conditions are satisfied, then a failure end judgment is made.

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#### Stuck high

(Output voltage greater than calibrated threshold (0.4 volts).

Again, the monitor strategy checks for stable air fuel ratio control prior to commencing the examination of the sensors output voltage. The monitor then utilizes the lean switching characteristics of the sensor during an over run fuel cut off (where the sensors output voltage tends towards 0 volts), to determine its correct operation. Finally, if the duration of the fuel cut off exceeds a calibrated period and the output voltage of the sensor is greater than calibrated threshold, then a failure judgment is set.

# 6.3.8 Monitoring Structure

		Heated Oxyg	gen Sensor Monitor	Operation -	Up to 2004 Model Ye	ar		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
D/s HO2S Bank	P0140	D/s HO2S voltage	Sensor voltage	< 0.4 volts for	Heater energy	> 524 Joules	600s	2 Drive
A no activity				600s	Airflow	> 10 g/s		Cycles
D/s HO2S Bank					Engine speed	> 1500 RPM		
B no activity	P0160				Engine Coolant Temperature			
				> 0.4 volts	Intake Air Temperature	-10 °C		2 Drive
				during fuel cut	Short term fuel trim	0.75 – 1.25		Cycles
				off	Total fuel trim	0.5 – 1.5	3.8s	
					Sub feedback control	Executing		
					Linear air fuel control	Executing		
					Atmospheric pressure	>= 70 kPa		
						>= 0 kPa (2004		
					Fuellevel	model year V6 S-		
					Fuel level	Type) > 11%		
					Disable:	P1313, P1314, P131	6, P0106 - P0	108,
						P0116 – P0118, P01	25, P1367, P1	368,
						P0444, P0445, P011	1 - P0113, P1	234,
						P1236, P1338, P010	1 – P0103, P1	104,
						P1637, P1642, P060		
						P0128, P1229, P122		
						P1251, P1631, P161		
						P0443, P0222, P022		
			1			P0181- P0183 C116	5, C1175, C11	37

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	Bank A Bank B	P0131 – P0133, P0171, P0172, P0351, P0353, P0355, P0357, P0201, P0203, P0205, P0207 P0031, P0032, P0037, P0038 P0151 – P0153, P0174, P0175, P0352, P0354, P0356, P0358 P0202, P0204, P0206, P0208 P0051, P0052, P0057, P0058.
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	He	ated Oxygen Sensor Me	onitor Operation – Fi	rom 2004 M	odel Year (XK8, S-Ty	pe and new XJ)		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
D/s HO2S Bank A no activity D/s HO2S Bank		D/s HO2S voltage	Sensor voltage		Heater energy Airflow Engine speed Engine Coolant Temperature Intake Air Temperature Atmospheric pressure Fuel level	>= -10 °C >= 70 kPa > 11%		2 Drive Cycles 2 Drive Cycles
				with movement of < 0.2 volts	Total fuel trim Sub feedback control Over run fuel cut off duration		3.8s (XK8) 3.5s (XJ) 5s (S-Type)	
				Disable: Bank A Bank B	C1137, C1145, C1155, C1165 P0107, P0108, P0111, P0112 P0122, P0123, P0125, P0128 P0193, P0222, P0223, P0441 P1104, P1224, P1229, P1233 P1316, P1338, P1339, P1367 P1637, P1642 P0031, P0032, P0037, P0038 P0201, P0203, P0205, P0207 P0051, P0052, P0057, P0058 P0202, P0204< P0206, P0208	, P0113, P0116, P01 , P0181, P0182, P01 , P0443, P0444, P04 , P1234, P1236, P12 , P1368, P1609, P16 , P0131, P0132, P01 , P0351, P0353, P03 , P0151, P0152, P01	17, P0118, P0 83, P0191, P0 45, P0460, P0 51, P1313, P1 11, P1631, P1 33, P0171, P0 55, P0357 53, P0174, P0	121, 192, 603, 314, 633,

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		Heated Oxygen S	Sensor Monitor Opera	ation – Fro	m 2004 Model Year (X-	-Type)		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
D/s HO2S Bank	P0140	D/s HO2S voltage	Sensor voltage	< 0.5 v	Heater control	Active	151s	2 Drive
A no activity					3,	>= 180 watts sec		Cycles
D/s HO2S Bank						>=15 g/s		
B no activity	P0160				3 - 1	>= 1500 RPM		
					Engine Coolant Temperature			2 Drive
						-10 to 119 °C		Cycles
						>= 74.5 kPa		
						30s		
					3	0.75 to 1		
						Active		
				Dia alala	Over run fuel cut off duration		00 00400 0	100
				Disable:	C1137, C1145, C1155, C1165			
					P0107, P0108, P0111, P0112			
					P0122, P0123, P0125, P0128			
					P0193, P0222, P0223, P0441 P1104, P1224, P1229, P1233			
					P1316, P1338, P1339, P1367			
					P1637, P1642	, F1300, F1009, F10	11, F1031, F1	033,
			Disable Additions (2005 mod	lel vear):	P0069, P0335, P0336, P0607	DOG27 DOG28 DOG2	0 D2118 D24	110
			Disable Additions (2005 mod	iei yeai).	P2135, P2228, P2229, P2632			113,
				Bank A	P0031, P0032, P0037, P0038			172
				Darik / (	P0201, P0203, P0205, P0207			, , , ,
				Bank B	P0051, P0052, P0057, P0058			175
				Dank D	P0202, P0204< P0206, P0208			
					. 5252, 1 525 1 1 5255, 1 5256	5, 1 0002, 1 000 1, 1 00		

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		Heated Oxy	gen Sensor M	Ionitor O	peration – 2008 Model Yea r (	(X-Type)		
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
Oxygen Sensors Downstream (HO2S) D/s HO2S A bank no activity D/s HO2S B bank no activity	P0140 P0160	D/s HO2S sensor voltage behaviour	D/s HO2S voltage max - min	< 0.35 V	Closed Loop Fuelling Fuel tank level D/s HO2S Voltage check (P0137/57 & P0138/58 diagnostic) Battery voltage Accumulated Mass Air Flow (This accumulates if: Atmospheric pressure Engine Coolant Temperature Intake Air Temperature Afterstart counter  Accumulated Heater Duty (This accumulates if: MAF accumulation conditions Heater control Accumulated HO2S heater energy Engine Speed Target lambda  An over run fuel cut off has occurred, duration	-10 < T < 120 degC -10 < IAT < 120 degC >= 20 s) >= 1400 True Active >= 180 Watt Seconds		2 Drive Cycles

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		Heated O	xygen Sensor	Monitor	Operation – 2008 Model Yea	a r (X-Type)		
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
Oxygen Sensors Downstream (HO2S) D/s HO2S A	P0140	D/s HO2S sensor	D/s HO2S voltage	< 0.35 V	Closed Loop Fuelling	Active		2 Drive
bank no activity  D/s HO2S B  bank no activity	P0160	voltage behaviour	max - min		Fuel tank level D/s HO2S Voltage check (P0137/57 & P0138/58 diagnostic) Battery voltage Accumulated Mass Air Flow (This accumulates if: Atmospheric pressure Engine Coolant Temperature Intake Air Temperature Afterstart counter	-10 < T < 120 degC -10 < IAT < 120 degC		Cycles
					Accumulated Heater Duty (This accumulates if:  MAF accumulation conditions Heater control Accumulated HO2S heater energy Engine Speed Target lambda  An over run fuel cut off has occurred, duration	Active >= 180 Watt Seconds		

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### 6.3.9 Upstream Oxygen Sensors Circuit

This monitors the upstream O2S element current. If the current is above or below a calibrated value, and the stable operating conditions are satisfied, a failure timer is incremented, otherwise a normal timer is incremented. Upon exceeding the calibrated thresholds for either the failure/normal timers, an appropriate failure/normal end judgment is set.

# **6.3.10 Monitoring Structure**

			Heated Oxyge	n Sensor	Monitor Operation			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL
U/s HO2S Bank A low input	P0131	Element current	Element current stuck low	<= - 15.0 mA	Closed loop fuelling Sub feedback control U/s HO2S voltage Engine speed	Active Active 0.2 – 0.85 volts >= 1500 RPM	10s	2 Drive Cycles
U/s HO2S Bank B low input	P0151				After start time Vehicle speed Engine Coolant Temperature Intake Air Temperature	>= 0.9s >= 9 mph >= 40 °C >= - 40 °C >= - 30 °C (2008)	10s	2 Drive Cycles
U/s HO2S Bank A high input	P0132	Element current	Element current stuck high	>= 15.0 mA	Atmospheric pressure Mass Airflow Delta load	>= 75 kPa >= 10 g/s < 3.125 g/revolutions/s for >2s (=< 0.05 g/revolutions/s for 3.0L)		2 Drive Cycles
					Element impedance	20 – 60 ohms 0 – 60 ohm (X-Type)		
U/s HO2S Bank B high input	P0152				Purge vapor concentration or Purge Fuel cut off	>= 0.9  Not active Not active		2 Drive Cycles
					Disable: Bank A Bank B Disable: Bank A Bank B	P0132 P0152 P0131 P0151		

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#### 6.3.11 Upstream Oxygen Sensors Slow Response

The failure criteria for this monitor is the measurement of the time taken for the upstream sensor to attain a calibrated air fuel ratio reading following fuel reinstatement after an over run fuel cut off. The slow response monitor measures the response time of the sensor to react when the air fuel ratio changes from a known lean state to a known non-lean state. The monitor operates after fuelling has been reinstated and the engine management system is in ISC mode, following a period of fuel cut off. If all execution conditions are satisfied the monitor increments a response timer, if the timer exceeds a failure threshold prior to the sensor current switching back to a non-lean condition (6.97mA) a failure end judgment flag is set. If the current signal passes through the lean limit prior to the timer exceeding the failure threshold, then a normal end judgment is set. It should be noted that the slow response monitor is a single shot monitor, which only executes once per drive cycle.

#### Fuel Cut Off Operation

A timer is employed to ensure that a minimum period of fuel cut off is achieved prior to executing the monitor. This allows the sensors to respond to the lean air fuel ratio fuelling shift, which occurs during the period of fuel cut off.

#### **6.3.12 Monitoring Structure**

	Heated Oxygen Sensor Monitor Operation – Up to 2004 Model Year											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
U/s HO2S Bank	P0133	Response time of sensor from	Response rate time	2.6s (4.2L NA)	Engine speed	600 – 4000 RPM	< 5s	2 Drive				
A slow		lean to rich after over run fuel		> 4.02s (S-Type)	Airflow	< 70 g/s		Cycles				
response		cut off		> 3.2s (S/C)	Engine Coolant Temperature	70 to 110 °C						
					Intake Air Temperature	-30 to 100 °C						
					Atmospheric pressure	> 68 kPa						
U/s HO2S Bank	P0153				Element impedance	20 to 60 ohm		2 Drive				
B slow					Throttle closed flag	Set		Cycles				
response					Fuel cut off time	2 – 40s						
				D:	Closed loop fuelling	Active	 					
				Disable:	P1316, P0106–P0108, P0116–							
					P0111–P0113, P1313, P1314,							
					P0101- P0103, P1104, P1637, P1224, P0121-P0123, P0222, I	, ,	, ,	,				
					P0441, P0443, P0181-P0183, I	, ,	, ,	,				
				Bank A	P0132, P0131, P0137, P0138,	,	, ,					
				Dank A	P0355, P0357, P0201, P0203,			333,				
				Bank B	P0152, P0151, P0157, P0158,			354.				
					P0356, P0358, P0202, P0204,			,				

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		Heated Oxyg	jen Sensor Mo	nitor Operation	on – From 2004 Model \	/ear		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
U/s HO2S Bank	P0133	Response time of sensor from	Response rate time	>= 3.5s (X-Type)	Engine speed	600 – 4000 RPM		2 Drive
A slow		lean to rich after over run fuel		>= 4.0s (S-Type)	Airflow	< 70 g/s	4.0s (S-Type)	Cycles
response		cut off			Engine Coolant Temperature	70 to 110 °C	2.6s (XJ N/A)	
					Intake Air Temperature		3.2s (XJ S/C)	
					Atmospheric pressure		2.6s (XK8 N/A)	
				>= 4.0s (XK8 S/C)	Element impedance		4.0s (XK8 S/C)	
						20 to 60 ohm (XK8)		
II/ IIOOO D	D0450				T 1. 1.0	0 to 60 ohm (X-Type)		
U/s HO2S Bank	P0153				Throttle closed flag	Set		2 Drive
B slow					Fuel cut off time	2 to 60s (X-Type)		Cycles
response						4 to 60s (S-Type) 2 to 40s (XJ)		
					Closed loop fuelling	Active		
				Disable:	C1137, C1145, C1155, C1165, (		P0103 P0106	P0107
					P0108, P0111, P0112, P0113, F			
					P0125, P0128, P0181, P0182, F			
					P0441, P0443, P0444, P0445, F			
					P1234, P1236, P1251, P1313, F			
					P1609, P1611, P1631, P1633, F		, , , , , , , , , , , , , , , , , , , ,	,
			Disable additions (2	2005 model year X-	P0069, P0335, P0336, P0607,P	0627, P0628, P0629, F	2118, P2119, P	2135,
			Type):	·	P2228, P2229, P2632, P2633, F	2634, P2635, P2636		
				Bank A	P0132, P0131, P0137, P0138, F	20140 P0172 P0171 I	P0351 P0353 F	P0355
					P0357, P0201, P0203, P0205, F			0000,
					P0152, P0151, P0157, P0158, F		P0352. P0354. F	P0356.
					P0358, P0202, P0204, P0206, F		,, -	,

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		Heated Oxygen	Sensor Monito	or Operat	ion – 2008 Model Yea	r (X-Type)		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	,	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Oxygen Sensors Upstream (U/S HO2S) U/s HO2S A slow response U/s HO2S B slow response	P0133	Accumulated response time to forced fuelling dither during steady state driving. (Test runs twice, 15 seconds each time, separated by a minimum of 5 seconds)	Ratio of amplitude difference between the A/F control and the u/s HO2S output	< 0.3	CL A/F control  Catalyst Diagnostic  Time after start Engine Speed Vehicle speed Engine Load Mass Airflow  Engine Coolant Temperature Atmospheric pressure Element impedance Engine load change Throttle angle change Purge  Accelerator pedal movement  Fault Codes that disable Bank A	Active  Not in Progress  >= 180 s  1400 < N < 3500 rpm  0 <= v <= 420 mph  0.22 < Load < 0.80 g/s  6.2 < MAF < 35 g/s  >= 68.1 degC  >= 68 kPa  20 < R < 80 ohm  <= 0.40 g/rev/0.128 s  <= 10.0 deg/0.128 s  Not active, or vapour concentration <= 1.0  >= 10 deg/0.256 s on less than 5 occasions during execution of this diagnostic  P0300 P0301 P0303 P0305 P030 P1313 P1314 P1316 P0132 P013 P0140 P0172 P0171 P2229 P222 P0117 P0116 P0125 P0351 P038 P1368 P0201 P0203 P0205 P000 P0445 P0443 P0112 P0113 P017 P0628 P0629 P0102 P0103 P110 P1642 P0603 P0460 P1609 P012 P0191 P0181 C0037 C003A P05 P0122 P0123 P0222 P0223 P213 P0607 P1633	35 s 35 s 35 s 31 P0138 F 28 P0069 F 33 P0355 F 31 P0032 F 11 P0627 F 04 P0101 F 28 P0193 F 01 P2119 F	20137 20118 21367 20444 22635 21637 20192 22118

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		Heated Oxyger	Sensor Monit	tor Operati	on – 2008 Model Yea	r (X-Type)		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
		•			Fault codes that disable			
					Bank B	P0300 P0301 P0303 P0305 P03	02 P0304 P	0306
						P1313 P1314 P1316 P0152 P01		
						P0160 P0175 P0174 P2229 P22		
						P0117 P0116 P0125 P0352 P03		
						P1368 P0202 P0204 P0206 P00		-
						P0445 P0443 P0112 P0113 P01		
						P0628 P0629 P0102 P0103 P11	04 P0101 P	1637
						P1642 P0603 P0460 P1609 P01	28 P0193 P	0192
						P0191 P0181 C0037 C003A P05	501 P2119 F	2118
						P0122 P0123 P0222 P0223 P21	35 P1251 P	1631
						P0607 P1633		

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# 6.3.13 Upstream Oxygen Sensors Heater Circuit

The control module monitors the heater current to be within limits. If a failure is detected, the control module responds by setting the appropriate signal failure code. On detection of a failure code the monitor proceeds to increment a failure timer and a judgment is made if the failure timer exceeds a calibrated threshold. If a failure code is not present, then the monitor increments a normal judgment timer and sets a judgment upon exceeding a calibrated threshold.

# **6.3.14 Monitoring Structure**

			Heated Oxygen Se	nsor Monitor (	Operation			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Heater control	P0031	Control module monitors heater	Outside limits		HO2S control	Executing	3.6s	2 Drive
circuit Bank A		for current to be within limits			Heater on	>= 1.02s (2008)		Cycles
low input								
			Outside limits		HO2S control	Executing	3.6s	2 Drive
circuit Bank A		for current to be within limits			Heater on	>= 1.02s (2008)		Cycles
high input	D0054				11000	·	0.0	0.0
			Outside limits		HO2S control	Executing	3.6s	2 Drive
circuit Bank B		for current to be within limits			Heater on	>= 1.02s (2008)		Cycles
low input	P0052	Control module monitors heater	Outside limits		HO2S control	Evecution	3.6s	2 Drive
Heater control circuit Bank B		for current to be within limits	Outside iimits		Heater on	Executing >= 1.02s (2008)	3.08	
high input		lor carrent to be within limits			i leater on	>= 1.025 (2006)		Cycles
ingii iiput					Disable:	P1609, P0603		

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# **6.3.15 Drive Cycle Information**

11	pstream		on co	ncore
u	ustrean	ıı oxva	en se	115015

Drive cycle under review.

#### Downstream oxygen sensors:

Drive cycle under review.

#### Oxygen sensor heaters:

Drive cycle under review.

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#### 6.4 Electronic Control Module

The control function within the ECM enables hardware checks to be performed on the sensors. These DTCs will reflect sensor open circuit and short circuit faults along with heater faults. In addition to sensor fault monitoring these DTCs will also reflect failures of the control functions themselves. The sensor impedance is also monitored to ensure that its impedance is below the required level for correct operation after the sensor has been active for the required time.

# **6.4.1 Monitoring Structure**

	Heated Oxygen Sensor Monitor Operation											
Component/ System	Fault Code s	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL				
Control module open/shorted Bank A	P1646	Control module hardware checks	Heater failure Sensor open circuit Sensor short circuit Module failure	Failed Failed Failed Failed	Sensor control	Executing Ignition on	8.0s 8.0s 8.0s 8.0s All 3.6s (2004 model year)	2 Drive Cycles				
Control module open/shorted Bank B	P1647		Sensor impedance	> 60 ohms	Sensor control active Disable:	>= 60s P0603	20s 20.5s (2008)	2 Drive Cycles				

# **6.4.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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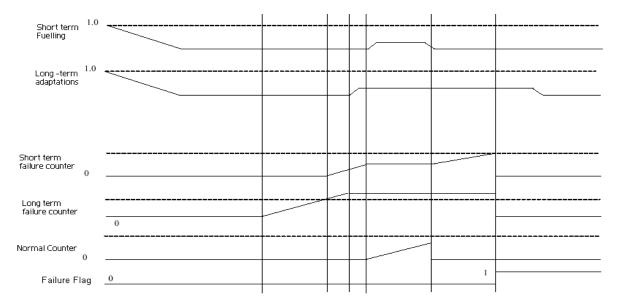


#### 6.5 Fuel System Monitor

The monitor operates continuously throughout the trip. The monitor timing is every 0.128 seconds. The monitor compares the long term adaptions for the current load site against a failure threshold. If the adaptions for that site are greater than the failure threshold, the long term failure counter is incremented. If this counter reaches a calibrated time, the monitor looks at the short term fuelling trim and compares this against another threshold. The short term failure counter is incremented and if this counter reaches its failure threshold then a failure is flagged.

The normal counter operates when both long term and short term fuelling is within the thresholds. If the normal counter reaches its calibrated time then both failure counters are reset.

The diagram below shows the flagging of a rich failure on Bank Aof an engine:



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# 6.5.1 Monitoring Structure

		Fue	System Monitor (V8	3) – Up to 200	04 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Bank A	P0171	Long term fuelling drift and short term feedback compensation			Engine Coolant Temperature Intake Air Temperature	> 75 °C > -30 °C	15s	2 Drive Cycles
Fuel too lean – Bank B	P0174	values outside limits	Total air fuel rate feedback compensation	> +19%	Closed loop fuelling Fuel level	Active > 11%		2 Drive Cycles
Fuel too rich – Bank A	P0172		Long term adaptions	< -17% and				2 Drive Cycles
Fuel too rich – Bank B	P0175		Total air fuel rate feedback compensation	< -16%				2 Drive Cycles
				6, P1338, P0102,	P0116, P0117, P0118, P0125, P P0103, P1104, P0101, P1642, P0 P0183, P1233, P1339			
			P0133, P0137, P0138, P014 P0038	0, P0351, P0353,	P0355, P0357 P0201, P0203, P0	205, P0207, P00	031, P0032, P	0037,
		Bank B	P0153, P0157, P0158, P016 P0058	0, P0352, P0354,	P0356, P0358, P0202, P0204, P0	0206, P0208, P0	051, P0052, F	P0057,

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		Fuel	System Monitor (V8	) – From 200	4 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel too lean –	P0171	Long term fuel trim and short	Long term fuel trim	>= +18% (XK8)	Fuel level	>= 11%	15s plus	2 Drive
Bank A		term fuel trim values outside		>= +19% (XJ)	Transient fuelling	<= 4 (+/-)		Cycles
Fuel too lean –	P0174	limits		>= +19% (XK8)	compensation		15s	
Bank B				>= +19% (XJ)				2 Drive
	D0470			470( ()(1(0)				Cycles
	P0172			>= -17% (XK8)			15s plus	2 Drive
Bank A	D0475			>= -20% (XJ)			15-	Cycles
Fuel too rich - Bank B	P0175			>= -16% (XK8) >= -25%(XJ)			15s	2 Drive
- Dalik D				>= -25%(\J)				Cycles
		Disable:	P0101, P0102, P0103, P010	ı 6. P0107. P0108.	P0111, P0112, P0113, P0	ı 116. P0117. P0118.	ı . P0125. P0128	. ,
			P0182, P0183, P0191, P019					
			P1313, P1314, P1316, P133	8, P1339, P1367,	P1368, P1609, P1642.		,	,
			P0133, P0137, P0138, P014 P0038	.0, P0351, P0353,	P0335, P0357 P0201, P02	03, P0205, P0207,	P0031, P0032,	P0037,
			P0153, P0157, P0158, P016 P0058	0, P0352, P0354,	P0356, P0358, P0202, P02	204, P0206, P0208	, P0051, P0052	, P0057,

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		Fuel	System Monitor (V6	6) – Up to 20	004 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel too lean – Bank A Fuel too lean – Bank B	P0171 P0174	Long term fuelling drift and short term feedback compensation values outside limits		> 25%	Engine Coolant Temperature Intake Air Temperature Closed loop fuelling Fuel level	> 75 °C > -30 °C Active > 11%	60s	2 Drive Cycles 2 Drive
Fuel too rich – Bank A Fuel too rich – Bank B	P0172 P0175		, ,	< 18% < 25%				Cycles 2 Drive Cycles 2 Drive Cycles
				6, P1338, P010	8, P0116, P0117, P0118, P0125, 2, P0103, P1104, P0101, P1642, 2, P0183, P1233, P1339			P0111,
			P0133, P0137, P0138, P014 P0038	0, P0351, P035	3, P0335, P0357 P0201, P0203, F	P0205, P0207, P0	031, P0032, F	P0037,
			P0153, P0157, P0158, P016 P0058	0, P0352, P035	4, P0356, P0358, P0202, P0204,	P0206, P0208, P0	0051, P0052,	P0057,

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		Fuel	System Monitor (	V6) – From 200	4 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Bank A Fuel too lean –		Long term fuel trim and short term fuel trim values outside limits	Long term fuel trim Short tem fuel trim	>= +18% (S-Type) >= +19% (X-Type) >= +25%	Fuel level Transient fuelling compensation	>= 11% <= 4 (+/-)	30s plus 30s	2 Drive Cycles 2 Drive
– Bank A	P0172		g	>= -18%			30s plus	Cycles 2 Drive Cycles
Fuel too rich – Bank B	P0175		Short tem fuel trim	>= -25%			30s	2 Drive Cvcles
				0192, P0193, P0441,	P0111, P0112, P0113, P0- P0443, P0444, P0445, P0- P1368, P1609, P1642.			3, P0181,
	Disable add	litions (X-Type 2005 model year):	P0069, P0627, P0628, P	0629, P2228, P2229,	P2632, P2633, P2634, P26	635, P2636.		
			P0133, P0137, P0138, P P0038	0140, P0351, P0353,	P0355, P0357 P0201, P02	03, P0205, P0207,	P0031, P0032	, P0037,
			P0153, P0157, P0158, P P0058	0160, P0352, P0354,	P0356, P0358, P0202, P02	204, P0206, P0208	, P0051, P0052	2, P0057,

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			Fuel System Moni	itor (V6) – 200	08 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel System		•						
Fuel too lean - Bank A	P0171	Long Term Fuel Trim outside limit for time	Long Term Fuel Trim	>= 118 %	Battery voltage	>= 10.0 V	60 s	2 Drive
Fuel too lean - Bank B	P0174	period & Short	<u>And</u>	(for 30 s)	Engine Start	Not in progress		Cycles
Fuel too rich - Bank A	P0172	Term Fuel Trim outside limit for additional	Short Term Fuel Trim	>= 125 %	Ignition turned on	For at least 2.0 s		
Fuel too rich - Bank B	P0175	time period		(for 30 s)	Transient fuelling compensation	< 4 %		
			<u>Or</u>		Fuel level	>= 11 %		
			Long Term Fuel Trim <u>And</u>	<= 82 % (for 30 s)	(for lean faults only)			
			Short Term Fuel Trim	<= 75 %				
				(for 30 s)	Fault Codes that disable	Boood Boood Boood Bo		D0004
					P0171 & P0172	P0306 P1313 P1314 P1 P0137 P0140 P2229 P2 P0117 P0116 P0125 P0 P1367 P1368 P0201 P0 P0032 P0444 P0445 P0 P0111 P0627 P2635 P0 P0103 P1104 P0101 P0 P1642 P0603 P0460 P1 P0192 P0191 P0181	316 P0133 2228 P0069 0351 P0353 0203 P0205 0443 P0112 0628 P0629 0054 P0038	P0138 P0118 P0355 P0031 P0113 P0102 P0037
						P0300 P0301 P0303 P0 P0306 P1313 P1314 P1 P0157 P0160 P2229 P2 P0117 P0116 P0125 P0 P1367 P1368 P0202 P0 P0052 P0444 P0445 P0 P0111 P0627 P2635 P0 P0103 P1104 P0101 P0 P1642 P0603 P0460 P1 P0192 P0191 P0181	316 P0153 2228 P0069 0352 P0354 0204 P0206 0443 P0112 0628 P0629 0060 P0058	P0158 P0118 P0356 P0051 P0113 P0102 P0057

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### 6.5.2 Fuel System Secondary Trim

On the X-Type from 2004 model year, a secondary monitor also checks the sub feedback trim levels. When the entry conditions are met, the sub feed back trim level is checked against a threshold. If it is either above or below a threshold, a counter is started, if at the end of the count the level is still above or below the threshold then an appropriate DTC is flagged.

# 6.5.3 Monitoring Structure

		Fuel System Mor	nitor - Secondary Fu	ıel Trim (X-1	Type From 2004 Model Ye	ar)		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Sub feedback too lean Bank A	P2096	Sub feedback outside limit	Sub feedback trim value	>= -3.49%	Mass Airflow Engine Coolant Temperature Fuel level	>= 20 g/s >= 60 °C >= 10%	5s	2DTC
Sub feedback too lean Bank B	P2098				Vapor concentration Sub feedback	< 30 % Executing	10 times	2DTC
Sub feedback too rich Bank A	P2097		Sub feedback trim value	>= 3.49%				
Sub feedback too rich Bank B	P2097							
				Disable:	P0101, P0102, P0103, P0106, P01 P0116, P0117, P0118, P0125, P01 P0192, P0193, P0441, P0443, P04 P1233, P1234, P1236, P1313, P13 P1368, P1609, P1642.	28, P0181, P01 44, P0445, P04	82, P0183, P0 60, P0603, P1	191, 104,
				Disable (2005 model year):	P0069, P0101,P0102, P0103, P0192, P0193, P0443, P0444, P04 P0629, P1104, P1367, P1368, P16 P2633, P2634, P2635, P2636.	45, P0460, P06	03, P0627, P0	628,
				Bank A	P0133, P0137, P0138, P0140, P03 P0203, P0205, P0207, P0031, P00			201,
				Bank B	P0153, P0157, P0158, P0160, P03 P0204, P0206, P0208, P0051, P00	, ,	, ,	202,

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		Fuel System M	lonitor - Secondary	Fuel Trin	n (X-Type 2008 Model Y	'ear)		
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
System  Fuel System - Secondary Trim Sub feedback too lean or too rich Bank A Bank B	P2A01	Sub feedback outside limit in at least one region of operation. (There are 6 regions, bounded by speed and engine load limits. The speed thresholds are up to 1500 rpm, from 1500 to 3000 rpm and above 3000 rpm. The load threshold is from 0 to 4.0 g/rev and above 4.0 g/rev)	Criteria  Sub feedback trim value Or	value >= +4 % <= -4 %	Sub feedback Sub feedback is active, if: Engine Coolant Temperature Engine Speed Time Afterstart Feedback fuelling control D/s HO2S signal  Fault Codes that disable P2A01  Fault Codes that disable	Active  >= 80 degC  <= 4000 rpm  >= see table below Active  P0132 P0131 P0133 P0 P0172 P0171 P2229 P2 P0117 P0116 P0125 P0 P1367 P1368 P0201 P0 P0032 P0444 P0445 P0 P0628 P0629 P0102 P0 P0054 P0038 P0037 P1 P0460 P1646 P0193 P0	228 P0069 F 351 P0353 F 203 P0205 F 443 P0627 F 103 P1104 F 638 P1642 F 192 P0191 F 158 P0157 F 228 P0069 F 352 P0354 F 204 P0206 F 443 P0627 F 103 P1104 F 638 P1642 F	P0118 P0355 P0031 P2635 P0101 P0603 P0139 P0160 P0118 P0356 P0051 P2635 P0101 P0603

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Time After Start Entry Condition – DTCs P2A01 and P2A04 – (X400 2008 Model Year)									
ECT Temperature (degC)	-30	-10	10	25	50	75			
Time (s)	98.304	49.152	32.768	24.576	16.384	8.192			

# 6.5.4 Drive Cycle Information

Drive cycle under review.

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#### 6.6 Evaporative Emissions System Monitor

The leak test monitor is designed to find any evaporative leak between 40 thou, (the EVAP reduces to 20 thou on V8 Sedan normally aspirated at 2001 model year) and a gross leak. The 40 thou test operates whilst the vehicle is moving and includes checks for canister closure valve stuck closed (restricted airflow on the fuel tank breather) and the EVAP canister purge valve stuck open (leaking). The EVAP canister closure valve stuck open and EVAP canister purge valve stuck closed is part of the gross leak judgment. The 20 thou leak test is an additional test, which is carried out at idle.

#### **DTCs**

P0442 40 thou (or larger) leak detected
P0443 EVAP canister purge valve malfunction EVAP canister purge valve circuit low electrical
P0444 EVAP canister purge valve circuit high electrical
P0445 EVAP canister closure valve malfunction restricted
P0446 EVAP canister closure valve open circuit electrical
P0447 EVAP canister closure valve short circuit electrical
P0448 EVAP canister closure valve short circuit electrical
P0450 Fuel Tank Pressure (FTP) sensor malfunction no change
P0451 FTP sensor low input electrical
P0452 FTP sensor high input electrical
P0455 gross leak

EVAP canister purge valve leaking electrical circuit check electrical circuit check restricted airflow through tank breather electrical circuit check electrical circuit check no change in output electrical circuit check electrical circuit check electrical circuit check

#### 6.6.1 Leak Test Operation

The leak test will be initialized when a number of entry conditions are satisfied. They will include Engine Coolant Temperature, Intake Air Temperature, engine load, vehicle speed, vapor concentration and purge amount.

#### 40 Thou Leak Test

P0456 20 thou leak

When the entry conditions are satisfied the EVAP canister purge valve will be closed and the EVAP canister closure valve will then close. The EVAP system is now sealed, the FTP sensor will take the initial value of pressure (P1). After 15 seconds the FTP sensor will take a further reading (P2). The difference between P1 and P2 becomes the first pressure rise.

The EVAP canister purge valve will then be ramped open to pull the FTP down to –2.00 kPa; the EVAP canister purge valve will then close. If the pressure rises too quickly then a second pull down will occur. The FTP sensor then takes a further reading of the tank pressure (P3). After a further 15 seconds a final pressure reading (P4) is taken. The difference between P3 and P4 becomes the second pressure rise.

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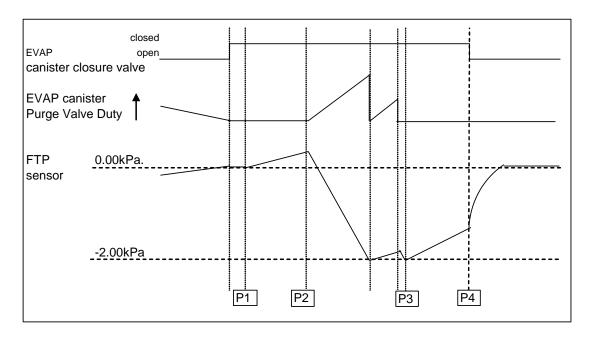


The EVAP canister closure valve is then opened and the leak value is calculated and compared with the pass/fail threshold. The result may be discarded if the vapor concentration is too high, the first pressure rise is too high or the fuel movement in the tank causes excessive vapor. If the pressure in the tank does not return close to atmospheric within a few seconds of the EVAP canister closure valve opening then the test will continue and may flag DTC P0446.

If the EVAP canister purge valve is ramped open and the tank is not pulled down to -2.00 kPa, a gross leak will be flagged. If however during the second pressure rise the tank pressure rises to a value, which would indicate that it couldn't be a gross leak.

Failure to pull the tank pressure down resulting in flagging P0455 can be due to a gross leak, vapor pipe detached / fuel cap left off etc. or the EVAP canister purge valve stuck closed or the EVAP canister closure valve stuck open.

#### Leak Test Diagram 40 Thou Test



#### 20 Thou Leak Test

The 20 thou leak test is similar to the diagram above, with the exception that the tank is pulled down to -1.25 kPa rather than -2.00 kPa as above. In addition the 20 thou test is carried out at idle or with the vehicle moving at less then 9 mph. Component faults P0443, P0446, P0450 & P0455 cannot be determined from the 20 thou test.

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# **6.6.2 Monitoring Structure**

		Evaporativ	e Emission Syste	m Monitor – U	Jp to 2004 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
EVAP canister	P0444	Hardware check	Commanded versus	Wrong	Battery voltage	> 6 volts	3.2s	2 Drive
purge valve low voltage			actual		EVAP canister purge valve duty cycle	< 0.102		Cycles
EVAP canister	P0445	Hardware check	Commanded versus	Wrong	Battery voltage	> 6 volts	3.2s	2 Drive
purge valve high voltage	1 0443	i laidware check	actual	vviolig	EVAP canister purge valve duty cycle		5.23	Cycles
EVAP canister	P0443	Incorporated in to P0455/P0442	Pressure change	-2 kPa			120s	2 Drive
purge valve malfunction			. recours onange		Disable:	P0603, P1609, P0441		Cycles
EVAP canister close valve open	P0447	Hardware check	Commanded versus actual	Wrong	Ignition on		1.28s	2 Drive Cycles
	P0448	Hardware check	Commanded versus actual	Wrong	Leak check active Disable:	P0603, P1609	1.28s	2 Drive Cycles
EVAP canister close valve malfunction	P0446	Incorporated in to P0455/P0442	Pressure change/time	< -0.4 kPa			150s approximately	2 Drive Cycles
FTP sensor malfunction	P0450	Incorporated in to P0455/P0442	Sensor activity	< -0.03 kPa			120s approximately	2 Drive Cycles
Gross leak detected	P0455	FTP during purge on, EVAP canister closure valve open and EVAP canister closure valve closed conditions	Pressure change over time	Time/pressure	Altitude change Vehicle speed Time after start	> 625 ft 6.25 to 81mph >765s	94s approximately	2 Drive Cycles
0.040" leak detected	P0442	FTP during purge on, EVAP canister closure valve open and EVAP canister closure valve closed conditions	Pressure change over time	See table TBDF_LEAK_FAL TLEVL_BASE	Purge accumulative	15 to 85% < 10,000 ft -8 to 100 °C < 3% 2.5 to 40 g/s 70 to 110 °C 700 > -200 kPa	70s approximately	2 Drive Cycles

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	Evaporative Emission System Monitor – Up to 2004 Model Year												
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL					
0.020" leak detected		FTP during purge on, EVAP	Pressure change over time	See table TBDF_LEAK_FAT LEVL_BASE20	Vehicle speed	< 9 mph > 1400s 30-85% < 10,000 ft -8 to 70 °C < 3% 1.5 to 15 g/s 70 to 110 °C 1100 > -1.25 kPa 9000s  Alternative entry conditions for 0.020" &0.040" > 1400s	55s	2 Drive Cycles					
					Engine speed Purge amount	> 70g/s for > 3.5s > 3500 RPM for	n						
					Disable:	> 3.5s > 450 P0101- P0103, P0111- P0113, P0128, P0201-	P1104, P0107, P0116- P0118,	P0125,					
						P0444, P0445, P0453, P0460, P1637, C1137, P1314, P1316, P1368, P1642,	P0447, P0448, P0603, P1609, C1165, C1175, P0106, P1637,	P0452, P1642,					

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		Evaporativ	e Emission System	Monitor –	From 2004 Model Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL
EVAP canister purge valve low voltage	P0444	Hardware check	Commanded v actual	Wrong	Battery voltage EVAP canister purge valve duty cycle	< 10 volts < 0.05	3.2s	2 Drive Cycles
	P0445	Hardware check	Commanded v actual		Battery voltage EVAP canister purge valve duty cycle	> 10 volts > 0.9 > 0.95 (2008)	3.2s	2 Drive Cycles
	P0443	Incorporated into P0455/P0442	Pressure change	<= -1 kPa	Disable:	P1609	120s approximat ely	2 Drive Cycles
	P0447	Hardware check	Commanded v actual	Wrong	Ignition on		1.3s	2 Drive Cycles
	P0448	Hardware check	Commanded v actual	Wrong	Leak check active Disable:	P0603, P1609	1.3s	2 Drive Cycles
EVAP canister close valve malfunction	P0446	Incorporated into P0455/P0442	Pressure change/time	<= -0. 2 kPa			150s approximat ely	2 Drive Cycles
FTP sensor malfunction	P0450	Incorporated into P0455/P0442	Sensor activity	< -0.03 kPa			120s approximat ely	2 Drive Cycles
Gross leak detected	P0455	FTP during purge on, EVAP canister closure valve open and EVAP canister closure valve closed conditions	Pressure change over time	Time/pressur e		>= 70 kPa (XK8 and S-type) >= 74.5 kPa (XJ and X-Type) 6 to 81mph >=766s	94s approximat ely	2 Drive Cycles
0.040" leak detected	P0442	FTP during purge on, EVAP canister closure valve open and EVAP canister closure valve closed conditions	Pressure change over time	See table EVAP1	Vehicle speed After start Fuel level Atmospheric pressure change Intake Air Temperature Fuel level change Airflow	15 to 85% <= 2 kPa -8 to 70°C < 3%	70s approximat ely	2 Drive Cycles
						2.5 to 40g/s 70 to 110°C		

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		Evaporativ	e Emission System	Monitor –	From 2004 Model Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL
					FTP drop	700 >= -2 kPa		
0.020" leak detected		FTP during purge on, EVAP canister closure valve open and EVAP canister closure valve closed conditions	Pressure change over time	See table EVAP 2	Vehicle speed After start Fuel level Atmospheric pressure	0 to 9 mph >= 1400s 30 to 85% >= 70 kPa (XK8 and S-type) >= 74.5 kPa (XJ and X-Type)	55s	2 Drive Cycles
					Intake Air Temperature Fuel level change	-8 to 50 °C -8 to 70 °C (Xk8) <= 3%		
					Airflow Engine Coolant Temperature Purge amount after start	1.5 to 15 g/s 70 to 110 °C >= 1000 (X-Type)		
					FTP Engine run time calculation	>= 1100 (all other) >= -1.25 kPa >= 5000s (X-Type) >= 9000s (S-Type) >= 10000s (XK8)		
					0.020" and 0.040" Idle	>= 10000\$ (XK8) >= 6000\$ (XJ N/A) >= 5000\$ (XJ S/C) > 1400\$		
					Airflow Engine speed Purge amount	> 70 g/s for > 3.5s > 3500 RPM for > 3.5s > 450	8	
			P0111, P0112, P0113, P011 P0202, P0203, P0204, P020	65, C1175, P0 6, P0117, P01 95, P0206, P02 88, P0452, P04	.031, P0032, P0051, P0052, P01 118, P0125, P0128, P0131, P01 207, P0208, P0351, P0352, P03 153, P0460, P0506, P0507, P06	01, P0102, P0103, P0 32, P0133, P0151, P01 53, P0354, P0355, P03	52, P0153, F 56, P0357, F	P0201, P0358,
			P0069, P2228, P2229.	,, i 1042, F10	, 1 10 <del>1</del> 7			

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	Evaporative Emission System Monitor – 2008 Model Year												
Component/ Fau System Code		Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL						
Fuel Evaporative Leak Monitoring													
Gross leak detected	Fuel tank pressure during purge on, CCV open and CCV closed conditions  If the refuelled flag set then the diagnostic will still run as stated but this P0457 DTC is set and "Check Cap" message displayed if a fault is detected	Pressure change over time	time / pressure	Atmospheric pressure Vehicle speed Afterstart  Refuelled Flag Fuel level Delta atmos. press. Intake Air Temperature Filtered Fuel Level Change Mass Airflow Engine Coolant Temperature Engine running time since ECT < 40 degC Accumulated purge amount  Fuel cut Atmospheric pressure - MAP  No of attempts to run monitor this drive cycle	> 74.5 kPa 6.2 <= V < 80.7 mph > 766 s  (Or Engine speed > 3500 rpm or MAF > 70 g/s for > 3.5 s) Not set 15 <= FL <= 85 % <= 2 kPa -8.125 <= IAT <= 70 degC <= 3 % during the test 1.5 <= MAF <= 50.0 g/s 70 <= ECT <= 110 degC <= 9000 s >= 700  (or >= 450, if Engine speed > 3500 rpm or MAF > 70 g/s for > 3.5 s) Not in progress >= 10 kPa (can be < 10 kPa for Up to 5.0 s) <= 20	50 s (approx)	2 Drive Cycles						

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		Evap	orative Emiss	sion Systen	n Monitor – 2008 Model	Year		
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel Evaporative Monitoring (continued	<u>d</u> )	Fuel tank pressure during	Pressure change	s – Toblo	Atmosphoria proggura	74.5 kDo	E9.0	2 Drive
0.040" leak detected	P0442	Fuel tank pressure during purge on, CCV open and CCV closed conditions  If the refuelled flag set then the diagnostic will still run as stated but this P0457 DTC is set and "Check Cap" message displayed if a fault is detected	Pressure change over time	>= Table EVAP1	Atmospheric pressure Vehicle speed Afterstart  Refuelled Flag Fuel level Delta atmos. press. Intake Air Temperature Mass Airflow Engine Coolant Temperature Engine running time since ECT < 40 degC Rough road Accumulated purge amount	> 74.5 kPa 6.2 <= V < 80.7 mph > 766 s (Or Engine speed > 3500 rpm or MAF > 70 g/s for > 3.5 s) Not set 15 <= FL <= 85 % <= 2 kPa -8.125 <= IAT <= 70 degC 1.5 <= MAF <= 50.0 g/s 70 <= ECT <= 110 degC <= 9000 s  Not detected >= 700 (or >= 450, if Engine speed > 3500	58 s (approx)	2 Drive Cycles
					Fuel cut Atmospheric pressure - MAP  Filtered Fuel Level Change Raw Fuel level change (slosh) Purge vapour concentration No of attempts to run monitor this drive cycle	rpm or MAF > 70 g/s for > 3.5 s) Not in progress >= 10 kPa (can be < 10 kPa for Up to 5.0 s) <= 3 % during the test <= Table EVAP3 <= 0.5 <= 20		

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		Evap	oorative Emiss	sion Syster	m Monitor – 2008 Model	Year		
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
Fuel Evaporative Monitoring (continued	Leak	Description	Ciliena	value	Falametei	Conditions	Required	
0.020" leak detected	P0456	Fuel tank pressure during purge on, CCV open and CCV closed conditions	Pressure change over time	>= Table EVAP2	Vehicle speed Afterstart Fuel level Atmospheric pressure Intake Air Temperature Filtered Fuel Level Change Raw Fuel level change (slosh) Mass Airflow Engine Coolant Temperature Accumulated purge amount Tank pressure drop Engine running time since ECT < 40 degC Fuel cut Tank pressure Refuelled Flag (if set, then gross or 40 thou test must complete first) First pressure rise No of attempts to run monitor this drive cycle Gross Leak Test status	0 <= V < 2.0 mph	66 s (approx)	2 Drive Cycles

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			T	BDF_LEAK_	FALTLEVL	<b>BASE - 3.0</b>	L			
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.55	0.55	0.563	0.599	0.63	0.672	0.727	0.776	0.801	0.825
			TE	BDF LEAK I	FALTLEVLE	3ASE20 - 3.	0L			
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.25	0.25	0.251	0.251	0.25	0.251	0.251	0.27	0.288	0.318
			T	BDF LEAK	FAI TI FVI	BASE - 42	1			
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.501	0.501	0.563	0.605	0.648	0.727	0.813	0.886	0.929	0.971
			Tr	DE LEAK I		A O F 00 4	01			
Fuel level %	19	30	40	BDF_LEAK_I 45	50	5 <b>ASE2U - 4.</b> 55	<b>2L</b> 60	70	80	91
Threshold level (kPa)	0.233	0.233	0.239	0.239	0.245	0.251	0.257	0.263	0.300	0.300
							2/2	•		
<b>5</b> 11 10/				DF_LEAK_F				1 00	T 0-	
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.630	0.630	0.630	0.630	0.660	0.697	0.752	0.819	0.949	0.898
			TBD	F LEAK FA	LTLEVLBA	SE20 – 4.2L	S/C			
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.331	0.331	0.331	0.337	0.343	0.343	0.343	0.349	0.361	0.361
			F\	VAP1 – V6 (	X-Tyne 2004	1 Model Yes	ar)			
Fuel level %	1	9 3		0 45	50	55	60	70	80	91
Threshold level	I (kPa) 0.	20 0.	20 0.	21 0.24	0.26	0.27	0.28	0.31	0.33	0.34

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			EVA	P1 (X-Type	2005 Mod	el Year)				
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.19	0.19	0.19	0.19	0.19	0.19	0.19	0.21	0.24	0.28
					~ .	lodel Year)		1		1
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.27	0.29	0.32
			EVAD	4 42L ( V	(J 2004 Mo	dal Vaar\				
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.25	0.25	0.27	0.28	0.29	0.29	0.30	0.33	0.39	0.45
			_							
			EVAP1	– 4.2L ( X	K8 2004 Mc	odel Year)				
Fuel level %	19	30	40	45	50	55	60	70	80	91
Threshold level (kPa)	0.20	0.20	0.20	0.20	0.20	0.21	0.22	0.24	0.26	0.26
			EVAF	P1 – (X Tvp	e 2008 Mod	del Year)				
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.093	0.093	0.093	0.099	0.111	0.123	0.123	0.123	0.141	0.160
			E\/4 D0	\\0 / \\ <b>T</b>	0004.14	1117				
E .1110/		4.5			/pe 2004 M		70		1 05	
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.90	0.90	0.90	0.98	1.05	1.13	1.20	1.28	1.31	1.36
			EVA	P2 ( X-Tvpe	2005 Mod	el Year)				
Fuel level %	9	15	30	40	50	60	70	80	85	91
Threshold level (kPa)	0.75	0.75	0.75	0.75	0.78	0.83	0.87	0.92	0.95	0.98
` '					<u> </u>	<u> </u>		<u> </u>		<u> </u>

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	EVAP2 – 3.0L (S-Type 2004 Model Year)												
Fuel level %	9	15	30	40	50	60	70	80	85	91			
Threshold level (kPa)	0.55	0.55	0.56	0.60	0.63	0.67	0.73	0.78	0.80	0.82			

	EVAP2 – 4.2L (XK8 2004 Model Year)													
Fuel level %	10	20	30	40	50	55	60	70	80	91				
Threshold level (kPa)	0.58	0.58	0.60	0.60	0.67	0.70	0.74	0.78	0.90	1.04				

	EVAP2 – 4.2L (XJ 2004 Model Year)													
Fuel level %	9	15	30	40	50	60	70	80	85	91				
Threshold level (kPa)	0.50	0.50	0.52	0.61	0.68	0.78	0.91	1.05	1.10	1.11				

	EVAP2 – (X Type 2008 Model Year)													
Fuel level %	Fuel level % 9 15 30 40 50 60 70 80 85 91													
Threshold level (kPa)	0.520	0.520	0.520	0.648	0.703	0.703	0.703	0.703	0.703	0.703				

EVAP3 – (X Type 2008 Model Year)											
Fuel Level (%)	15	20	30	45	55	70	80	85			
Fuel Slosh Threshold	40	40	18	15	15	14	11	10			

EVAP4 – (X Type 2008 Model Year)												
Fuel Level (%)	10	20	30	40	50	60	80	90				
Fuel Slosh Threshold	30	20	12	7	7	9	13	15				

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# **6.6.3 Drive Cycle Information**Evaporative emission system leak & DMTL module faults

Drive cycle under review.

**EVAP Canister Purge valve & Purge flow faults** 

Drive cycle under review.

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### 6.7 Fuel Tank Pressure Sensor Circuit

# 6.7.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software.

If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.7.2 Range/Performance Failure

This monitor is covered in the EVAP loss recovery system monitor section.

# 6.7.3 Monitoring Structure

	Fuel Tank Pressure Sensor Monitor											
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL				
FTP sensor low input	P0452	Out of range check	Sensor voltage	<= 0.10 volts	Ignition on		5s 1.3s (2004 MY) 5s (2008 MY)	2 Drive Cycles				
FTP sensor high input	P0453	Out of range check	Sensor voltage	>= 4.95 volts >= 4.9 volts (2004 model year)	Ignition on		5s 1.3s (2004 MY) 5s (2008 MY)	2 Drive Cycles				
					Disable:	P0603, P1241, P124 P0562, P0563	I 2, P1243, P1642, P16	1 609,				
FTP sensor malfunction	P0450	Incorporated in to P0455/P0442	Sensor activity	<= 0.03 kPa		See EVAP system		2 Drive Cycles				

# 6.7.4 Drive Cycle Information

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.8 Exhaust Gas Recirculation System Monitor (V8 Engines)

### 6.8.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software.

If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored.

If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.8.2 Exhaust Gas Recirculation Valve Range/Performance Failure

The method employed to check the EGR valve operation involves forcing the valve open and closed during an over run fuel cut off. A reading from the Manifold Absolute Pressure sensor is checked before, during and after the valve operation. The difference in values between the open and closed states of the valve is checked against a map of engine speed versus the difference value. If this calculated value is below or over the threshold, a failure is judged.

## 6.8.3 Monitoring Structure

	Exhaust Gas Recirculation System Monitor												
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL					
System	Codes	Description	Criteria	value	Parameter	Conditions	Required						
Flow	P0400	Rationality flow check versus	Inlet manifold pressure	See table EGR1	Atmospheric pressure	67 kPa	2.4s	2 Drive					
malfunction		engine speed and atmospheric			Engine speed	1200 to 2500 RPM		Cycles					
		pressure			Airflow	0.25 to 13 g/s							
					Ambient temperature	-30 to 100 °C							
						-11.3 to 100 °C S/C							
					Engine load	0.1 to 0.4 g/rev							
						0.1 to 0.46g/rev S/C							
					Change in throttle position	< 12.5 deg/s							
						<= 50 deg/s (04MY)							
					Throttle Position	<= 4.5 deg							
					Engine Coolant Temperature	75 to 110 °C							
					Catalyst monitor	Not executing							
					EVAP leak check	Not executing							
					EGR system	Not executing							
					Over run fuel cut off	Invoked.							

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	Exhaust Gas Recirculation System Monitor												
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL					
System	Codes	Description	Criteria	value	Parameter	Conditions	Required						
				Disable:	P0101-P0103, P0111-P0113,	P0131-P0133, P015	51-P0153, P1313	, P1314,					
					P1316, P0171, P0172, P0174,	P0175, P0106 -P0	108, P0116- P01 <i>1</i>	18,					
					P0125, P1367, P1368, P0351-	,	, ,	,					
					P0051, P0052, P0443-P0445,								
					P0603, P1609, P0441, P1224,	P1224, P1229, P0	128, C1165, C117	75,					
					C1137, C1145, C1155								
EGR valve	P0405	Out of range check	Control signals voltages	Low level (I/O)		Ignition on 0		2 Drive					
circuit low input								Cycles					
	P0406		Control signals voltages	High level (I/O)									
circuit high input													
					Disable:	P1642, P0603, P16	609						

EGR1											
Atmospheric pressure (kPa)		Engine speed (RPM)									
pressure (kPa)	1500	1500 1700 1900 2100 2300 2500									
68	4.6	4.6	4.4	4	3.6	3.5					
76	5.2	4.8	4.6	4	4	3.6					
95	7	6.5	6.3	6	5.3	5					
101	7	6.5	6.3	6	5.3	5					

**6.8.4 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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### 6.9 Crankshaft/Camshaft Position Sensor

## 6.9.1 Open and Short Circuit Detection of the Crank Signal

Checks are performed to see if normal crank edge signals are detected during cranking.

### 6.9.2 Intermittent Crank Failure Detection

The number of crank teeth is checked every 360° of crank angle (1revolution).

## 6.9.3 Crank Request Signal High Input Monitor

If the crank request input is high when then the engine is running and the vehicle is moving, a high failure is flagged.

# 6.9.4 Open/Short Circuit

For open and short circuit detection, the monitor looks for:

- No CMP edge signal is input during cranking.
- No CMP edge signal is input during normal running.

# 6.9.5 Missing Phase Detection

For missing phase detection, the cylinder identification flag does not turn on or off every 360°.

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# 6.9.6 Monitoring Structure

		Crar	kshaft Position S	ensors Monitor	ing Operation			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
CKP sensor malfunction	P0335	1). Crank sensor signal when engine cranking	Time to crank pulse	No pulse	Cranking Battery voltage Engine speed (RPM)	Operation 6.5 to 16.0 volts >= 600 (V8) >= 650 (V6)	2.0s	2 Drive Cycles
		2). Crank sensor during engine running	Time to crank pulse	No pulse	Engine speed (RPM)	>= 1000 >= 650 (X-Type)	0.1s	2 Drive Cycles
CKP sensor range/ performance	P0336	Crank sensor pulses judged between missing teeth	Number of pulses	Incorrect number of pulses		>= 600 (V8) >= 650 (V6) < 0.077s (2008MY) P1245, P1246, P1609, P0341, P0512	1 revolution P0616, P061	2 Drive Cycles 7, P0340,
Crank request low input		Starter relay on while crank request off	Crank request signal Starter relay	Off On			0.512s	2 Drive Cycles
Crank request high input		Crank request active while vehicle moving	Crank request signal	On	Vehicle speed (mph) Engine speed (RPM)	>= 12 (X-Type) >= 9 (all others) 1200 to 3000 (X-Type) 1500 to 4000 (all others)	5 times	2 Drive Cycles
				Disable:	Engine load P0335, P0336, P0102, F P0616, P0617, P1516, F C1145, C1155, P0851			

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			Camshaft Po	sition Senso	ors					
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	IVIIL		
CMP sensor Bank A malfunction CMP sensor Bank B malfunction	P0340 P1340 P0345 (2004 model year)	CMP sensor at engine start		No pulse	Cranking Battery voltage  Crank signal pulse detected	Operation >= 8.5 volts (X- Type) >= 6.5 volts (all others) >= 24 times		2 Drive Cycles		
manunction		CMP sensor during engine running	Time to CMP pulse	No pulse	Engine speed (RPM)  Battery voltage Engine speed (RPM)	>= 600 (V8) >= 650 (V6) >= 10.5 volts >= 600 (V8)	5s	2 Drive Cycles		
CMP sensor	P0341	Detection of CMP sensor pulse between crank	Pulse not detected	No pulse	30 deg crank angle time Engine speed (RPM)	>= 650 (V6) < 0.077s (2008MY) >= 600 (V8)	2 revolutions			
Bank A range/ performance		missing teeth			Missing camshaft position signal	>= 650 (V6) >= 2 times (X-Type) >= 3 times (all others)		Cycles		
					Delay – reverse gear selected/deselected	>= 5s				
CMP sensor Bank B range/	P1341 P0346 (2004				30 deg crank angle time	< 0.077s (2008MY)	I	2 Drive Cycles		
performance	model year)			Disable:	P0335, P0336, P0512, P0605, P0606, P0610, P0616, P0617, P0641, P0651, P0666, P0701, P0702, P0705, P0706, P0709, P0710, P0711, P0715, P0720, P0725, P0729, P0730, P0731, P0732, P0733, P0734, P0735, P0740, P0741, P0743, P0750, P0753, P0755, P0758, P0760, P0763, P0765, P0768, P0770, P0773, , P0780, P0781, P0782, P0783, P0784, P0787, P0788, P0815, P0829, P1245, P1246, P1572, P1603, P1605, P1609, P1642, P1643, P1719, P1774, P1796, P1797, P1783, P1798, P1799					

**6.9.7 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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#### 6.10 Mass Airflow Sensor and Manifold Absolute Pressure Sensor

The Mass Airflow sensor contains a hot wire resistance element that forms part of a Wheatstone bridge. Air flowing around the hot-wire cools it, so altering the value of its resistance. The consequent change in the voltage dropped across the resistance is compared with the voltage dropped by the other resistance arms of the Wheatstone bridge to determine the airflow. The Mass Airflow sensor is continually monitored by OBD routines. A DTC is recorded if the input signal from the sensor to the ECM is outside pre-defined thresholds at the high or low end of the scale.

# 6.10.1 High/Low Input Failure and Ground Monitor

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored. For Mass Airflow sensor ground open monitoring, the voltage on the ground pin of the Mass Airflow sensor is monitored in the same way as described above.

# 6.10.2 Range/Performance Failure

The monitor operates continuously whilst the entry conditions are met. Every 0.128 seconds the airflow sensor monitor compares the actual airflow with an estimated airflow, which is calculated by a model. Similarly, every 0.032 seconds the Manifold Absolute Pressure sensor monitor compares the actual Manifold Absolute Pressure with an estimated pressure, which is calculated by a model. The models to calculate the estimated airflow and pressure have look-up tables that use engine speed, throttle angle and atmospheric pressure to derive base values and compensation values by which the estimated airflow and pressure are calculated.

Whether the Mass Airflow sensor and the Manifold Absolute Pressure sensor are behaving normally is determined if the difference between the actual and estimate values are below a calibrated threshold for more than 5 seconds. Whether the Mass Airflow sensor and the Manifold Absolute Pressure sensor are behaving abnormally, as failed components, is determined if the difference between the actual and estimated values is greater than a calibrated threshold for fifteen seconds continuously. The monitors have the ability to make a normal judgments followed by failed judgments or vice versa as the monitors run continuously whilst the entry conditions are met.

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# **6.10.3 Monitoring Structure**

			Ма	ss Airflow Sens	sor			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
MAF high voltage	P0103	Out of range check	MAF voltage	> 4.9 volts		Ignition on	0.5s	2 Drive Cycles
MAF Low voltage	P0102	Out of range check	MAF voltage	< 0.2 volts		Ignition on	0.5s	2 Drive Cycles
MAF ground open	P1104	Out of range check	MAF ground voltage	> 1.0 volts		Ignition on	0.5s	2 Drive Cycles
MAF range/ performance	P0101	Rationality v Throttle Position and engine speed	Airflow actual versus estimated	See table MAF1 and MAF2 (X-Type) >= 20 g/s (S-type) >= 25 g/.s (XJ) >= 20 g/s (XK8)	Engine speed (RPM):  Engine Coolant Temperature:	1050 to 5100 (X-Type) 1500 to 2500 (S-Type) 1000 to 2000 (XJ an XK8)) 60 to 119 °C	15s	2 Drive Cycles
				20 9/0 ((0)		(X-Type) 70 to 110 °C (all others)		
					Intake Air Temperature: Atmospheric Pressure: Throttle Position:	-30 to 100 °C >= 68 kPa 6 to 45 deg (X-Type) 7 to 30 deg (S-Type) 7 to 20 deg (XJ an XK8)		
					Fuel level: TP change:	>=10% <= 45 deg/s (X-Type) <= 44 deg/s (S-Type and XK8) <= 25 deg/s (XJ)		
			Disable:	P0341, P1340, P134 P1367, P1368, P020 P0113, P1241, P124 P1243, P0603, P164	6, P0131-P0133, P0151-P0153 1, P0335, P0336, P0106-P0108 1- P0208, P0031, P0032, P005 2, P0101- P0103, P1104, P001 6, P1647, P1107, P1108, P012 1, P1611, P1633, C1165, C117	, P0171, P0172, P0174, 3, P0125, P0116- P0118 1, P0052, P0444, P0445 0, P0020, P1384, P1396 8, P1224, P1229, P0121	, P0351-P035 5, P0443, P01 6, P1642, P16 -P0123, P022	88, 11- 37, 23,

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	Mass Airflow Sensor – MAF1 (2.5L) MAF Upper Limit												
Throttle		Engine speed (RPM)											
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090				
6	15.6	16.2	16.9	16.9	16.9	16.9	16.9	16.9	16.9				
10	21.3	24.4	26.9	28.7	29.4	28.1	28.4	27.8	28.1				
15	23.7	32.5	38.8	42.5	47.5	48.7	50.0	50.0	50.6				
20	27.5	35.0	45.0	53.7	65.0	70.0	73.7	76.9	79.7				
25	27.5	37.5	48.1	60.0	72.5	81.3	88.8	95.3	101.3				
30	27.5	38.1	50.0	65.0	78.1	90.0	100.0	109.4	118.8				
35	27.5	39.4	50.6	67.5	85.0	96.3	108.1	120.0	131.6				
40	27.5	39.4	51.3	68.8	85.6	99.4	112.5	126.3	140.6				
45	27.5	39.4	51.3	68.8	85.6	99.4	115.6	128.4	145.6				

	Mass Airflow Sensor – MAF2 (2.5L) MAF Lower Limit												
Throttle		Engine speed (RPM)											
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090				
6	5.2	5.6	6.4	6.4	6.4	6.4	6.4	6.4	6.4				
10	9.7	11.6	12.4	13.5	13.9	13.1	13.3	12.9	13.1				
15	11.2	15.7	19.5	21.8	22.5	23.2	24.0	24.0	24.4				
20	12.0	17.2	22.5	26.3	30.7	33.8	36.0	37.9	39.6				
25	12.0	18.0	23.6	29.2	35.2	40.5	45.0	48.9	52.5				
30	12.0	17.6	24.7	30.7	37.1	44.3	50.3	55.9	61.5				
35	12.0	18.4	25.1	31.5	39.8	46.5	53.6	60.7	67.7				
40	12.0	18.4	25.5	32.3	40.1	48.4	56.3	64.5	73.1				
45	12.0	18.4	25.5	32.3	40.1	48.4	58.1	65.8	76.1				

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	Mass Airflow Sensor – MAF1 (3.0L) MAF Upper Limit												
Throttle		Engine speed (RPM)											
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090				
6	16.2	16.9	17.5	17.5	17.5	17.5	17.5	17.5	17.5				
10	23.7	26.3	27.5	28.7	28.7	28.7	28.7	28.7	28.7				
15	27.5	35.6	41.2	44.4	48.7	50.0	51.3	51.3	51.3				
20	30.0	40.0	50.0	58.8	67.5	71.3	73.7	76.3	78.7				
25	31.3	43.8	55.0	67.5	80.0	86.2	93.8	100.0	105.0				
30	31.3	45.0	57.5	72.5	88.8	98.7	108.8	118.0	127.5				
35	31.3	45.6	60.0	76.3	93.1	106.3	118.8	133.8	145.0				
40	31.3	46.3	60.0	78.7	96.3	111.2	126.3	143.8	158.8				
45	31.3	46.3	60.6	79.4	98.7	115.0	132.5	150.0	166.2				

Mass Airflow Sensor – MAF2 (3.0L) MAF Lower Limit											
Throttle				Eı	ngine speed (RPI	M)					
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090		
6	6.0	6.4	6.8	6.8	6.8	6.8	6.8	6.8	6.8		
10	10.5	12.8	13.5	13.5	13.5	13.5	13.5	13.5	13.5		
15	12.8	18.0	21.4	24.7	24.7	25.5	25.5	25.5	25.5		
20	14.3	21.0	26.3	31.5	36.0	39.0	41.2	42.0	42.7		
25	15.0	21.8	27.8	34.5	42.0	47.2	51.0	55.5	59.3		
30	15.0	22.5	29.2	36.7	45.0	52.5	58.5	65.3	71.3		
35	15.0	22.5	30.0	38.3	47.2	55.5	63.8	72.7	80.2		
40	15.0	22.5	30.7	39.8	49.5	57.8	66.7	78.7	88.5		
45	15.0	23.2	30.7	39.8	49.5	59.3	69.0	81.8	92.2		

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	Mass Airflow Sensor – MAF1 (2008MY) MAF Upper Limit												
Throttle				Er	ngine speed (RP	M)							
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090				
6	16.25	16.88	17.50	17.50	17.50	17.50	17.50	17.50	17.50				
10	23.75	26.25	27.50	28.75	28.75	28.75	28.75	28.75	28.75				
15	27.50	35.63	41.25	44.37	48.75	50.00	51.25	51.25	51.25				
20	30.00	40.00	50.00	58.75	67.50	71.25	73.75	76.25	78.75				
25	31.25	43.75	55.00	67.50	80.00	86.25	93.75	100.00	105.00				
30	31.25	45.00	57.50	72.50	88.75	98.75	108.75	118.75	127.50				
35	31.25	45.62	60.00	76.25	93.13	106.25	118.75	133.75	145.00				
40	31.25	46.25	60.00	78.75	96.25	111.25	126.25	143.75	158.75				
45	31.25	46.25	60.63	79.38	98.75	115.00	132.50	150.00	166.25				

	Mass Airflow Sensor – MAF2 (2008MY) MAF Lower Limit											
Throttle		Engine speed (RPM)										
Angle (deg)	1050	1540	2025	2550	3040	3560	4040	4570	5090			
6	6.00	6.37	6.75	6.75	6.75	6.75	6.75	6.75	6.75			
10	10.50	12.75	13.50	13.50	13.50	13.50	13.50	13.50	13.50			
15	12.75	18.00	21.37	24.75	24.75	25.50	25.50	25.50	25.50			
20	14.25	21.00	26.25	31.50	36.00	39.00	41.25	42.00	42.75			
25	15.00	21.75	27.75	34.50	42.00	47.25	51.00	55.50	59.25			
30	15.00	22.50	29.25	36.75	45.00	52.50	58.50	65.25	71.25			
35	15.00	22.50	30.00	38.25	47.25	55.50	63.75	72.75	80.25			
40	15.00	22.50	30.75	39.75	49.50	57.75	66.75	78.75	88.50			
45	15.00	23.25	30.75	39.75	49.50	59.25	69.00	81.75	92.25			

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			Manifold A	bsolute Pressu	ire Sensor			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
MAP high	P1108	Out of range check	MAP voltage	> 4.9 volts		Ignition on	0.5s	2 Drive Cycles
MAP low	P1107	Out of range check	MAP voltage	< 0.1 volts		Ignition on	0.5s	2 Drive Cycles
MAP malfunction	P0105	1	Pressure actual versus estimated	See tables MAP1 and MAP2 (X-Type) >= 20 kPa (all others))	Engine speed (RPM):	1050 to 4550 (X- Type) 1500 to 2500 (S- Type) 1000 to 2000 (XJ and XK8)	15s	2 Drive Cycles
					Engine Coolant Temperature:	70 to 110 °C 60 to 119 °C (X- Type)		
					Intake Air Temperature:	-30 to 100°C		
					Atmospheric pressure:	>= 68 kPa		
					Throttle Position:	7 to 20 deg 6 to 40 deg (X-Type)		
					Fuel level:	>= 10%		
					TP change:	<= 44 deg/s		
					Variable camshaft timing advance	<= 160 deg (X-Type		
						only)		
					and a sum of the sum o	<= 100% (X-Type		
					Manifold Absolute Pressure	only)		
						> 0 kPa (X-Type		
			D: 11	Diala Bioli Biol	•	only)	D0475 D00	
			Disable:		6, P0131- P0133, P0151- P0153,		, P0175, P03	40,
					.1, P0335, P0336, P0106- P0108, 51-P0358, P1367, P1368, P0201-		D0051 D004	52
				•	.3, P0111- P0113, P1241, P1242,			•
					2, P1637, P1243 P0603, P1646,			
					2, P0223, P0222, P0121, P1251,			
				C1137,C1145, C115	5, P2118, P2119, P2135, P2228,	P2229		

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			Manifold Absolute F	Pressure	Sensor (2008MY)			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
MAP high input MAP low input	P0108	Out of range check Out of range check	MAP voltage (>= 200 kPa) MAP voltage (<= 10 kPa)	>= 4.86 V <= 0.12 V	r didificiei	Ignition on	0.5 s	2 Drive Cycles
MAP range / performance		estimate based on TP & RPM with compensation for altitude and temperature.	Measured MAP deviation from estimate: Estimate - Measured Or Measured - Estimate Where: MapDiff = MaxDiff * 30 kPa  See table for setting of MaxDiff	·	Engine Speed Engine Coolant Temperature Intake Air Temperature Atmospheric pressure Throttle Position Fuel level TP change  VVT advance Purge valve duty Manifold Absolute Pressure Vehicle speed  Fault Codes that disable MAF Monitoring	1050 < N < 4550 rpm 60 < T < 119 degC -30 < IAT < 100 degC >= 68 kPa 6 < TP < 40 degrees >= 10 % <= 1.4 deg/0.032 s for at least 1.024 s <= 160 degCA <= 99.6 % >= 0 kPa 0 <= V <= 420 mph  P0300 P0301 P0303 P030 P0306 P1313 P1314 P131 P0133 P0152 P0151 P015 P0175 P0174 P0340 P034 P0335 P0336 P2229 P222 P0116 P0125 P0351 P035 P0354 P0356 P1367 P136 P0203 P0204 P0205 P020 P0051 P0052 P0444 P044 P0113 P0111 P0562 P056 P1104 P0101 P0010 P138 P0020 P1396 P0021 P002 P1642 P1243 P0603 P046 P0107 P0108 P0128 C003 P2119 P2118 P0122 P012 P2135 P1251 P1631 P060	6 P0132 P0 3 P0172 P0 1 P0345 P0 2 P0118 P0 3 P0355 P0 6 P0201 P0 6 P0031 P0 5 P0443 P0 6 P0011 P0 1 P0163 P1 6 P1646 P1 7 C003A P0 2 P0222 P0	131 171 346 117 352 202 032 112 103 012 638 647 0501

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	Manifold Absolute Pressure Sensor – MAP1 (2.5L) MAP Estimate											
Throttle Angle		Engine speed (RPM)										
(deg)	1050	1540	2025	2550	3040	3560	4040	4570				
6	55.0	47.5	40.0	33.0	23.5	22.2	19.8	18.8				
10	73.0	66.0	59.5	48.5	40.5	35.5	30.3	25.5				
15	92.0	86.0	78.0	70.5	60.0	51.0	47.0	41.5				
20	97.0	94.0	90.0	84.0	76.2	71.3	65.5	59.5				
25	98.0	97.0	94.0	90.2	85.7	82.0	77.0	72.5				
30	99.0	98.0	96.7	94.3	91.5	88.0	85.0	81.5				
35	99.5	98.5	98.0	96.3	94.5	92.8	90.0	87.8				
40	99.5	99.0	99.0	97.5	96.5	95.3	93.2	91.5				

	Manifold Absolute Pressure Sensor – MAP1 (3.0L) MAP Estimate											
Throttle Angle		Engine speed (RPM)										
(deg)	1050	1540	2025	2550	3040	3560	4040	4570				
6	55.0	42.0	35.0	24.0	19.5	18.0	17.0	14.5				
10	72.0	61.0	50.0	40.0	32.0	31.0	26.5	20.0				
15	90.5	82.5	72.5	62.0	50.0	48.0	41.0	34.5				
20	95.0	90.5	85.5	78.5	68.0	65.0	58.5	51.0				
25	97.0	94.5	91.5	87.5	79.5	76.5	70.5	64.0				
30	98.0	96.5	94.5	92.0	87.0	84.5	79.5	75.0				
35	98.5	97.5	96.5	94.5	91.5	89.5	86.5	83.0				
40	98.5	98.0	97.5	96.5	94.0	92.5	90.0	88.5				

	Manifold Absolute Pressure Sensor – MAP2 (2.5Land 3.0L) MAP Limit										
Engine speed (RPM)	1050	1540	2025	2550	3040	3560	4040	4570			
Maximum difference (kPa)	39	36	33	30	27	24	21	18			

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	M	anifold Absolu	ite Pressure S	ensor – MAP1	(2008MY) Esti	mate value (kf	Pa)					
Throttle Angle		Engine speed (RPM)										
(deg)	1050	1540	2025	2550	3040	3560	4040	4570				
6	55.0	42.0	35.0	24.0	19.5	18.0	17.0	14.5				
10	72.0	61.0	50.0	40.0	32.0	31.0	26.5	20.0				
15	90.5	82.5	72.5	62.0	50.0	48.0	41.0	34.5				
20	95.0	90.5	85.5	78.5	68.0	65.0	58.5	51.0				
25	97.0	94.5	91.5	87.5	79.5	76.5	70.5	64.0				
30	98.0	96.5	94.5	92.0	87.0	84.5	79.5	75.0				
35	98.5	97.5	96.5	94.5	91.5	89.5	86.5	83.0				
40	98.5	98.0	97.5	96.5	94.0	92.5	90.0	88.5				

	Manifold Absolute Pressure Sensor – MAP2 (2008MY) Fault limit (MaxDiff)												
Camshaft		Engine speed (RPM)											
Advance	1050	1540	2025	2550	3040	3560	4040	4570					
Angle (deg)													
0.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
4.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
8.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
12.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
16.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
20.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
24.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					
30.0	1.3	1.2	1.1	1.0	0.9	0.8	0.7	0.6					

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	Manifold Absolute Pressure Sensor – MAP3 (2008MY) Altitude correction (AltitudeDifComp)											
Throttle Angle		Engine speed (RPM)										
(deg)	1050	1540	2025	2550	3040	3560	4040	4570				
6	55.0	42.0	35.0	24.0	19.5	18.0	17.0	14.5				
10	72.0	61.0	50.0	40.0	32.0	31.0	26.5	20.0				
15	90.5	82.5	72.5	62.0	50.0	48.0	41.0	34.5				
20	95.0	90.5	85.5	78.5	68.0	65.0	58.5	51.0				
25	97.0	94.5	91.5	87.5	79.5	76.5	70.5	64.0				
30	98.0	96.5	94.5	92.0	87.0	84.5	79.5	75.0				
35	98.5	97.5	96.5	94.5	91.5	89.5	86.5	83.0				
40	98.5	98.0	97.5	96.5	94.0	92.5	90.0	88.5				

Manifold Absolute Pressure Sensor – MAP4 (2008MY) Atmospheric pressure correction (AtmoPComp)										
Atmospheric Pressure (kPa)	60	70	80	90	100					
Correction Factor	1.203	0.898	0.602	0.297	0.000					

Manifold Abso	lute Pr	essure	Sensor	r – MAF	25 (2008	BMY) In	let air te	empera	ture co	rrectio	n (InAir	TComp	)	
Inlet Air Temperature (deg C)	-30	-20	-10	0	10	20	30	40	50	60	70	80	90	100
Correction Factor	1	1	1	1	1	1	1	1	1	1	1	1	1	1

**6.10.4 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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#### 6.11 Barometric Pressure Sensor

The barometric pressure (BARO) sensor (also referred to as the high altitude compensation sensor) is located within the ECM.

# 6.11.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.11.2 Range/Performance Failure

The signal from the sensor is compared to the signal from the Manifold Absolute Pressure sensor at ignition on only. During this time the pressure within the inlet manifold should be at atmospheric, and therefore should match the value from the barometric pressure sensor.

The following conditions must be met first before the monitor can execute:

- Engine speed = 0
- Vehicle speed = 0
- Monitor is not inhibited
- Ignition is on
- Engine is not cranking
- Battery voltage exceeds the minimum threshold
- Engine Coolant Temperature above minimum threshold
- Atmospheric pressure within limits
- Inlet manifold pressure value has settled

If the absolute value of the difference between the signal from the barometric pressure sensor and the Manifold Absolute Pressure sensor differ by more than a defined amount, then a timer is executed. If the timer exceeds a calibrated amount, a temperature failure is judged. Providing there is no failure of the Manifold Absolute Pressure sensor, a DTC is then stored.

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# **6.11.3 Monitoring Structure**

			i i ooodai o c	Sensor			
Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
P0107 8 (X-Type 2005 nodel year)	Out of range check	Sensor voltage	<= 0.1 volts		Ignition on	0.5s	2 Drive Cycles
P0108 9 (X-Type 2005 nodel year)	Out of range check	Sensor voltage	>= 4.9 volts		Ignition on	0.5s	2 Drive Cycles
	Comparison with MAP sensor signal and barometric pressure signal			P0108, P0111, P0112, P0113, P0116 P0125, P0128, P0222, P0223, P0335 P1104, P1107, P1108, P1224, P1229	6, P0117, P0118, F 5, P0336, P0460, F 9, P1245, P1246, F	P0121, P0122 P0603, P0616 P1251, P1609	, P0123, , P0617, , P1611,
n	P0107 8 (X-Type 2005 lodel year) P0108 9 (X-Type 2005 lodel year) P0106 9 (X-Type 2005	Codes  P0107  3 (X-Type 2005) Odel year) P0108 Out of range check	Codes  Potor Potor Strategy Description  Potor Strategy Description  Criteria  Sensor voltage  Sensor voltage  Sensor voltage  Sensor voltage  Sensor voltage  Comparison with MAP Sensor voltage   Codes  P0107 3 (X-Type 2005) R0del year) P0108 R (X-Type 2005) R0del year) P0106 R (X-Type 2005) R0del year) R0del year) P0106 R (X-Type 2005) R0del year) R0d	Codes    Codes	Codes	Codes	

# **6.11.4 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.12 Intake Air Temperature Sensor

The Intake Air Temperature sensor is a thermistor device mounted inside the Mass Airflow sensor. It provides an input signal to the ECM proportional to the temperature of air passing through the inlet duct into the engine. A DTC is recorded if the voltage input signal from the sensor to the ECM is outside pre-defined thresholds at the high or low end of the scale.

# 6.12.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.12.2 Range/Performance Check 1

If engine speed and intake airflow is sufficient, the Engine Coolant Temperature is low enough and the air temperature sensor voltage is lower than calibrated constants, then a monitoring failure judgment is made.

If after a calibrated period has elapsed the voltage from the sensor is greater than a calibration constant then a monitoring normal judgment is made.

## 6.12.3 Range/Performance Check 2

At intervals of approximately 2 seconds, the Intake Air Temperature is sampled to monitor for rapid drop in air temperature. If the change in Intake Air Temperature (over a 6 second period) is greater than a calibration constant then a monitoring failure judgment will be made. A normal judgment is made if the change in Intake Air Temperature change is less than this calibrated value.

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# **6.12.4 Monitoring Structure**

			Intake Air Ter	nperature Sens	sor			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
IAT high input	P0113	Out of range check	Sensor voltage	<= 0.1 volts		Ignition on	0.5s	2 Drive Cycles
IAT low input	P0112	Out of range check	Sensor voltage	>= 4.9 volts		Ignition on	0.5s	2 Drive Cycles
IAT range/ performance	P0111	1 - Rationality versus run time	Sensor voltage	<=- 0.3 volts (> 100°C)	Engine speed Mass Airflow Engine Coolant Temperature	> 1000 RPM > 5 g/s < 40°C	17.5s	2 Drive Cycles
		2 – Two sided other check	Sensor voltage change/2 seconds	>= 20°C (X-Type) >= 45°C (V8) >= 35°C (S-Type)		Ignition on	6s	
				(- 3)/		P0101, P0102,		
						P0116, P0117,		
						P0335, P0336, P1104, P1241,		

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			Intake Air Temp	erature Se	nsor (2008MY)			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
IATS low input	P0112	Out of range check	IAT voltage (>= 4.86 V)	<= -40 degC	Ignition	On	0.512 s	2 Drive
IATS high input	P0113	Out of range check	IAT voltage (<= 0.12 V)	>= 119.4 degC				Cycles
IATS range /	P0111	Range Performance	IAT Signal	<= 0.33 V	Engine speed	>= 1000 rpm	17.5 s	2 Drive
performance		IAT stuck high		(>= 100	Mass Airflow	>= 5 g/s		Cycles
				degC)	Engine Coolant Temperature	<= 40 degC		
					Time after start	>= 1.28 s		
IATC rongo /	P0111	Range Performance	IAT(i - 3) - IAT(i)	> 40 degC	Battery voltage	>= 10.0 V		2 Drive
IATS range / performance		Readings taken every	<u>And</u>		Engine Start	Not in progress		Cycles
periormance		2 seconds and compared	IAT(i - 4) - IAT(i-1) <b>And</b>	> 40 degC	Ignition turned on	Not in last 2.0 s		
		(unexpected step change in Signal)	IAT(i - <del>5) - I</del> AT(i-3)	> 40 degC				
IATS range /	P0111	Rationality versus	Average_IAT - (average_ECT	> 20 degC	Engine Stall Condition	Not set	Dependent	2 Drive
performance		ECT and Engine oil	+ average_EOT)/2		Block Heater	Not detected	upon	Cycles
		temperature	<u>Or</u>		Time after start	120 <= time <= 200 s	drive cycle	
			(average_ECT+ average_EOT)/2	> 20 degC	5	28800 <= time <= 655000 s		
			- Average_IAT		Difference between Engine	<= <mark>10</mark> degC		
					Coolant Temperature average			
					and Oil temperature average at ignition on			

**6.12.5 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.13 Intake Air Temperature Sensor 2 Monitor (V8 Supercharged Only)

### 6.13.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software.

If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored.

If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.13.2 Range/Performance Check 1

If engine speed and intake airflow is sufficient, the Engine Coolant Temperature is low enough and the air temperature sensor voltage is lower than calibrated constants, then a monitoring failure judgment is made.

If after a calibrated period has elapsed the voltage from the sensor is greater than a calibration constant then a monitoring normal judgment is made.

## 6.13.3 Range/Performance Check 2

At intervals of approximately 2 seconds, the Intake Air Temperature is sampled to monitor for rapid drop in air temperature. If the change in Intake Air Temperature (over a 6 second period) is greater than a calibration constant then a monitoring failure judgment will be made. A normal judgment is made if the change in Intake Air Temperature change is less than this calibrated value.

## 6.13.4 Range/Performance Check 3

The monitor examines the integrity of IAT 2 sensor, by comparing it with the temperature signal from IAT 1 sensor, during the initial engine start up period (first 60 sec). The monitor will only execute after a cold start has been detected and appropriate cold soak flag has been set. The cold soak flag is set when the absolute of value (IAT – ECT < 10 °C), and a cold start has been initiated. Once a cold start has been identified and the monitor entry conditions are satisfied, the monitor proceeds to compare the two sensor readings. If the absolute value of IAT 2 – IAT 1 is less than the threshold then a normal counter is incremented, and upon exceeding a calibrated threshold, a normal judgment is set. If the absolute value is greater than the threshold, then a failure counter is incremented, and upon exceeding a calibrated threshold of the counter, a failure judgment is set.

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# **6.13.5 Monitoring Structure**

		Intake Ai	ir Temperature 2 Se	ensor (4.2L	Supercharged Only)			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
IAT 2 low input	P0097	Out of range check	IAT 2 voltage	< 0.1 volts		Ignition on	0.5s	2 Drive Cycles
IAT 2 high input	P0098	Out of range check	IAT 2 voltage	> 4.9 volts		Ignition on	0.5s	2 Drive Cycles
IAT 2 range/ performance	P0096	1 – Rationality versus run time	IAT 2 voltage	<= 0.3 volts (>= 100°C)	Engine speed Airflow Engine Coolant Temperature	>= 1000 RPM >= 5 g/s <= 40°C	18s 0.5s (2004 model year)	2 Drive Cycles
		2 – Two sided other check	IAT 2 voltage change/2 seconds	>= -45°C	Intake Air Temperature	Ignition on <= 40°C	6s	
		3 – Comparison check	IAT 2 versus IAT 1	>= 35°C	Engine Coolant Temperature Engine soak judged ECT – IAT 1 Manifold pressure Engine after start count	<= 40°C <= 10°C <= 70 kPa (2003 model year only) <= 60s		
					Disable: The state of the state	P0097, P0098, P010 P0105, P0111, P011 P0117, P0118, P012 P0336, P0603, P110 P1240-P1242, P124 P1474, P1642, P160	12, P0113, P01 25, P0128, P03 04, P1107, P11 3, P1245, P124	16, 35, 08,

**6.13.6 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.14 Engine Coolant Temperature Sensor

The sensor is a thermistor, a solid-state variable resistor that changes resistance in response to a rise or fall in temperature. It is mounted in the engine block coolant system. The sensor is supplied with a reference voltage through a fixed resistor. As the current passes through the thermistor resistance, the ECM measures the voltage drop across the fixed resistor and translates this into a temperature using a pre-programmed table of values.

# 6.14.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software.

If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored.

If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.14.2 Range/Performance Failure

There are two parts to the range/performance monitor. The first part ensures that the Engine Coolant Temperature reaches the level required for closed loop fuelling. The second part ensures that the Engine Coolant Temperature reaches 80°C. Both parts of the monitor operate with the same strategy, are one shot monitors and each part has its own calibration values. If the Engine Coolant Temperature and intake air temperature are above the required level for each monitor part then the following strategy will be carried out otherwise the counters for that monitor part are reset.

There are two counters associated with each monitor - the load conditions met counter increments when the engine speed and load are above the required level - the load conditions not met counter increments when any of those conditions is not met.

A normal judgment is made if the Engine Coolant Temperature reaches the required level before the load conditions met counter reaches the value held in the judgment table.

A failure judgment is made if the load conditions met counter reaches the value held in the judgment table and the Engine Coolant Temperature has not yet reached the required level.

The judgment table holds the values that the load conditions met counter must reach, mapped against minimum Engine Coolant Temperature (and minimum intake air temperature for the range/performance monitor), for a failure judgment to be made.

The load conditions not met counter has a value associated with it which if exceeded will reset both the load conditions met counter and the load conditions not met counter.

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# **6.14.3 Monitoring Structure**

			Engine Co	olant Temp	erature Sensor			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
ECT high input	P0118	Out of range check	ECT voltage	<= 0.14 volts		Ignition on	0.5s	2 Drive Cycles
ECT low input	P0117	Out of range check	ECT voltage	>= 4.86 volts		Ignition on	0.5s	2 Drive Cycles
ECT range/ performance	P0116	1) Time for ECT to reach 80 °C check	ECT/time	See table ECT1	Engine speed (RPM) Engine load	>=1600 (X-Type) >=1400 (V8) >=1500 (S-Type) > 0.4 g/revolutions (X-Type) > 0.5 g/revolutions (XJ) > 0.6 g/revolutions (XK8) * If these conditions are not met for > 1100s	See table ECT1	2 Drive Cycles
	P0116	2) Two sided other sheet.	FOT valtage	> - 20 °C	Engine Coolant Temperature Intake Air Temperature	then the monitor is reset.  -15 to 80 °C  >= -15 °C	6 s	2 Drive
	PULIO	2) – Two sided other check	ECT voltage change/ 2s	> - 20 °C		Ignition on	68	Cycles
	P0125	Time to closed loop fuelling enable temperature (-15 °C)	ECT/time	See table ECT2	Engine speed (RPM) Engine load	> 500 * > 0.2 g/revolutions * * If these conditions are not met for >300s (>60s 2008MY) then the monitor is reset.	See table ECT2	2 Drive Cycles
				Disable:	ECT Intake Air Temperature P0031, P0032, P0051, P0052, I P0117, P0118, P0201, P0202, I P0352, P0353, P0354, P0355, I P1242, P1243, P1367, P1368, I	P0203, P0204, P0205, P0206, P0356, P0357, P0358, P0562,	P0207, P0208	8, P0351,

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		En	ngine Coolant Temperatu	re Sensor	(P0116 – 2008MY)			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
ECT range /	P0116	Coolant temperature	ECT signal Voltage	< ECT3	Time after engine start	< 3.584 s	1.02 s	2 Drive
performance		biased high			Engine Oil Temperature	-15 < EOT < 40 degC		Cycles
					Fuel Rail Temperature	-15 < FRT < 40 degC		
					Intake Air Temperature	-15 < IAT < 40 degC		
					Oil temperature at ignition off -	> 40 degC		
					current oil temperature			
					Difference between oil	< 10 degC		
					temperature and Intake Air			
					Temperature	40.1.0		
					Difference between oil	< 10 degC		
					temperature and Fuel rail temperature			
					Difference between Fuel rail	< 10 degC		
					temperature and IAT	10 dege		
					Oil temperature at ignition off	< 100 degC		
					On temperature at ignition on	100 dogo		
ECT range /	P0116	Range Performance	ECT(i - 3) - ECT (i)	> 20 degC	Battery voltage	>= 10.0 V		2 Drive
performance		Readings taken every 2	And	J	Engine Start	Not in progress		Cycles
		seconds and compared	ECT(i - 4) - ECT(i-1)	> 20 degC	Ignition turned on	Not in last 2.0 s		
		(unexpected step change	<u>And</u>		_			
		in Signal)	ECT(i - 5) - ECT(i-3)	> 20 degC				
			, , , , ,					
ECT range /	P0116	Time for the coolant to	ECT	< 80 degC	Time to closed loop or ECT	Not set	ECT1	2 Drive
performance		reach 80 degC	<u>And</u>		biased high faults			Cycles
		(i.e. Coolant temperature	Entry conditions true for	>= Table	Engine Coolant Temperature	>= -15 degC		
		biased low)		ECT1	Intake Air Temperature	>= -15 degC		
					Engine Speed	>= <mark>1200</mark> rpm*		
					Engine load	>= 0.4 g/rev*		
						*If these conditions		
						are not met for >=		
						1100 s, then the		
						monitor is reset		
				<u> </u>		<u> </u>		

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	Enç	gine Cool	ant Tem	perature	Sensor F	Range Pe	rformand	ce (4.2L)	- ECT1			
Start ECT (°C)	-15	-10	0	10	20	30	40	50	60	70	80	90
Failure time counter (sec)	1350	1350	1200	1050	1000	950	800	700	700	400	400	400

Engine Coolant Temperature Sensor Range Performance (3.0L) – ECT1												
Start ECT (°C)	-30	-15	-5	5	15	25	35	45	55	65	75	80
Failure time counter (sec)	3212	2888	2658	2418	2325	2107	2157	1658	1492	1380	1380	1380

	<b>Engine Coola</b>	nt Temperatur	e Sensor Ran	ge Performano	e (X-Type Fro	m 2004 Model	Year) – ECT1	
				Start E	CT (°C)			
Min. IAT (°C)	-15	0	15	30	45	55	65	75
-15	2165	2045	1930	1765	1525	1285	930	365
0	2165	1310	1190	1065	885	715	505	185
15	2165	1310	880	755	620	495	345	140
30	2165	1310	880	595	455	360	250	95
40	2165	1310	880	595	455	360	250	95

	<b>Engine Coola</b>	nt Temperatur	e Sensor Ran	ge Performano	ce (S-Type Fro	m 2004 Model	Year) – ECT1	
				Start E	CT (°C)			
Min. IAT (°C)	-15	0	15	30	45	60	75	80
-15	2570	2405	2245	2025	2025	2025	2025	2025
0	2570	2000	1840	1775	1775	1775	1775	1775
15	2570	2000	910	785	785	785	785	785
30	2570	2000	910	630	630	630	630	630
40	2570	2000	910	630	630	630	630	630

Engine Coolant Temperature Sensor Range Performance (XK8 From 2004 Model Year) – ECT1														
		Start ECT (°C)												
Min. IAT (°C)	-15	-15         0         15         30         45         50         60         70         80												
-15	2250	2150	1950	1750	1550	1550	1550	1550	1550					
0	2250	1400	1250	1100	950	950	950	950	950					
15	2250	1400	950	800	650	650	650	650	650					
30	2250	1400	950	625	625	625	625	625	625					
45	2250	1400	950	625	625	625	625	625	625					

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	Engine Coolant Temperature Sensor Range Performance (New XJ From 2004 Model Year) – ECT1													
					Start ECT (°C)									
Min. IAT (°C)	-15	15 0 15 30 45 50 60 70 80												
-15	4404	4404	4404	4205	4205	4205	4205	4205	4205					
0	4404	1744	1548	1358	1093	1093	1093	1093	1093					
15	4404	1744	1021	882	733	733	733	733	733					
30	4404	1744	1021	655	514	514	514	514	514					
45	4404	1744	1021	655	396	396	396	396	396					

	En	gine Coc	lant Tem	perature	Sensor	Range Pe	erforman	ce (X400	2008 Mo	del Year)	- ECT1		
		Minimum coolant temperature (°C)											
Min. IAT (°C)	-15												
-15	2337	2295	2272	2225	2012	1906	1677	1290	625	625	625	625	2337
0	2337	1310	1190	1065	945	885	715	505	220	220	220	220	2337
15	2337	1310	880	755	665	620	495	345	140	140	140	140	2337
30	2337	1310	880	595	502	455	360	250	115	115	115	115	2337
40	2337	1310	880	595	502	455	360	250	95	95	95	95	2337

Engine Coolant Temperature Sensor Range Performance (4.2L) – ECT2										
Start ECT (°C) -30 -25 -20 -15										
Failure time counter (seconds)	200	200	200	200						

	Engine Coolant Temperature Sensor Range Performance (3.0L) – ECT2											
Start ECT (°C)	-30	-20	-10	0	10	20	30	40	50	60	70	80
Failure time counter (seconds)	326	326	324	324	324	324	324	324	324	324	324	324

Engine Coolant Temperature Sensor Range Performance (New XJ From 2004 Model Year) – ECT2										
Start ECT (°C)	-40	-32	-23	-20	-15	-15				
Failure time counter (seconds)	600	300	120	120	120	120				

Engine Coolant Temperature Sensor Range Performance (XK8 From 2004 Model Year) – ECT2										
Start ECT (°C)	-40	-40	-30	-25	-20	-15				
Failure time counter (seconds)	300	200	200	200	200	200				

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Engine Coolant Temperature Sensor Range Performance (S-Type From 2004 Model Year) – ECT2									
Start ECT (°C)	-40	-30	-20	-15	-15	-15			
Failure time counter (seconds)	240	120	120	120	120	120			

Engine Coola	Engine Coolant Temperature Sensor Range Performance (X-Type From 2004 Model Year) – ECT2										
Start ECT (°C)	-40	-40	-32	-23	-20	-15					
Failure time counter (seconds)	600	600	300	120	120	120					

ECT (P	ECT (P0116) Time to closed loop enable temperature (X400 2008 Model Year) – ECT2											
Min Coolant Twmperature (°C)	-40	-40	-31.9	-23.1	-20	-15	-15	-15	-15	-15	-15	-15
Time (seconds)	600	600	300	120	120	120	120	120	120	120	120	120

Engi	Engine Coolant Temperature Sensor – Fault limit (X400 2008 Model Year) – ECT3											
Average Temperature (degC)	-15	-5	5	25	35	45	55	65				
Fault Limit (V)	2.632	2.129	1.689	1.011	0.781	0.601	0.464	0.361				

# 6.14.4 Drive Cycle Information

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

#### 6.15 Thermostat Monitor

The monitor operates once per trip and is not a continuous monitor. Every 1 second the monitor compares the actual Engine Coolant Temperature with an estimated temperature. This is derived from a model and accumulates the error between the two temperatures. The model to calculate the estimated Engine Coolant Temperature has look-up tables, which use various engine and vehicle parameters to derive compensation values by which the estimated Engine Coolant Temperature is increased or decreased. These look-up tables' takes into account engine speed, engine airflow, vehicle speed and temperature difference between Intake Air Temperature and Engine Coolant Temperature.

A judgment of whether the thermostat is behaving normally or not is made when the estimated Engine Coolant Temperature reaches a judgment level which is 35°C above starting Engine Coolant Temperature or 80°C, whichever is reached first. The monitor has the ability to make one of three judgments once the judgment point is reached. The judgment made can be "normal", "fail" or "null". The normal judgment is made if the accumulated error is below the calibratable normal level and the actual Engine Coolant Temperature has reached 80°C at the judgment point. The failure judgment is made if the accumulated error equals or exceeds the calibratable failure level at the judgment point. A null judgment is made if the accumulated error is above the normal level and below the failure level at the judgment point. The null judgment is included to allow for the gray area that exists between normal and failed thermostats, as in extreme conditions a failed thermostat may resemble normal behavior and a normal thermostat could resemble failed behavior.

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# **6.15.1 Monitoring Structure**

			Thermost	tat Monitor				
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Thermostat	P0128	Comparisons of actual warm up	Accumulated difference	See table	Intake Air Temperature	- 8 to 100 °C	Dependent on	2 Drive
range/		profile with estimated profile.	between estimated ECT		Engine Coolant Temperature	- 8 to 100 °C	drive cycle	Cycles
performance			and actual ECT is too large		ECT at engine start	- 8 to 60 °C	(typically 460s)	
		estimated ECT increases by 35			Airflow	>= 1 g/s		
		°C or reaches 80 °C			Engine Speed	>= 400		
					C1155, C1165, C1175, P0010, F			
					P0103, P0107, P0108, P0111, P			
					P0123, P0125, P0128, P0131, P			
					P0174, P0175, P0201, P0202, P			
					P0223, P0335, P0336, P0340, P			
					P0355, P0356, P0357, P0358, P			
					P1108, P1224, P1229, P1241, P			
					P1368, P1384, P1396, P1611, P			642,
				P1646, P1647, F	P0562, P0563, P0607, P2118, P	'2119, P2135, P2	2228, P2229	

		Thermos	tat Monitor	- P0128 Fa	ult limit thre	eshold (X40	0 2008 Mod	el Year)		
					Coolant tem	perature (°C)				
IAT (°C)	-10	0	10	20	25	30	40	50	60	-10
-30	10110	7300	5110	3400	2700	2000	1200	1000	900	10110
-20	10110	7300	5110	3200	2500	1800	1100	900	850	10110
-10	10110	7300	5110	3100	2375	1650	1000	850	800	10110
0	10110	7300	5110	2980	2240	1500	1000	750	750	10110
10	10110	7300	4500	2500	1850	1200	750	750	750	10110
20	10110	7300	3500	1400	920	600	600	600	600	10110
30	10110	7300	3500	1400	920	600	600	600	600	10110
40	10110	7300	3500	1400	920	600	500	500	500	10110

**6.15.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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### 6.16 Throttle Position Sensor

The Throttle Position sensor comprises of a potentiometer with a pointer that is rotated by the throttle shaft. The ECM supplies the potentiometer with a nominal 5 volts. The signal output from the Throttle Position sensor to the ECM depends on the position of the pointer and ultimately the position of the throttle shaft. The sensor's position in relation to the shaft cannot be adjusted and the ECM compensates for wear and aging in service.

# **6.16.1 Monitoring Structure**

			Throttle Po	sition Senso	r			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Throttle position 1 low input	P0122	Out of range check	Output voltage	<= 0.35 volts		Ignition on	1.0s	2 Drive Cycles
Throttle position 1 high input	P0123	Out of range check	Output voltage	>= 4.9 volts		Ignition on	1.0s (V6) 0.1s (V8)	2 Drive Cycles
Throttle position 2 low input	P0222	Out of range check	Output voltage	<= 0.35 volts		Ignition on	1.0s	2 Drive Cycles
Throttle position 2 high input	P0223	Out of range check	Output voltage	>= 4.9 volts		Ignition on	1.0s (V6) 0.1s (V8)	2 Drive Cycles
performance	P0121 P2135 (2005 model year X- Type)	Rationality 1 to 2	Signal 1 versus signal 2	See table TPS1	Battery voltage	9 to 18v	0.1s	2 Drive Cycles
					Disable:	P1241, P1242		

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	Throttle Position Sensor Range Performance – TPS1										
Throttle angle (degrees)	0.00	2.00	2.13	4.25	9.0	20.5	32.0	84.0			
Value (degrees)	3.2	3.2	3.2	6.7	7.1	10.0	11.1	11.1			

Throttle Position Sensor Range Performance (2008MY) – TPS1									
Throttle angle (degrees)	0.00	2.00	2.13	4.25	9.00	20.50	32.00	84.00	
Value (degrees)	4.23	4.36	4.36	6.37	8.8	12.89	13.61	19.23	

**6.16.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.17 Engine Oil Temperature Sensor

## 6.17.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

# 6.17.2 Range/Performance Failure

The EOT movement is monitored during the warm up phase of a trip. If the Engine Coolant Temperature is cool enough at start and rises by the required amount then a judgment is made on the EOT. If the EOT movement (maximum reading for the trip – minimum reading for the trip) has not been sufficient then a failure judgment will be made.

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# **6.17.3 Monitoring Structure**

Engine Oil temperature Sensor									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL	
System	Codes	Description	Criteria	value	Parameter	Conditions	Required		
EOT high input	P0198	Out of range check	Sensor voltage	<= 0.03 volts		Ignition on	0.5s	2 Drive Cycles	
EOT low input	P0197	Out of range check	Sensor voltage	>= 4.6 volts		Ignition on	0.5s	2 Drive Cycles	
EOT range/	P0196	Rationality versus ECT	EOT rise too low compared to ECT	<= 2.5 °C	EOT	<= 130°C	Dependent	2 Drive	
performance			rise		Engine Coolant Temperature ECT rise	-30 - 100°C >= 45 °C	on drive cycle	Cycles	
		EOTS stuck (2008MY)	EOTS change (2008MY)		Intake Air Temperature  Delta oil temperature	-30 - 100°C -30 - 50°C (2008MY) <= 0.015 V in 0.128 s (2008MY)	•		
EOT range/ performance	P0196	Rationality versus Engine Coolant Temperature and Inlet air temperature (2008MY)	Average_EOT - (average_ECT + average_IAT)/2  Or  (average_ECT+ average_IAT)/2	> 20 degC > 20 degC	Engine Stall Condition Block Heater Time after start Engine off time	Not set Not detected 120 <= time <= 200 s 28800 <= time <= 655000 s	Dependent upon drive cycle	2 Drive Cycles	
			- Average_EOT		Difference between Engine Coolant Temperature average and inlet air temperature average at ignition on	<= 10 degC			
					Disable	:P0111, P0112, P0113, P0118, P0125, P0128, P1241, P1242			

**6.17.4 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.18 Fuel Rail Temperature Sensor

## 6.18.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage is over the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

## 6.18.2 Range/Performance Failure

The monitor checks that the fuel rail temperature sensor signal is not stuck within the normal operating range. It checks that the signal has varied by a calibrated amount before the Engine Coolant Temperature signal has increased by 40°C and twenty minutes of engine running has elapsed. Maximum and minimum values of fuel rail temperature and Engine Coolant Temperature are continually calculated. If the difference between the fuel rail temperature maximum and minimum values is greater than the calibrated threshold then normal judgment is made. For failure judgment, the monitor can only flag a failure if a cold start is detected. A cold start is detected when the difference between the Intake Air Temperature and Engine Coolant Temperature is less than a second calibrated value.

## 6.18.3 Monitoring Structure

Fuel Rail Temperature Sensor									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL	
System	Codes	Description	Criteria	value	Parameter	Conditions	Required		
Fuel rail temperature sensor low input		Out of range check	Voltage too low	<= 0.03 volts		Ignition on	0.5s	2 Drive Cycles	
		Out of range check	Voltage too high	>= 4.6 volts		Ignition on	0.5s	2 Drive Cycles	
•	P0181	_	Fuel rail temperature; maximum- minimum		Fuel rail temperature ECT rise ECT at engine start After start time Difference between IAT and ECT at engine start Engine Coolant Temperature Intake Air Temperature	<= 100°C >= 40°C <= 40°C >= 1200s <= 5°C -30 to 100°C -8.13 to 100°C -30 to 100°C -8.13 to 100°C	(S-Type 2004 MY) (S-Type 2004 MY)	2 Drive Cycles	

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Fuel Rail Temperature Sensor									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL	
System	Codes	Description	Criteria	value	Parameter	Conditions	Required		
Fuel rail temperature sensor range/ performance	P0181	Fuel rail temperature rationality compared to ECT and IAT (2008MY)	Average_FRT - (average_ECT + average_IAT)/2  Or (average_ECT+ average_IAT)/2	> 20 degC > 20 degC	Engine Stall Condition Block Heater Time after start Engine off time	Not set Not detected 120 <= time <= 200 s 28800 <= time <=	Dependent upon drive cycle	2 Drive Cycles	
			- Average_FRT		Difference between ECT average and inlet air temperature average at ignition on	655000 s <= 10 degC			
Fuel rail temperature sensor range/ performance	P0181	Fuel rail temperature stuck (2008MY)	EOTS Change <u>And</u>	< 1.9 degC	Cold Start Identified at engine start	ECT < 40 degC And Difference Between ECT & IAT <= 10 degC	Dependent upon drive cycle	2 Drive Cycles	
			Engine Coolant Temperature	> 80 degC	Engine Coolant Temperature Intake Air Temperature Delta FRT Delta ECT Fuel Temperature Change in ECT	-30 < T < 100 degC -30 < IAT < 50 degC <= 0.015 V in 0.128 s <= 0.015 V & <= 20 degC in 0.128 s < 100 degC >= 50 degC			
				Disable:	Time after start P0111, P0112, P0113, P0116, P0 P0460, P0562, P0563, P0603, P1			P0183,	

**6.18.4 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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#### 6.19 Fuel Rail Pressure Sensor

# 6.19.1 High/Low Input Failure

These are continuous monitors. The voltage from the sensor is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage exceeds the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

#### 6.19.2 Stuck Detection

Stuck at monitoring executes when closed loop fuel pump control is executing. It checks that the fuel rail pressure signal has varied by at least 5 kPa over a range of demanded fuel pump duties. The maximum and minimum fuel rail pressures are updated each time. The change in demand duty is integrated and when the integral reaches 4%, the variation between the maximum and minimum values is checked. If it is less than 5kPa, failure judgment is made; otherwise, a normal judgment is made.

#### 6.19.3 Offset Detection

This part of the monitor executes when the vehicle is idling. When closed loop fuel pump control is executing, a settle timer is incremented. After the counter reaches 5 seconds monitoring can be started. This is to allow the system time to settle after a transition from open to closed loop fuel pump control. Once the counter is greater than 5 seconds the target pressure is checked against the actual fuel rail pressure. If the error is less than the failure threshold, a normal counter is started. If the normal counter reaches 1 second, normal judgment is made. If the target to actual error is greater than the failure threshold, a failure counter is started. If the failure counter reaches 5 seconds then failure judgment is made.

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# **6.19.4 Monitoring Structure**

			Fuel Rail Pre	ssure Senso	or			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel rail pressure sensor	P0192	Out of range check	Voltage too low	<= 0.1 volts		Ignition on	0.5s	2 Drive Cycles
low input Fuel rail pressure sensor high input	P0193	Out of range check	Voltage too high	>= 4.9 volts		Ignition on	0.5s	2 Drive Cycles
Fuel rail pressure sensor range/ performance offset detection		Comparison with target pressure	Error	>= 30 kPa	Fuel level Idle flag set Fuel pump feedback control	>= 11% >= 5s Executing	5s	2 Drive Cycles
Fuel rail pressure sensor range/ performance stuck detection	P0191	Rationality versus fuel pump duty integral	Pressure change too low when fuel pump integral duty above threshold	<= 5 kPa	Fuel level Fuel pump feedback control Fuel pump integral duty	>= 11% Executing >= 4%	Dependent on drive cycle	2 Drive Cycles
Stuck detection					Disable:	P1241, P1242, P12 P1609, P0192, P01		

# **6.19.5 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.20 Fuel Injectors

The fuel injector monitor operates on a continuous basis. Open and short detection of each injector is possible by comparing the actual injection signal with a target injection signal. The actual injection signal is derived from a change in injector voltage when the injector is turned off and the target injection signal is derived from an injection set flag.

A normal judgment is made when the injector voltage moves from the on to off position i.e. on the signal edge. If the target signal and the actual signal are both set to one, a normal judgment is made. This process is repeated for each injector in firing order. A failure judgment is made when no injector signal edge is detected i.e. no change in voltage but the injector has been triggered.

# **6.20.1 Monitoring Structure**

			Fuel	Injector N	lonitor					
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Require d	MIL		
Cylinder 1	P0201	Drive hardware check	Commanded versus actual	10 times	Engine speed	200 – 7000	20	2 Drive		
Cylinder 2	P0202	Drive hardware check	Commanded versus actual	10 times	ECT IAT Airflow change	>= - 30°C >= - 30°C < 2g/s/s (up to 2004 model year)	revolutions	Cycles		
Cylinder 3	P0203	Drive hardware check	Commanded versus actual	10 times	(not 2008MY) Injector pulse width	< 31g/s/s (2004 model year)				
Cylinder 4	P0204	Drive hardware check	Commanded versus actual	10 times	Battery voltage TP sensor change	10 to 16v < 22 deg/s				
Cylinder 5	P0205	Drive hardware check	Commanded versus actual	10 times	(not 2008MY)	<= 44 deg/s (V8 2004 model year) <= 56 deg/s (S-Type 2004 model year)				
Cylinder 6	P0206	Drive hardware check	Commanded versus actual	10 times	Fuel cut-off	<= 37 deg/s (X-Type 2004 model year) Not active				
Cylinder 7 (V8 only)	P0207	Drive hardware check	Commanded versus actual	10 times	Time after start  MAF rate of	>= 0s <= 2.0 g/s/0.064 s				
Cylinder 8 (V8 only)	P0208	Drive hardware check	Commanded versus actual	10 times	change (2008MY) MAF (2008MY) TP rate of change (2008MY)	0 <= MAF <= 400 g/s < 0.30 deg/s/0.008 s				
				Disable:	Engine starting   Not active   P0101, P0102, P0103, P0111- P0113, P0121- P0123, P0222, P0223, P0336, P0351- P0358, P1367, P1368, P0603, P0607, P1104, P1224, P1229, P1251, P1367, P1368, P1609, P1611, P1631, P1633, P1637, P1642, P2118, P2119, P2135, C1165, C1175, C1137					

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INJ1 - 4.2L (All from 2004 Model Year)											
Engine speed (RPM)	500	1000	1500	2000	2500	3000	3500	4000	5000	6000	7000
Injector pulse width (us)	42000	21000	14000	10500	8400	7000	6000	5300	4200	3500	3000

INJ1 – 3.0L											
Engine speed (RPM)	500	1000	1500	2000	2500	3000	3500	4000	5000	6000	7000
Injector pulse width (us)	56000	28000	18700	14000	11200	9300	8000	7000	5600	4700	4000

**6.20.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.21 Fuel Pumps

#### 6.21.1 Primary Fuel Pump - No Commands Received

The rear electronics module drives the fuel pump motor. It also monitors the circuit and sends its status to the ECM via the communications network buses. As part of this status, the ECM receives flags indicating invalid input and open circuit on the battery supply. If either of these flags indicates a fault for longer than a set time, then a fault judgment is made and P1234 is logged.

## 6.21.2 Primary Fuel Pump - Not Working When Requested

The ECM also receives a 'fuel pump loss of ground' flag via the CAN network from the rear electronics module. If this flag is set for longer than a pre-defined time a fault judgment is made and P1236 is logged.

# 6.21.3 Primary Fuel Pump Circuit High/Low Fault

The ECM also receives the following flag via the CAN bus from the rear electronics module:

- Fuel pump monitor line open circuit.
- Fuel pump monitor line short circuit to battery.
- Fuel pump monitor line short circuit to ground

If any of these flags indicate a fault for longer than a set time, then a fault is registered and P1338 is logged.

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# **6.21.4 Monitoring Structure**

		Р	rimary Fuel Pump –	Up to 2004 N	lodel Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
No fuel pump	P1234	Monitor control module control	Control module control line	Battery voltage	Battery voltage	10 volts	4.5s	2 Drive
commands		line	invalid input		Delay counter	3.5s		Cycles
received					Fuel pump duty	25% to 75%		
Fuel pump not	P1236	Control module circuit	Control module loss of	No signal	Battery voltage	10 volts	4.5s	2 Drive
working when			ground		Delay counter	3.5s		Cycles
requested					Fuel pump duty	25% to 75%		
Circuit low input	P1338	Monitor control module monitor	Control module monitor line	Battery voltage	Battery voltage	10 volts	4.5s	2 Drive
		line	high		Delay counter	3.5s		Cycles
					Fuel pump duty	25% to 75%		
Circuit high	P1338	Monitor control module monitor	Control module monitor line	No signal	Battery voltage	10 volts	4.5s	2 Drive
input		line	low		Delay counter	3.5s		Cycles
					Fuel pump duty	25% to 75%		
					Disable:	P1609		

		P	rimary Fuel Pump –	From 2004 Mo	del Year			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
No fuel pump commands	P1234	Monitor control module control line		< 39.2% (X-Type) < 35.2% (all others)	Battery voltage Delay counter	10 volts 3.5s	4.5s	2 Drive Cycles
received Fuel pump not working when requested	P1236	Control module circuit	Control module status line duty cycle	> 60.8% (X-Type) > 64.8% (all others)	Fuel pump duty Battery voltage Delay counter Fuel pump duty	25% to 75% 10 volts 3.5s 25% to 75%	4.5s	2 Drive Cycles
requested					Disable:	P1609		

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		Pr	imary Fuel Pump – 2	X-Type 2005 Mc	odel Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
No fuel pump	P0627	Monitor control module	Control module status line	< 39.2% (X-Type)	Battery voltage	10 volts	4.5s	2 Drive
commands		control line	duty cycle	< 35.2% (all others)	Delay counter	3.5s		Cycles
received					Fuel pump duty	25% to 75%		
Fuel pump not	P2635	Control module circuit	Control module status line	> 60.8% (X-Type)	Battery voltage	10 volts	4.5s	2 Drive
working when			duty cycle	> 64.8% (all others)	Delay counter	3.5s		Cycles
requested					Fuel pump duty	25% to 75%		
Circuit low input	P0628	Monitor control module	Control module status line	Battery voltage		Ignition on	4.5s	2 Drive
		status line	high		Delay counter	3.5s		Cycles
					Battery voltage	10 volts		
					Fuel pump duty	25% to 75%		
Circuit high	P0628	Monitor control module	Control module status line	No signal		Ignition on	4.5s	2 Drive
input		status line	low		Delay counter	3.5s		Cycles
					Battery voltage	10 volts		
					Fuel pump duty	25% to 75%		
					Disable:	P1609		

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# **6.21.5 Secondary Fuel Pump Monitor**

A status flag monitors the Pulse Width Modulation (PWM) signal from the secondary fuel pump driver module. When this status flag is stuck low for a set time, then a fault is flagged and P1233 is logged. When this status flag is stuck high, or the PWM duty is outside a calibrated range for a set time, then a fault is flagged and P1339 is logged.

# **6.21.6 Monitoring Structure**

		Secor	ndary Fuel Pump – S	upercharge	d Vehicles Only			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Fuel pump	P1233	Monitor control module control	Control module control line	< 0.392s	Battery voltage	10 volts	4.5s	2 Drive
driver circuit		line	duty cycle		Delay counter	3.5s		Cycles
input circuit fault					Fuel pump duty	25% to 75%		
Fuel pump	P1339	Control module circuit	Control module control line	608 - 1.000s	Battery voltage	10 volts	4.5s	2 Drive
driver circuit			duty cycle		Delay counter	3.5s		Cycles
output fault					Fuel pump duty	25% to 75%		
Circuit low input	P1339	Monitor control module monitor	Control module control line	No signal	Battery voltage	10 volts	4.5s	2 Drive
		line	duty cycle		Delay counter	3.5s		Cycles
					Fuel pump duty	25% to 75%		
Circuit high	P1339	Monitor control module monitor	Control module control line	No signal	Battery voltage	10 volts	4.5s	2 Drive
input		line	duty cycle		Delay counter	3.5s		Cycles
					Fuel pump duty	25%>Duty>75%		
					Disable:	P1609		

# **6.21.7 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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#### 6.22 Fuel Level Sensor

There are two parts to the fuel level sensor monitor. The output of the fuel level sensor is monitored to detect if its output does not change as fuel is used. It is also monitored when the vehicle is stationary and fuel movement is expected to be at a minimum to check for a noisy signal.

#### 6.22.1 Fuel Level Stuck Monitor

The fuel level is monitored continuously and it needs to change by more than a set percentage before a calculated amount of fuel is used. This process will operate through cumulative trips if necessary. Once the fuel level changes by the amount required the process is reset and starts again. If the fuel used threshold is reached before the fuel level changes by the required percentage, a temporary fault will be stored. A second occurrence will cause the Malfunction Indicator Lamp (MIL) to be illuminated.

#### 6.22.2 Fuel Level Noisy Monitor

Once the fuel level percentage has changed to satisfy the stuck monitor described above and a few other entry conditions have been met, the system will complete a fuel level noisy test in the next available idle period. When the vehicle comes to rest the fuel movement will be allowed to subside. The output of the fuel level sensor will be monitored for a short period. During this period the output of the fuel level sensor will be integrated and compared to a threshold, which is set to find faulty fuel level sensors. This process is repeated as the fuel level falls. If the failure threshold is exceeded a first trip temporary failure flag will be set. A further failure in the next trip will illuminate the MIL.

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# **6.22.3 Monitoring Structure**

				Fuel Level Sensor				
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
Fuel level sensor circuit		Rationality versus fuel used	Fuel level change	<= 3% <= 6% (S-Type)	Fuel used (calculated) After start Battery voltage Disable:	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	Dependent on drive cycle	2 Drive Cycles
Fuel level sensor malfunction	P0460			>= 5000/20s (S-Type) >= 2500/20s (X-Type) >=11000/20s (XJ)	Battery voltage Vehicle speed Fuel level Then Vehicle speed Entry delay Monitor period	>= 3% >= 6% (S-Type) 8 to 16 volts 10 to 16 volts (2004 model year) > 31mph for >20s 15 to 85% 5 to 95% (2008MY) = 0 10s 20s <= 410 mph/0.064 s <= 0.25 mph (between CAN messages)	3, P0561, P0 0, P1241, P1	562, 242,

**6.22.4 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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#### 6.23 Knock Sensor

'Knocking' or 'pinking' is caused by uncontrolled combustion and can result in engine damage as well as excessive emissions. Knocking noises are essentially vibrations with frequencies that are detected by a piezo-electric sensing element and converted into electrical signals. Two knock sensors are strategically located on the engine casing and switched to the firing sequence so that knocking from any cylinder may be detected.

## 6.23.1 High/Low Input Failure

High and low input failure of the knock sensor is detected in the knock sensor processor and is then transmitted to the ECM. The Direct Current (DC) voltage of the sensor is compared with the upper and lower limits in order to judge high or low input failure.

#### 6.23.2 Knock Sensor Processor Failure

Knock sensor processor failure is detected within the processor and is then transmitted to the ECM.

## 6.23.3 Monitoring Structure

			Knock	Sensor				
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Knock sensor A	P0327	Out of range check	Sensor output low and	<= 1.25 volts	After start	>= 3s	8 revolutions	2 Drive
low input			knock sensor processor reporting failure	<=1.3v (2004 model year)	Engine speed	>= 500 RPM	64 revolutions (2004 model year)	Cycles
Knock sensor B low input	P0332	Out of range check						
Knock sensor A high input	P0328		Sensor output low and knock sensor processor reporting failure	>= 3.75 volts >= 3.8v (2004 model year)	After start Engine speed	>= 500 RPM		2 Drive Cycles
Knock sensor B high input	P0333	Out of range check						
Knock sensor	P1648	Knock sensor processor	Knock sensor processor		After camshaft and crank	>= 5s	8 revolutions	2 Drive
			reporting self-check failure		sensors judged normal Engine speed		64 revolutions (2004 model year)	Cycles
					Disable:	P1609		

# **6.23.4 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.24 Variable Valve Timing

VVT is a mechanically operated, electronically controlled system and is fitted to all current Jaguar engines except the 4.2L V8 supercharger.

The system comprises an actuator (phaser) built into the camshaft chain sprocket and an oil control valve which controls the flow of oil to the camshaft phaser. The system is controlled via the oil control valve and CMP sensors. The oil control valve varies the oil flow into the camshaft phaser and creates a variable offset between the camshaft and the camshaft sprocket, feedback for this system is provided by the CMP sensors.

The monitors for this topic are best described in two sections. The first section is concerned with VVT position failure and normal operation counters. If calibratable conditions are met for a failure condition then fault counters are incremented. The same applies for normal operation of the VVT system. The counters are then compared to a calibratable constant (threshold) and a judgment made. For a failure judgment, the failure counter has to be of an equal or higher value than the threshold constant and likewise, for a normal judgment the normal counter has to be equal or greater than the normal counter. Once these comparisons have been carried out, the relevant failure/judgment flags are set.

The second section of this monitor is concerned with monitoring the oil control valve on both banks 1 and 2. The oil control valve duty output is compared to an upper and lower threshold and the state of the latch port (1 = output, 0 = no output). If oil control valve duty output is outside of the upper/lower band and the latch has no output then a failure counter is incremented. If the conditions are not met, the monitor moves on to the next comparison. The oil control valve duty output is compared to an upper and lower threshold and the state of the latch port (output/no output). If the oil control valve duty output is outside of the upper/lower band and the latch has an output then the failure counter is set to zero, normal judgment flag set to 1 and failure judgment flag set to zero. If the conditions are not met, the monitor moves on to the next comparison. The failure time counter is compared to the failure judgment time threshold and if equal or greater than the threshold a failure flag is set and a present failure flag is set. If none of the comparison conditions are met then the oil control valve latch port is set to zero. This is also performed after the comparisons have been carried out. The monitor now moves onto the flag control section and restarts.

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# **6.24.1 Monitoring Structure**

		Variable	e Valve Timing – Nor	mally Aspirated	d Engines Only			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
VVT Bank A circuit malfunction	P0010	Hardware check	Commanded versus actual	Different	Oil control valve duty cycle	30 to 70%	5s 3s (2004 model year)	2 Drive Cycles
VVT Bank B circuit malfunction	P0020							2 Drive Cycles
VVT Bank A malfunction		Actual cam position compared with target position	Target versus actual	Error > 20 degrees of crank angle	Engine speed > 0			2 Drive Cycles
VVT Bank B malfunction		Actual cam position compared with target position	Target versus actual				`	2 Drive Cycles
					Disable:	P0335, P0336, P1609, P0196, P0197, P0198	after cleaning)	
					Bank A Bank B	P0340, P0341 P1340, P1341 (P0345, P0346 from 2004 model year)		

**6.24.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.25 Ignition Amplifiers/Coils

The ignition amplifiers monitor is very similar in operation to the injectors monitor, albeit with different enable conditions. Please refer to the fuel injectors monitor explanation. The ignition amplifiers have two monitor lines that carry multiplexed ignition amplifier monitor signals whereas the injectors can be monitored individually. It is for this reason that the ignition amplifiers monitor does not operate over such a wide range of engine speeds as the injectors monitor.

# **6.25.1 Monitoring Structure**

			Ignition Ampl	ifiers/Coils	S			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Ignition amplifiers cylinder 1 Bank A	P0351	Hardware check	Primary coil current		Engine speed	< 2500 RPM <= 3000rpm (2008MY)	40 revolutions	2 Drive Cycles
Ignition amplifier cylinder 2 Bank A	P0353	Hardware check	Primary coil current		Battery voltage	> 10 volts		2 Drive Cycles
Ignition amplifier cylinder 3 Bank A	P0355	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier cylinder 4 Bank A	P0357	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier cylinder 1 Bank B	P0352	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier cylinder 2 Bank B	P0354	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier cylinder 3 Bank B	P0356	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier cylinder 4 Bank B	P0358	Hardware check	Primary coil current					2 Drive Cycles
Ignition amplifier group 1	P1367	Hardware check	Primary coil current				20 revolution	2 Drive Cycles
Ignition amplifier group 2	P1368	Hardware check	Primary coil current					2 Drive
					Disable:	P1642, P1609, P0336		Cycles

# 6.25.2 Drive Cycle Information

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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### 6.26 Charge Air Cooler Water Pump

The charge air cooler water pump monitor has been implemented to prevent engine damage, in the event of water pump failure. The monitor is only present on supercharged variants and operates continuously during each drive, with a sample rate of 2.048 seconds. The basic operation of the monitor is to compare the value of the intercooler IAT 2 against the IAT 1, at the end of a period of steady state operating conditions. Once the defined steady state conditions are satisfied, a drive delay counter is incremented. Upon exceeding a calibrated threshold, if the difference between the two temperature values (IAT 2 – IAT 1) is greater than the mapped threshold, a failure counter is incremented. If the counter exceeds a calibrated threshold, a failure judgment is made. A normal judgment is made if the two temperature values are below the failure threshold, at the point of judgment.

## **6.26.1 Monitoring Structure**

	Charge Air Cooler Water Pump – 4.2L Supercharged Only											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
Charge air	P1474	Comparison check	IAT 2 versus IAT 1	See table WTP1	3	80 to 110 °C	30s (430s	2 Drive				
cooler water					Intake Air Temperature	-8 to 100 °C	including drive	Cycles				
pump					Mass air flow	6 to 40 g/s	counter)					
malfunction					Engine speed	600 to 4000 RPM						
					Vehicle speed	18.6 to 74.5 MPH						
					Vehicle drive counter	> 400s						
					Disable:	P0335, P0336, P00	)96-P0098, P011	I1-P0113,				
						P0101-P0103, P11	04, P1637, P164	12,				
						P1609, P0116-P01	18, P0125, C113	37,				
						C1145, C1155, C1	165, C1175					

WTP1 (Up to 2004 Model Year)										
IAT °C	-10	0	10	20	25	30	40	50	60	70
Delta temperature (IAT 2 - IAT 1)	70	70	70	70	70	70	70	70	70	70

WTP1 (From 2004 Model Year)										
IAT °C	-10	0	10	20	25	30	40	50	60	80
Delta temperature (IAT 2 - IAT 1)	75	70	70	70	70	70	70	70	70	70

## **6.26.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.27 Idle Speed Control

If all the entry conditions are satisfied, then the monitor will start execution.

If the actual engine speed is more than 100 RPM lower than the target engine speed then a counter is started and once this exceeds the failure time limit a failure judgment is made for idle speed lower than expected.

If the actual engine speed is greater than 200 RPM higher than the target engine speed then a counter is started and once this exceeds the failure time limit a failure judgment is made for idle speed higher than expected.

			Idle Speed Contro	ol – Up to 2004	4 Model Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
ISC	P0506	Idle speed lower than	Idle speed versus target	100 RPM too low	Engine Coolant Temperature	80 to 110 °C	2.8s	2 Drive
		expected			Atmospheric pressure	< 75.5 kPa		Cycles
	P0507	Idle speed higher than	Idle speed versus target	200 RPM too high		> 13.76s	2.8s	2 Drive
		expected			Transmission oil temperature	-8 to 125 °C		Cycles
					Intake Air Temperature			
					ISC	-8 to 110 °C		
					Stable condition	Active > 4.86s		
					Vehicle speed	See below		
						<= 0.6 mph		
					P0336, P0603, P1245, P1246, P1	· ·	•	
					P0106-P0108, P0125, P0111-P01			
					P0460, P1224, P1229, P0121, P1			
					P1699, P0122, P0123, P0222, P0	)223, P0616, P0617	', P0702, P065	51,
					P0606, P0741, P0750,			
					P0753, P0755, P0758, P0760, P0	)763, P0765, P0768	s, P0770, P077	73,
					P0740, P0743, P0787, P0788, P0	, ,	,	,
					P0735, P0729, P0780, P0781, P0	)782, P0783, P0784	, P0829, P179	98,
					P1799, P1797, P0666, P0641, P1	1605, P0815, P0815	5, P1774, P070	06,
					P0709, P0610, P1783, P1572			

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		le	dle Speed Control -	From 2004 N	lodel Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
ISC	P0506	Idle speed lower than expected	Idle speed versus target	200 RPM too low	Engine Coolant Temperature	80 to 110 °C	15s	2 Drive
					Atmospheric pressure	>= 74.8 kPa	3s (XK8)	Cycles
	P0507	Idle speed higher than expected	Idle speed versus target	200 RPM too	After start	>= 14s	15s	2 Drive
				high	Transmission oil temperature		3s (XK8)	Cycles
					Intake Air Temperature	-8 to 110 °C		
					ISC	>= 4.9s Active		
					Stable condition	See below		
					Vehicle speed	<= 0.6 mph		
			Disable:		1155, C1165, C1175, P0106, I			
					)118, P0121, P0122, P0123, P			
					0605, P0606, P0610, P0641, P			
					)711, P0715, P0720, P0725, P			
				P0734, P0735, P0	)740, P0741, P0743, P0750, P	20753, P0755, P075	8, P0760, P07	763,
				P0765, P0768, P0	)770, P0773, P0780, P0781, P	20782, P0783, P078	4, P0787, P07	788,
				P0815, P0829, P1	I224, P1229, P1241, P1242, P	P1516, P1572, P160	3, P1605, P16	609,
				P1611, P1631, P1	1633, P1637, P1642, P1643, F	1699, P1719, P177	4, P1783, P17	796,
				P1797, P1798, P1	1799			
			Disable additions (X-Type	P0069, P0562, P0	0563, P0851, P1251, P2118, F	2119, P2135, P222	8, P2229.	
			2005 model year):					

Stable condition: The idle speed system is deemed unstable for a period of 1 second, following a change in state of any of the following parameters:

- Park/neutral switch
- Heated screen
- A/C clutch
- Cooling fan fast mode
- Cooling fan slow mode
- Headlamp
- Main beam
- Side lamp
- Footbrake

# **6.27.1 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.28 Starter Relay

During normal starting, the ECM should pull the low side of the starter motor relay coil to ground. If this voltage is high when starting is being requested, a fault is logged.

# **6.28.1 Monitoring Structure**

	Starter Relay										
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL			
High input		3.	Starter relay is off but starter relay request is on		Ignition Starter relay Starter relay request Time since initialization Battery voltage Disable:	On Off On >0.064s (2008MY) >6.48 (2008MY) P1245, P1246, P16		2 Drive Cycles			

# **6.28.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 6.29 Air Conditioning Clutch Relay

This monitor checks to confirm that the A/C control relay is responding to a request from the ECM to switch it on or off. When the entry conditions have been met the ECM compares the state of the A/C compressor clutch relay to the commanded state. If they do not agree then a timer is started. If at the end of the period the commanded and actual relay states do not agree then the DTC is flagged.

# **6.29.1 Monitoring Structure**

	Air Conditioning Control Relay											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
Low input		Rationality, relay versus drive circuit	Relay on but ECM is requesting relay off		Disable:	P1609	1.3s	2 Drive Cycles				
High input	P0647		Relay off but ECM is requesting relay on		Disable:		1.3s	2 Drive Cycles				

# **6.29.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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#### 6.30 Park/Neutral Switch

During the engine crank operation if the park/neutral input is low, with the CAN signal from the transmission indicating park/neutral is selected; the low fault timer is enabled. When the low fault timer reaches the calibrated time, the low fault flag is set. If the park/neutral input is high, and the vehicle is detected as moving with an appropriate engine load, then the high fault timer will be enabled. When the high fault timer reaches the calibrated time, the high fault flag is set.

# **6.30.1 Monitoring Structure**

			Park/N	leutral Switcl	n			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Park/neutral	P1516	Malfunction during driving		Park/neutral	Vehicle speed	>= 9 <= 160 mph	5s	2 Drive
switch high	P0851 (2005		during driving		Engine speed	1500 to 4000 RPM		Cycles
Input	model year X-				Engine Coolant Temperature	>= -30 °C		
Park/neutral	Type)				Transmission type	Automatic		
switch low					Engine load	> 0.4 g/revolutions		
Input (2004								
model year)				Disable:	C4407 C4445 C4455 C44	 	  400   D0400   I	00446
				Disable.	C1137, C1145, C1155, C116 P0117, P0118, P0125, P012			
					P0606, P0610, P0616, P061			
					P0705, P0706, P0709, P071			
					P0730, P0731, P0732, P073			
					P0750, P0753, P0755, P075			
					P0773, P0780, P0781, P078			
					P0829, P1104, P1245, P124			
					P1642, P1643, P1719, P17	74, P1783, P1796, P1	797, P1798, F	21799
Park/neutral	P1517	Malfunction during	Park/neutral during	Park/neutral	Gear selected	0 or 2	0.256s	2 Drive
switch low input		starting	starting		Actual gear	0		Cycles
(2001 to 2003								
model year)				D: 11	Doors Books Books Books	 	. Dolloo Doll	
					P0335, P0336, P0118, P0117, I			
					P0101, P0104, P1643, P1637, I	20603, P1609, P0128	s, P0616, P06	17,
					P1799, P1224,			
					P1229			

# **6.30.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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#### 6.31 Accelerator Pedal Position Sensor Monitor

During ignition on conditions, the voltages from the two-track APP sensor are monitored. If the input voltage stays above a calibration value for more than a calibratable period, the high input failure judgment is made. If the input voltage stays below a calibration value for more than a calibratable period, the low input failure judgment is made. If the angle obtained from sensor 1 differs from the angle obtained from sensor 2 by more than a calibratable amount for more than a calibration period a range/performance failure judgment is made.

# **6.31.1 Monitoring Structure**

	Accelerator Pedal Position Sensor											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
APP circuit 1 low	P1122	Out of range check	Output voltage	< 0.35 volts		Ignition on	01s	2 Drive				
input								Cycles				
APP circuit 1 high	P1123	Out of range check	Output voltage	> 4.9 volts		Ignition on	0.1s	2 Drive				
input								Cycles				
APP circuit 2 low	P1215	Out of range check	Output voltage	< 0.10 volts		Ignition on	0.1s	2 Drive				
input								Cycles				
APP circuit 2 high	P1216	Out of range check	Output voltage	> 4.55 volts		Ignition on	0.1s	2 Drive				
input								Cycles				
( )	P1344	Rationality of 1 to 2	Signal 1 versus 2	See table DDS1		Ignition on	0.1s	2 Drive				
range/performance					Battery voltage	9 to 18 volts		Cycles				
					Disable:	P1241, P1242						

	Accelerator Pedal Position Sensor - X-Type 2005 Model Year											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
APP circuit 1 low	P0227	Out of range check	Output voltage	< 0.35 volts		Ignition on	01s	2 Drive				
input								Cycles				
APP circuit 1 high	P0228	Out of range check	Output voltage	> 4.9 volts		Ignition on	0.1s	2 Drive				
input								Cycles				
APP circuit 2 low	P2122	Out of range check	Output voltage	< 0.10 volts		Ignition on	0.1s	2 Drive				
input								Cycles				
APP circuit 2 high	P2123	Out of range check	Output voltage	> 4.55 volts		Ignition on	0.1s	2 Drive				
input				> 4.9V (2008MY)				Cycles				
( )	P0226	Rationality of 1 to 2	Signal 1 versus 2	See table DDS1		Ignition on	0.1s	2 Drive				
range/performance					Battery voltage	9 to 18 volts		Cycles				
					Disable:	P1241, P1242						

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DDS1									
Pedal angle (degrees)	0	1	3	71	74	80			
Value (degrees)	12.8	13.6	13.7	13.9	11.6	11.6			

**6.31.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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#### 6.32 Throttle Control

## 6.32.1 Sensor Power Supply Monitor

#### High/Low Input Failure

These are continuous monitors. The voltage from the supply is compared to a failure threshold defined in the software. If the voltage is below the low threshold, then a timer starts to increment. Once this timer exceeds another threshold, then a failure flag is set and a DTC is stored. If the voltage exceeds the high threshold defined in the software, then a timer starts to increment. Once this timer exceeds a threshold, then a failure flag is set and a DTC is stored.

#### Malfunction

The outputs from two Throttle Position sensors and one pedal demand sensor are checked. If they <u>ALL</u> fall below a threshold value then a counter is incremented, otherwise the counter is reset to zero. If the counter reaches a calibrated value, a failure judgment is made.

# 6.32.2 Analogue Ground Monitor

The output voltages from the following sensors are checked:

- Throttle Position sensor 1
- Throttle Position sensor 2
- APP sensor 2
- FTP sensor (on USA market cars)
- Intake Air Temperature sensor
- Engine Coolant Temperature sensor
- Intake Air Temperature sensor after charge air cooler (on supercharged cars)
- Fuel rail pressure sensor
- Intake manifold pressure sensor
- Oil temperature sensor

If they <u>all</u> fall below a threshold value then a counter is incremented, otherwise the counter is reset to zero. If the counter reaches a calibrated value a failure judgment is made.

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#### 6.32.3 Throttle Actuator Control Monitor

#### Throttle Actuator Control OBDII Position Error

During ignition on conditions the calculated target throttle voltage is compared to the actual Throttle Position sensor voltage. If the voltage of the target and actual throttle signal differ by more than a calibratable amount for more than a calibratable period a failure judgment is made.

#### Throttle Actuator Control OBDII Circuit Malfunction

During ignition on conditions, the throttle motor current signal is monitored by hardware. If an over current condition is detected for more than a calibratable period, a failure judgment is made. During ignition on conditions, the throttle motor current is monitored by software. If the throttle motor current is more than a calibratable period a failure judgment is made. During ignition on conditions, the PWM throttle motor duty is monitored. If 100% duty cycle is detected for more than a calibratable period a failure judgment is made.

# 6.32.4 Throttle Motor Relay Monitor

#### DC Motor Relay Off Failure

During ignition on the relay driver signal is compared with the relay output signal. If the ECM is commanding the relay on and detecting the relay as off for more than a calibratable period, a failure judgment is made.

#### DC Motor Relay On Failure

During ignition on the relay driver signal is compared with the relay output signal. If the ECM is commanding the relay off and detecting the relay as on for more than a calibratable period, a failure judgment is made.

# **6.32.5 Throttle Motor Relay Driver Monitor**

## DC Motor Relay Driver Off Failure

During ignition on the relay driver target flag is compared with the relay driver signal. If the ECM is commanding the relay on and detecting the relay driver as off for more than a calibration period, a failure judgment is made.

## DC Motor Relay Driver On Failure

After ignition off, the ECM sets the relay driver off. This is compared with the relay driver monitor. If the ECM is commanding the relay off and detecting the relay driver as on for more than a calibration period, a failure judgment is made.

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# 6.32.6 Throttle Return Spring Monitor

After ignition off, the throttle blade is moved by the throttle motor to a calibrated position. The motor is then turned off. The monitor checks that the throttle blade is moved by the return spring. If movement of less than a calibrated amount is detected, a failure judgment is made.

# **6.32.7 Throttle Limp Home Spring Monitor**

After ignition off, the throttle blade is moved by the throttle motor to a calibrated position. The motor is then turned off. The monitor checks that the throttle blade is moved by the limp-home spring. If movement of less than a calibrated amount is detected, a failure judgment is made.

## **6.32.8 Throttle Watchdog Monitor**

After ignition off, the watchdog pulse is stopped in order to check whether the throttle motor relay driver will be disabled. If the throttle motor relay driver command is detected on for more than a calibratable period, a failure judgment is made.

# **6.32.9 Monitoring Structure**

	Throttle Control – Up to 2004 Model Year											
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL				
System	Codes	Description	Criteria	value	Parameter	Conditions	Required					
Throttle control	P1224	Rationality sensor out	Sensor out v target	> 1.001 volts		Ignition on	See table THC1	2 Drive				
position error	P2119 (2005	versus target	difference	>= 1v (2004	Battery voltage	9 to 18 volts		Cycles				
	model year X-			model year)								
	Type)	0.5		00			0.5	o D :				
	P1229	.,	Number of times over	30	D = # = =   # = = -	Ignition on		2 Drive				
circuit malfunction	P2118 (2005 model year X-	current by hardware	current		Battery voltage	9 to 18 volts		Cycles				
manunction	Type)											
		2) Detection of over	Current	8.3A			15s					
		current by software		>= 8A (2004								
				model year)								
		3) Duty 100% failure	100% duty cycle	100%		Ignition on	See table THC2	2 Drive				
					Battery voltage	9 to 18 volts		Cycles				

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			Throttle Control – U	p to 2004 Mc	odel Year			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Throttle control sensor power supply malfunction	P1240	TP, FTP, MAP sensor, Fuel rail pressure sensor voltage	Sensor output voltages: Pedal position TP 1 TP 2 FTP	< 0.35 volts < 0.35 volts < 0.35 volts < 0.2 volts		Ignition on	3s	2 Drive Cycles
			MAP sensor Fuel rail pressure A/C pressure	< 0.3 volts < 0.4 volts < 0.3 volts				
Throttle control low input	P1241	Out of range check	Output voltage	<= 3.0 volts		Ignition on	3s	2 Drive Cycles
Throttle control high input	P1242	Out of range check	Output voltage	>= 4.5 volts		Ignition on	3s	2 Drive Cycles
Throttle control analogue ground malfunction	P1243		TP 1 TP 2 FTP IAT ECT Fuel rail pressure MAP Charge air cooler (S/C only)	>= 4.9 volts >= 4.9 volts		Ignition on	1s	2 Drive Cycles
Throttle return spring failure		Monitoring of throttle blade angle when throttle motor turned off at fully open throttle	Throttle blade movement	< -0.6 degrees  Disable:	Disable: Ignition Idle condition Throttle limp home Valve sensor offset adaptions Valve sensor normal judgment DC throttle motor Throttle over current Throttle DC motor relay P1609, P1224, P1229, P0	Idling Not in limp home Complete Complete No failure No over current No failure	0.760s	2 Drive Cycles
				Disable:	P1609, P1224, P1229, P0- P1631, P1611, P1633,P06	122, P0123, P0222,		P1251,

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		Thrott	tle Control – Up to 2	004 Model Y	ear - Continued			
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
Throttle control DC motor relay off fail  Throttle control DC motor relay		Rationality, commanded versus actual	Commanded versus actual	Different	Battery voltage Disable:	Ignition on  9 to 18 volts P0603	0.352s 0.4s (V6 2004 model year) 0.5s (V8 2004 model year) 0.496s 0.5s (2004 model	2 Drive Cycles 2 Drive
on fail						. 0000	year)	Cycles
Throttle control DC motor relay driver off failure		Rationality, commanded versus actual	Commanded versus actual	Different		Ignition on	0.352s 0.4s (V6 2004 model year) 0.5s (V8 2004 model year)	2 Drive Cycles
Throttle control DC motor relay driver on failure	P1657				Battery voltage Disable:	9 to 18 volts P0603	0.496s 0.5s (2004 model year)	2 Drive Cycles
Throttle limp home spring failure		Monitoring of throttle blade angle when throttle motor turned off at fully closed throttle	Throttle blade movement	< +0.6 degrees  Disable:	Ignition Idle condition Throttle DC motor relay Throttle limp home Throttle motor over current Valve sensor offset adaptions Valve sensor normal judgment P1224, P1229, P0122, P0	current Complete Complete	0.640s	2 Drive Cycles
				Disable.	P1611, P1633, P0607, P2	118, P2119, P2	135	
Throttle watchdog circuit failure			Watchdog pulse train not present when throttle relay on	> 1 cycle	Throttle DC motor driver Disable:	Ignition on No failure P1609, P1657	0.304s	2 Drive Cycles

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	Throttle Control – From 2004 Model Year									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required			
Throttle control	P1240	Out of range check	Pedal position 2	< 0.35 volts		Ignition on	3s	2 Drive		
sensor power			TP 1	< 0.35 volts				Cycles		
supply			TP 2	< 0.35 volts						
malfunction										

	Throttle Control – 2005 Model Year X-Type										
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL			
System	Codes	Description	Criteria	value	Parameter	Conditions	Required				
Throttle control	P0561	Out of range check	Pedal position 2	< 0.35 volts		Ignition on	3s	2 Drive			
sensor power			TP 1	< 0.35 volts				Cycles			
supply			TP 2	< 0.35 volts							
malfunction											
Throttle control	P0562	Out of range check	Output voltage	<= 3.0 volts		Ignition on	3s	2 Drive			
low input								Cycles			
Throttle control	P0563	Out of range check	Output voltage	>= 4.5 volts		Ignition on	3s	2 Drive			
high input								Cycles			
Throttle	P2107	Rationality of throttle watchdog	Watchdog pulse train not	> 1 cycle		Ignition on	0.304s	2 Drive			
watchdog circuit		pulse train	present when throttle relay		Throttle DC motor driver	No failure		Cycles			
failure			is on		Battery voltage	9V to 18V					
					Disable:	P1609, P1657					

THC1								
Battery voltage (v)	6.48	8.98	9.06	12.03				
Voltage deviation for failure judgment (seconds)	0.992	0.992	0.192	0.192				

	THC2		
Battery voltage (v)	6.48	8.98	9.06
Time for failure judgment (seconds)	10.000	10.000	0.352 (1.248 (V8))

**6.32.10 Drive Cycle Information** The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.33 Intake Manifold Tuning Valve System

When the entry conditions have been met, the control module checks the commanded versus actual position of the Intake Manifold Tuning (IMT) valves. If they are not matched, a timer is started. If at the end of the set time the commanded and actual positions of the IMT valves do not match then the relevant DTC is flagged and the IMT valve affected is disabled.

# **6.33.1 Monitoring Structure**

	Intake Manifold Tuning Valve (V6 Only)									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required			
IMT valve 1	P1549	Hardware check	Commanded versus actual	Different	Duty cycle	10 to 90%	10s	2 Drive		
low/high input					Battery voltage	>10 volts		Cycles		
	P1532				Disable:	P1609				
low/high input										

# **6.33.2 Drive Cycle Information**

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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#### 6.34 Generator Monitor

# 6.34.1 Generator Charge Line Monitor (V6 Only)

The generator used with the V6 engine can operate in two output modes. The high charge mode provides an output of 15.3 volts, whilst the low charge mode provides an output of 13.6 volts. This monitor checks the output of the generator to confirm it matches the mode selected. When the entry conditions have been met the rationality of the actual charge mode is compared to the commanded mode, if they do not match then a timer is started. If at the end of the timed period the commanded and actual modes still do not match the relevant DTC is flagged.

## 6.34.2 Generator Field Line Failure (V6 Only)

Once the entry conditions have been met, the ECM checks the duty cycle of the generator field line against pre-defined thresholds. If the duty cycle is outside the threshold limits for more than a defined period then the field line failure DTC is logged.

#### 6.34.3 Charging System/Generator Load Failure

On V6 engines, this monitor checks the charge line for irrational behavior, these being charge line off when engine running and charge line on when the engine is not running. If either of the above conditions exist for more than a predefined time then the DTC is set and the charge warning lamp is illuminated.

The V8 engine uses an alternative strategy due to differences in the generator used. This generator provides a variable voltage output dependent on the temperature of the generator itself. Once the entry conditions have been satisfied, the average charge voltage over a predefined time is checked. If this falls below a defined threshold value then the DTC is logged and the charge warning lamp is illuminated.

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# **6.34.4 Monitoring Structure**

			Generate	or Monitor				
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
Charge line low	P1146	Rationality of charge mode	Requested high mode	Regulator in low	Battery voltage	> 10 volts	1.3s	2 Drive
input		versus requested mode	against actual mode	mode				Cycles
Charge line	P1244	Rationality of charge mode	Requested low mode	Regulator in high	Battery voltage	> 10 volts	1.3s	2 Drive
high input		versus requested mode	against actual mode	mode				Cycles
Field line failure	P1629	Generator output duty cycle	Driver duty outside valid	< 5% or > 45%	Battery voltage	> 10 volts	0.320s	2 Drive
		rationality	duty range		Engine RPM	< 200 RPM		Cycles
					Ignition switch	On		
0 0		Charge line status rationality	Charge monitor line off		Ignition switch	On	5s	2 Drive
, ,	(V6)		when engine running		Battery voltage	> 10 volts		Cycles
or load failure					After start time	> 1.28s		
			Charge monitor line on		Ignition switch	On	0.320s	2 Drive
			when engine not running		Battery voltage	> 10 volts		Cycles
				0.7	Engine speed	< 200 RPM		o <b>n</b> :
		Regulator control rationality	Voltage difference between	< 0.7 volts	Engine RPM	> 1000 while	> 20s	2 Drive
			high and low charge modes		Charge mode	Low for 10s and		Cycles
	D4000			40.0	E : DDM	High for 10s	4.5	o <b>o</b> :
		Continuous voltage rationality	, , ,	< 13.9 volts	Engine RPM	> 650	15s	2 Drive
	(v8)		below limit		Charge mode	Low	 	Cycles
					Disable:	P0335, P0336, P16	509, P1146, P12	<u>4</u> 44,
						P1629, P1632		

**6.34.5 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.35 Engine Control Module

The engine management system is centered on an ECM. The ECM receives input signals from engine sensors to evaluate engine-operating conditions. In addition, the ECM communicates with other powertrain systems and vehicle systems. The ECM then processes the sensor information and the information received from other systems using programmed software strategies and issues control output signals to the engine and emission control functional systems.

At it's very basic level of control the ECM:

- Takes engine speed and load input signals.
- Applies correction factor inputs and emissions control feedback signals.
- Processes the signals to access pre-programmed software strategies.
- Outputs control signals to the various engine and emission components.
- During this process, the ECM employs diagnostic tests to monitor and report engine management system faults. Faults are stored in ECM memory as codes. Technician access to the DTCs and data is gained through a diagnostic data link.

# 6.35.1 ECM Control Relay Monitor

After the vehicle ignition has been turned off, the ECM can maintain its own power source by holding on the ECM relay. The ECM turns itself off by releasing this relay. If it has done this but is still operating then there is a fault with the ECM control relay circuit and this is logged.

#### **6.35.2 Main Processor Monitor**

At processor initialization, this monitor checks whether the Read Only Memory (ROM) checksum for the sub processor monitor is OK. If the checksums do not agree, a failure judgment is made. The same check is performed for the Random Access Memory (RAM) area for the sub processor monitor. If the checksums do not agree, a failure judgment is made. During ignition on, the main processor mirror checks certain sequence, RAM and ROM calculations with the sub processor. If the mirror checks do not agree, a failure judgment is made.

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#### 6.35.3 Sub Processor Monitor

This monitor duplicates various sections of the throttle control functions performed by the sub processor in the main processor and continuously compares the results during ignition on. In case of the sub processor value differing from the main processor value by more than a calibratable amount, a failure judgment is made.

The following functions are checked:

- Throttle target calculation.
- Throttle offset voltage differential failure.
- Throttle target voltage differential failure.
- Throttle valve angle input.
- Pedal angle input.
- Digital servo control.
- Total sub processor calculation.
- Speed control mode cancel.
- Sub processor self-check.

# 6.35.4 Battery Back Up Monitor

The ECM supply input status is checked after the system initialization with ignition applied. If the supply input is low, the status flag is set. When the ignition is cycled the fault timer is incremented until the timer reaches the calibrated time, thus the fault flag is set.

## 6.35.5 Processor Communications Monitor

At regular intervals, the validity of all RAM data is checked. Any corruption of RAM data will result in a monitoring failure judgment being made. If all RAM data is verified then a monitoring normal judgment is made.

## 6.35.6 Engine Control Module Keep Alive Memory Monitor

Every data value stored in the Electrically Erasable Programmable Read Only Memory (EEPROM) is duplicated in a 'mirror' EEPROM location. If all the data values and their mirrors match, a normal judgment is made. If any of the EEPROM data values differ from the value stored in their mirror location then a failure judgment is made and P0603 is logged.

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# **6.35.7 Monitoring Structure**

			Engine Co	ntrol Module				
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL
	P0560	No permanent power to ECM		Not set	Processor communications  Battery Voltage Disable:	Main and sub processor communications. Correct 9 to 18V P1642, P1609	10s	2 Drive Cycles
Keep alive memory error ECM control relay		Mirror check Relay operating when not requested	Mirror check ECM relay energized	Not correct	Ignition on Disable: Ignition switch Disable:	P1642, P1609 P1642, P1609 Accessory on, ignition off P1609	1.024s 7.2s	1 Drive Cycle 1 Drive Cycle
ECM processor communications error	P1609	Internal communications check	Keyword	Not correct	Ignition on	000	5s	2 Drive Cycles
Sub processor failure	P1611 P0607 (2005 model year X-Type)	Throttle target calculation failure	Sub processor throttle target calculation versus Main processor		Speed control DC motor relay Processor to processor communications.	Not active On No failure	0.128s	2 Drive Cycles
	, , , ,	Throttle offset voltage differential failure		> 5 volts >=0.40 volts (2004 model year)	DC motor relay Processor to processor communications.	On No failure	0.128s	2 Drive Cycles
		Throttle target differential failure	Differential of target voltage too large	> 5 volts	Traction, acceleration and power limitation DC motor relay Processor to processor communications.	Not active On No failure	0.128s	2 Drive Cycles
		Throttle valve angle input failure	processor	> 4.58 degrees n/c > 5.48 degrees (2004 model year) > 10.66 degrees (2005 model year X-Type)	DC motor relay Processor to processor	On No failure	0.128s	2 Drive Cycles

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			Engine Co	ntrol Module				
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
		Pedal angle input failure	Sub processor pedal angle	> 8.02 degrees n/c	DC motor relay	On	0.128s	2 Drive
			calculation versus main		Processor to processor	No failure		Cycles
			processor	(2004 model year)	communications			
		Digital servo control failure	Throttle sensor 1 output	> see table SUB1	DC motor relay	On	0.128s	2 Drive
			voltage versus final target		Processor to processor	No failure		Cycles
			voltage		communications			
		Total sub processor	Throttle valve angle versus	1.07 degrees	DC motor relay	On	0.128s	2 Drive
		calculation failure	pedal angle					Cycles
		Speed control mode cancel	Speed control active with	0.496s	DC motor relay	On	0.5s	2 Drive
		failure	P/N switch set or brake		Processor to processor	No failure		Cycles
			switch set or park-brake on		communications			
			or vehicle speed < 16.1mph					
	P1633	RAM/ROM checks	Failure detected in RAM		Battery voltage	9 to 18V	0.08s	2 Drive
processor failure			check or ROM check or					Cycles
			sequence check or mirror					
E014 116	54050	A 1151	data check	0.400		0.01/ 4.51/		
•	P1656	Amplifier output voltage	Output voltage versus 4 X		Amplifier input voltage	>= 0.3 V <=1.15 V	0.496s	2 Drive
failure for valve		rationality	input voltage	difference				Cycles
sensor					Disable:	P1241, P1242		

SUB1 (for P1611 or P0607)								
Final target voltage (volts)	2	3	4	5				
Deviation voltage (Volts)	1.0	2.0	3.0	4.0				

**6.35.8 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 6.36 Communications Network Monitors

If the ECM does not receive any messages from the required module for a set time, then a fault is flagged.

# **6.36.1 Monitoring Structure**

			Communication	ns Network M	onitors			
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Codes	Description	Criteria	value	Parameter	Conditions	Required	
CAN link	P1637	No CAN signal from ABS	ABS CAN identifier not	No ID	Crank request flag	Not set	2.5s	2 Drive
ECM/Anti-lock Braking System (ABS)		module	received		Battery Voltage  Disable:	>=10V Ignition on P1642. P1609	1.5s (2004 model year)	Cycles
CAN link ECM/	D1620	No CAN signal from IPK	IPK CAN identifier not	No ID	Crank request flag	Not set	2.5s	1 Drive
IPK	F 1030	INO CAIN SIGNAL HOLLI IFK	received	NO ID	Battery Voltage	>=10V Ignition on	1.5s (2004 model year)	Cycle
					Disable:	P1642, P1609	, , ,	
CAN link failure	P1642	CAN circuit failure	All modes missing	No IDs	Crank request flag CAN bus off line flag	Not set Set	2.5s 1.5s (2004	2 Drive Cycles
					Communications failure	Set	model year)	1 Drive
					flag	Set		Cycle
					TCM mode missing flag	Auto		(2004
					Transmission	Set		model
					ABS mode missing flag	Set		year)
					Climate control mode			
					missing flag	Set		
					IPK mode missing flag			
					Gearshift selector module	Set		
					mode missing flag			
					Adaptive speed control	Set		
					mode missing flag			
					Disable:	P1609		
CAN link	P1643	No CAN signals from TCM	TCM CAN identifier not	No ID	Transmission	Automatic	2.5s	2 Drive
ECM/Transmiss		module	received		Crank request flag	Not set	1.5s (2004	Cycles
ion Control					Battery Voltage	>=10V	model year)	
Module (TCM)					Disable:	Ignition On P1642, P1609		
CAN link	P1699	No CAN signals from BCC	Climate control CAN	No ID	Crank request flag	,	2.50	2 Drive
ECM/Rear	F 1099	No CAN signals from RCC module	identifier not received	טו טאן		Not set >=10V	2.5s 1.5s (2004	
Climate Control		module	identifier not received		Battery Voltage		,	Cycles
					Diaghlar	Ignition On	model year)	
(RCC)					Disable:	P1642, P1609		

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**6.36.2 Drive Cycle Information**The generic drive cycle (see 2.1 *Generic OBD-II Drive Cycle*) applies.

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# 7 Anti-lock Braking System

This section includes the ABS codes that are reported as part of the vehicle emissions certification.

## 7.1 Wheel Speed Sensors

The ABS modulates brake pressure on each wheel independently to maintain vehicle stability during braking.

The ABS continually monitors the rotational velocity of each wheel anytime the ignition switch is in the on position and determines if a tire is skidding when the brakes are applied. Only then does the ABS intervene to modulate the brake pressure to the skidding wheel. The modulation continues until the wheel rotates freely. The brake pressure is then restored and the modulate/restore cycle is repeated whenever skidding is detected. This cycle occurs at a rate of several times per second.

The ABS module is capable of detecting the following system conditions:

- Hydraulic valve failure.
- Wheel speed sensor failure.
- ABS power relay short circuit.
- Interconnect failures to the ABS sensors, power and ground to the ABS module.
- Over/under voltage conditions.

The ABS provides failure messages, via the ABS indicator, in the ipk. Failure of the ABS module, for whatever reason, will not compromise the normal operation of the brake system.

# 7.1.1 Wheel Speed Sensor Monitoring (XJ Range, XK Range and S-Type)

The ABS system monitors all four wheel speed censors continuously. A number of checks are performed, the failure of any one will cause the ABS system to be disabled and the ABS warning lamp together with the MIL to be illuminated. The monitors are performed differently on the X-Type and, therefore, the description for this system is dealt with separately.

## Sensor Signal Current Out of Range

The current from each sensor is continually monitored against an upper and lower threshold. If the current is outside the threshold limits a counter is incremented and the check re-run. When the counter reaches its predefined limit the DTC for the appropriate wheel speed sensor is logged.

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#### Missing Wheel Speed Sensor Input

If any of the wheel speed signals is lost (assuming normal signals from the other three wheels) for more than 0.007 seconds, the DTC for the appropriate wheel speed sensor is logged.

### Wheel Speed Sensor Signal Continuously too Low

If the signal current from any wheel speed sensor is identified as being too low for more than a defined period then the DTC for the appropriate wheel speed sensor is logged.

#### Comparison of Maximum Wheel Speed Versus Minimum Wheel Speed

This monitor compares the difference in wheel speed of the sensors over a long period (180 seconds). If the difference between the maximum and minimum wheel speeds continuously exceeds the defined threshold the DTC for the appropriate wheel speed sensor is logged.

#### Wheel Speed Signal Changes Erratically

Erratic wheel speed signals are monitored by checking the variation in successive samples. If the difference in signal from each successive sample is greater than 15.5 mph or the signal interrupt is detected (no sample) then a software counter is incremented. If the counter reaches its defined limit the DTC for the appropriate wheel speed sensor is logged.

#### Periodic Drops of Wheel Speed Signal

At wheel speeds above 12.4 mph, each sensor is monitored for loss of wheel speed signal. If the signal is lost for more than 15 revolutions then the DTC is logged.

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# 7.1.2 Monitoring Structure

	Wheel Speed Sensors (XJ, XK8 and S-Type)									
Component/ System	Fault Codes	Monitoring Strategy Description	Malfunction Criteria	Threshold value	Secondary Parameter	Enable Conditions	Time Required	MIL		
Right rear wheel speed plausibility	C1165	Sensor signal current out of range or	Sensor signal current	>= 4.5 mA <= 20mA	Supply voltage	7.5 to 8.5 volts	19 software loops	2 Drive Cycles		
	C1175	Missing wheel speed sensor input or			Supply voltage	7.5 to 8.5 volts	1 software loop (approximately 0.007s)			
	C1145	Wheel speed sensor signal continuously too low or			Supply voltage	7.5 to 8.5 volts	1 software loop			
Left front wheel speed plausibility	C1155		Vehicle speed or	> 6.2 mph	Vmax. Vmin1 Vmin2 Vmin3	< 6.2 mph < 1.2 mph < 1.2 mph < 1.2 mph	180s			
			Vehicle speed or	> 9.3 mph	Vmax. Vref.	< 4.3 mph < 3.7 mph	180s			
			Wheel speed or	<= 0.4 Vmax.	Vmax.	> 9.3 mph				
			Wheel speed	<= 0.6 Vmax.	Vmax.	24.8 mph	180s			
		Wheel speed signal changes erratically	Erratic step of wheel speed or	Vx(n) – Vx(n-1) > 15.5 mph			22 software loops			
		or .	Number of interrupts per loop	> 40			22 software loops			
		Periodic drops of wheel speed					15 wheel revolutions.			
		Long time monitoring of the ABS	Pressure reduction too long following pressure hold phase		Wheel speed Supply voltage	> 12.4 mph 7.5 to 8.5 volts	28s			

7.1.3 Drive Cycle Information
The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 7.1.4 Wheel Speed Sensor Monitoring (X-Type)

#### **Dynamic Monitoring**

The monitor runs when the vehicle speed reaches 24.8 mph. If any of the wheel speed signals is lost (assuming normal signals for the other 3 wheels) for more than 20 ms the DTC for the appropriate wheel speed sensor is logged.

#### Static Start-up Monitoring

This monitor checks for the loss of the wheel speed signal at ignition on. If any wheel speed signal is not present for more than 20 seconds then the appropriate DTC is logged.

#### **Drive-off High Speed**

This monitor checks for loss of a wheel speed sensor signal during rapid acceleration from being stationary. The monitor looks for one wheel speed signal being stuck at 0 mph when the other three are greater than 11 mph. If this situation occurs, a timer is started. If after 0.020 seconds the situation still exists then the DTC for the appropriate wheel speed sensor is logged.

#### **Drive-off Low Speed**

This monitor checks for the loss of a wheel speed sensor signal during slow acceleration from being stationary and during continued low speed driving. If the difference between the maximum and minimum wheel speed continuously exceeds any of the defined thresholds for more than 20 seconds the DTC for the appropriate wheel speed sensor is logged.

#### Static Wheel Slip

This monitor compares the difference in the wheel speed of the sensors over a longer period of time (5 seconds) during normal driving. If the vehicle speed is below 62 mph, then the wheel speed sensors are checked for either the deviation of the two wheel speeds at either side of the vehicle being greater than 3.7 mph, or the deviation of the wheel speed at the front axle being greater than 6.2 mph. If at least one wheel is at 3 mph or lower, a wheel speed deviation of adjoining wheel of 7.4 mph is permitted. If the detected deviation exists for more than 5 seconds then the appropriate DTC is logged. If the vehicle speed is greater than 62 mph then the wheel speed sensors are checked for either the deviation of two wheels speeds at either side of the vehicle being greater than 6% or the deviation of wheel speeds at the front axle being greater then 2.5 mph +6%. If the detected deviation exists for more than 5 seconds then the appropriate DTC is logged.

## **Ohmic Monitoring**

This monitor performs a static impedance check on each wheel speed sensor when the ignition is switched on. If the impedance of any sensor is outside of its defined limits, then the appropriate DTC is logged.

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# 7.1.5 Monitoring Structure

	Wheel Speed Sensors (X-Type)									
Component/ System Right rear wheel speed plausibility	Fault Codes C1165	Monitoring Strategy Description  Dynamic monitoring or Static start-up monitoring	Malfunction Criteria No wheel speed signal for: Wheel speed not present	Threshold value 0.010 to 0.020s	Secondary Parameter Vehicle speed	Enable Conditions 24.8 mph	Time Required 0.020s 20s	MIL 2 Drive Cycles 2 Drive		
speed plausibility	C1175 C1145 C1155	or Sensor supply, signal quality or Drive—off high speed or Drive-off low speed or	1 wheel at 0 mph with 3 wheels at > 11 mph (V1 = fastest wheel)  V4 = slowest wheel)  V2>= 7.4 mph and  V3> 3 mph and  V4< 3 mph  or  V2>= 14.9 mph and  V3<= 3 mph  or  V3> 55.8 mph and  V4= Vmin  or  V1,V2,V3= 7.4 mph and  V4= Vmin				0.240s 0.020s 20s	Cycles 2 Drive Cycles 2 Drive Cycles 2 Drive Cycles		

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Wheel Speed Sensors (X-Type) continued										
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required			
		Static wheel slip or	*Deviation of the two wheel side of the vehicle > 3.7 mp axle > 6.2 mph * If at least one wheel is at wheel speed deviation of ac 7.4 mph is permitted Deviation of two wheels speed of vehicle > 6% or at the from	oh or at the front  3 mph or lower, a djoining wheels of eeds at either side	•	< 62 mph	5s	2 Drive Cycles		
		Ohmic monitoring	Broken Shorted to ground Short to supply voltage Short between sensor lines				0.280s	2 Drive Cycles		

	Wheel Speed Sensors (X-Type – 2008MY)									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required			
Invalid signals Front Left	C0031	CAN signal 'error marker' received from ABS	ABS Unable to Transmit  Valid Data		Ignition Switch Battery Voltage	On for at least 2.0 s	5.0 s	2 Drive Cycles		
Front Right					Engine Start	Not in progress				
Rear Left										
Rear Right	C003A									

# 7.1.6 Drive Cycle Information

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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# 7.2 Control Module Failure

The ABS control module runs a number of internal power on initialization self-tests when the ignition is switched on. If any of the self-tests fail then DTC C1137 is logged and the ABS is disabled.

# 7.2.1 Monitoring Structure

	Control Module									
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Codes	Description	Criteria	value	Parameter	Conditions	Required			
ABS control	C1137	Defective control module	Major ABS control module			Power applied	0.7s	2 Drive		
module failure			internal fault					Cycles		

	Control Module – X-Type								
Component/	Fault	Monitoring Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL	
System	Codes	Description	Criteria	value	Parameter	Conditions	Required		
ABS control	C1137	Long term interference	Interference on one or more					2 Drive	
module failure			wheels					Cycles	
noise detection									

# 7.2.2 Drive Cycle Information

The generic drive cycle (see 2.1 Generic OBD-II Drive Cycle) applies.

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